



SpaceSUITE

Real-Time Central Processing Facility for High Accuracy Navigation (IONO4HAS)

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A tutorial elaborated in the framework of the SpaceSUITE
ERASMUS+ Blueprint Project, Funded by the European Union.

EUREF Symposium 2024, Barcelona, Spain.



Outline

1. Introduction
2. IONO4HAS ionospheric correction tool
3. Assessment of the IONO4HAS ionospheric corrections
4. Results from the user perspective
5. gAGE RT-products portal

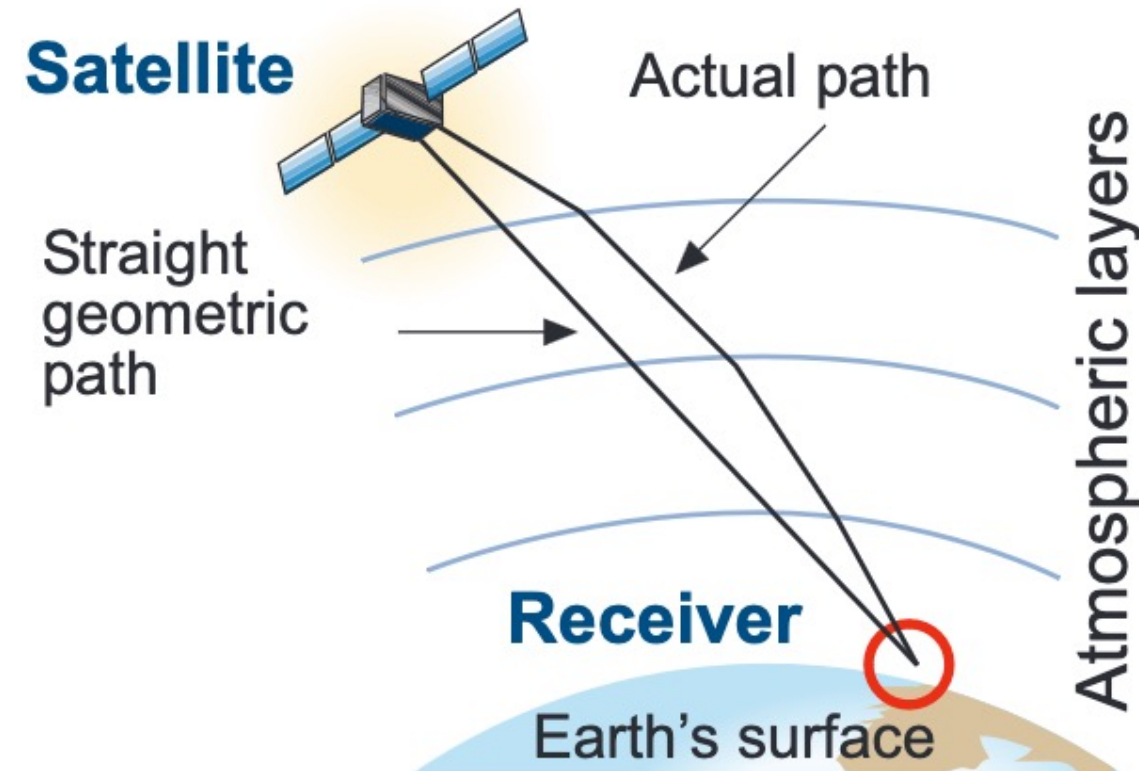
1

Introduction

1. Introduction

Ionospheric delay on GNSS

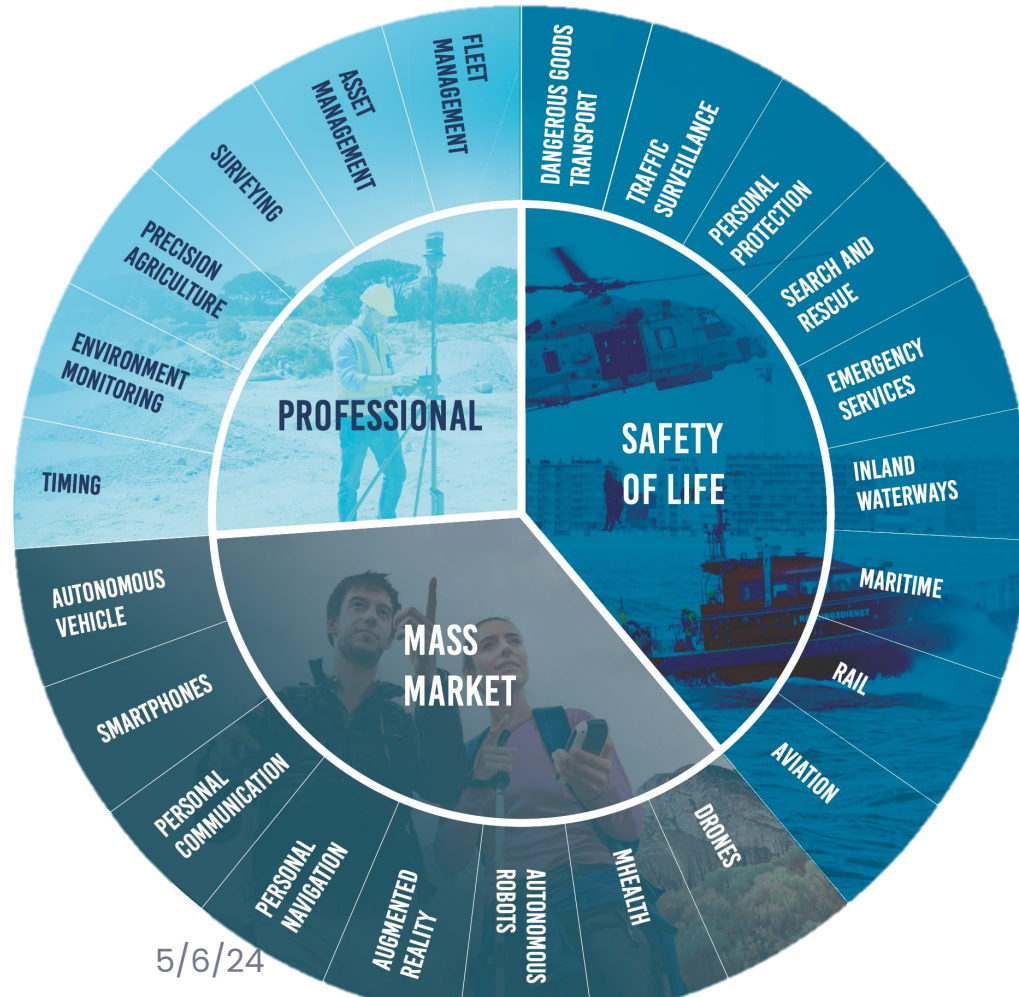
- The total electron content (TEC) in the atmosphere affects the GNSS signals:
 - **Double-frequency** receivers can apply a linear combination of measurements at different frequencies to reduce the ionospheric error up to 99.9%
 - **Single-frequency** receivers require external information to mitigate the ionospheric effects.
 - ✓ Klobuchar (GPS)
 - ✓ NeQuick-G (Galileo)



Source: "GNSS data processing, Vol. I: fundamentals and algorithms" (2013)

1. Introduction

Galileo HAS

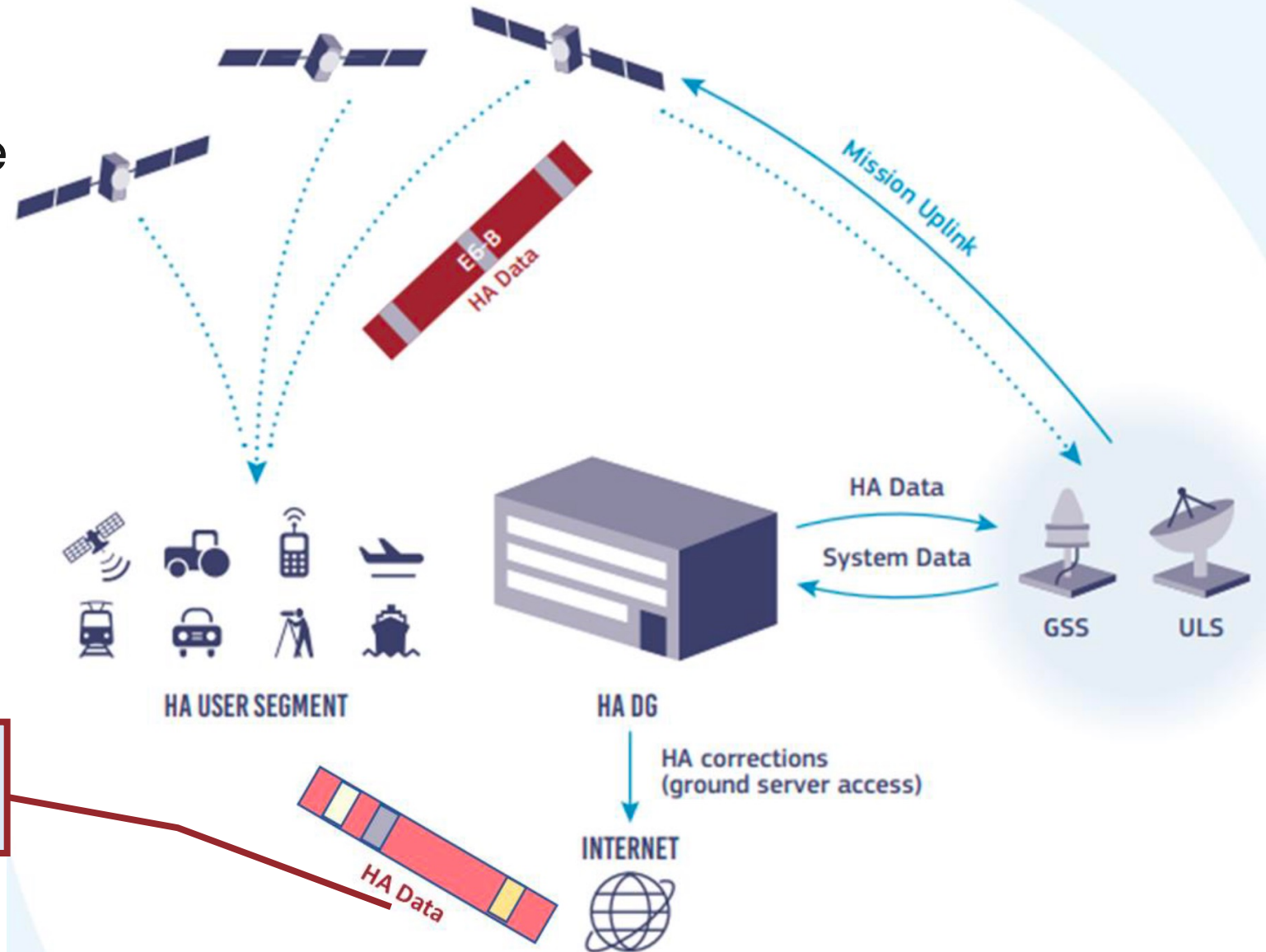


GALILEO High Accuracy Service (HAS)

Enabling Precise Point Positioning (PPP) on a global scale

	Service Level 1	Service Level 2
Coverage	Global	European Coverage Area
Corrections	Orbit, clock, biases (code and phase)	Orbit, clock, biases (code and phase), <u>ionospheric corrections</u>
Constellations	GPS, GALILEO	GPS, GALILEO
Hor. Accuracy (95%)	< 20 cm	< 20 cm
Ver. Accuracy (95%)	< 40 cm	< 40 cm
Convergence Time	< 300 s	< 100 s

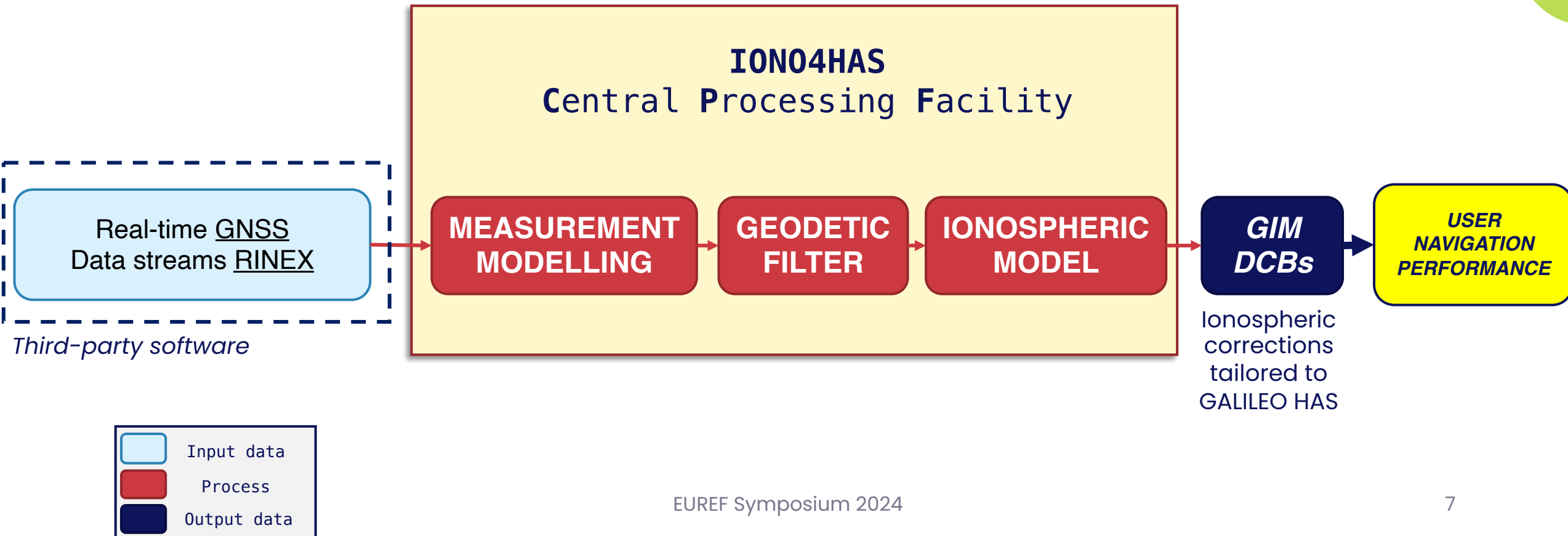
Galileo HAS architecture



RTCM format NTRIP protocol

1. Introduction

IONO4HAS: a real-time implementation of the ionospheric correction model for Galileo HAS SL2

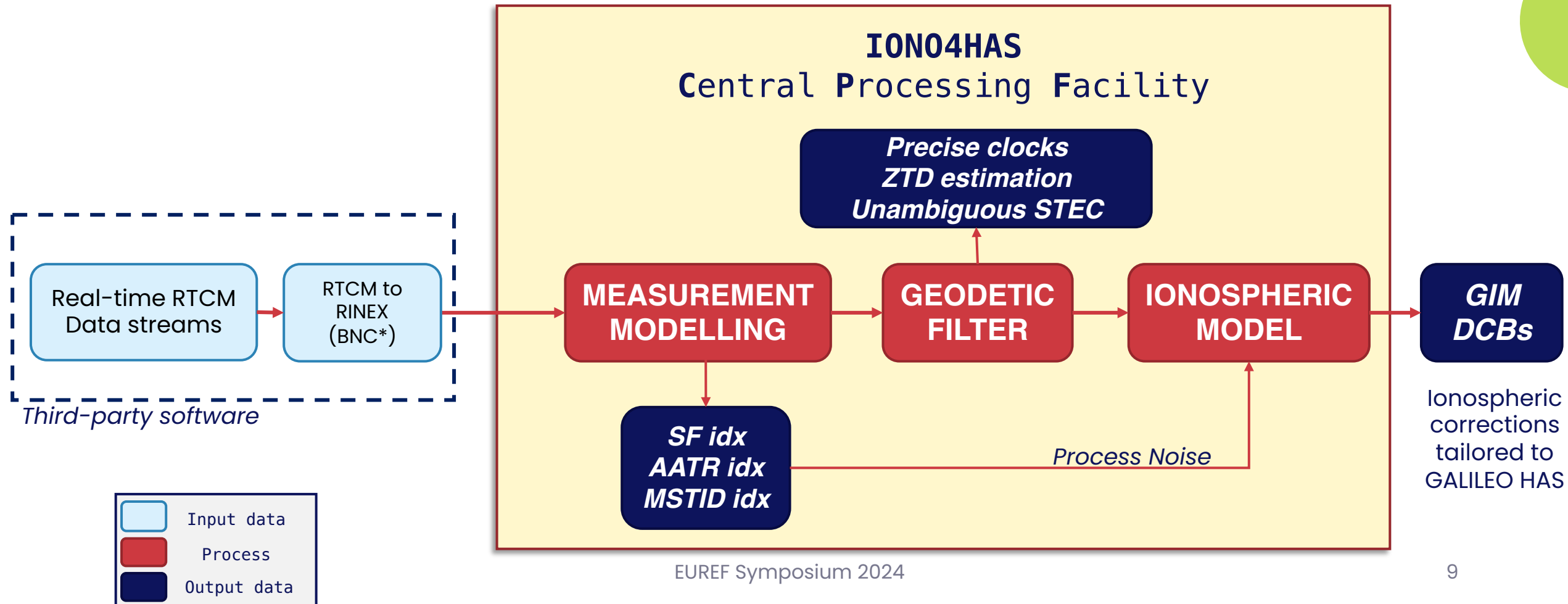


2

IONO4HAS ionospheric correction tool

IONO4HAS ionospheric correction tool

General overview



2.1

Measurement Modelling Module

IONO4HAS ionospheric correction tool

2. IONO4HAS tool

Measurements Modelling

- ✓ Outliers removal
- ✓ Cycle slip detection
- ✓ Modelling (cm level)

Geodetic Filter

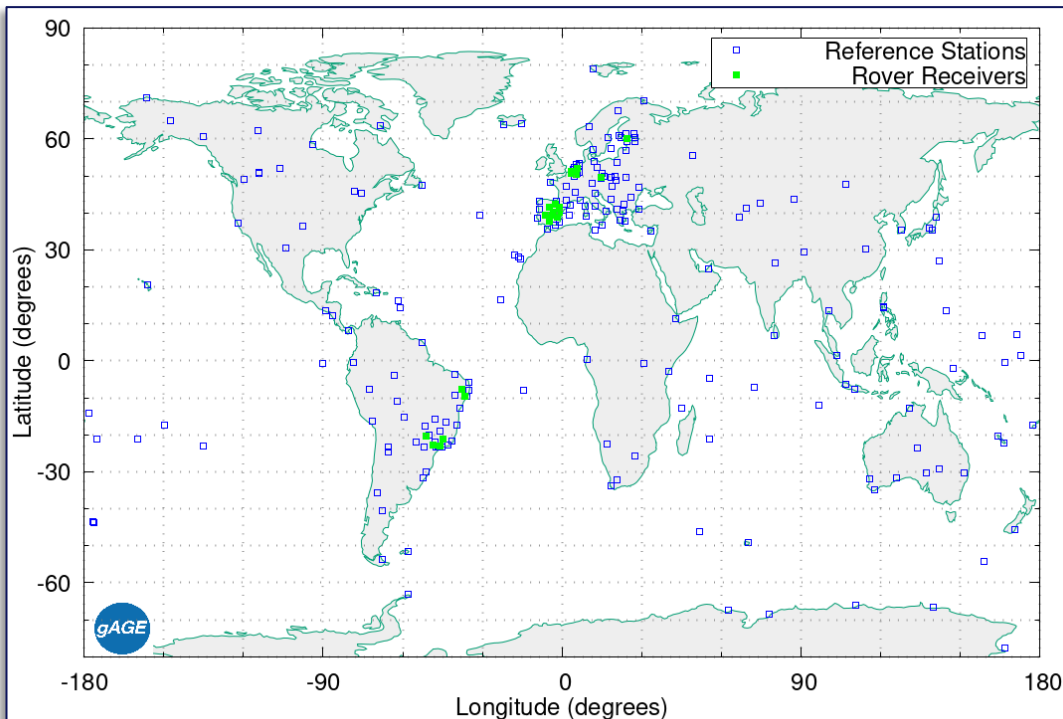
Ionospheric Filter

GNSS data streams providers

IGS
EUREF
AUSCORS



IBGE
RAMSAC
IGM
UNAVCO



IONO4HAS NETWORK FEATURES

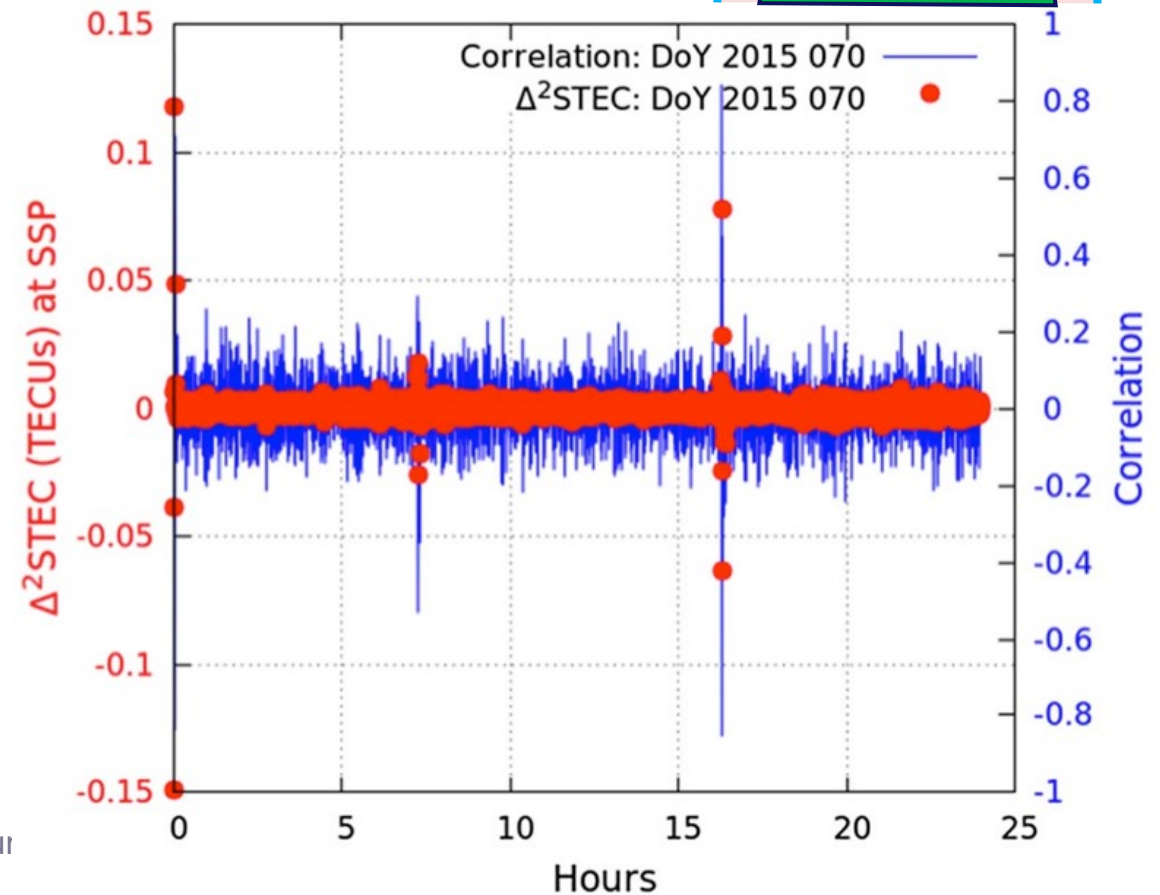
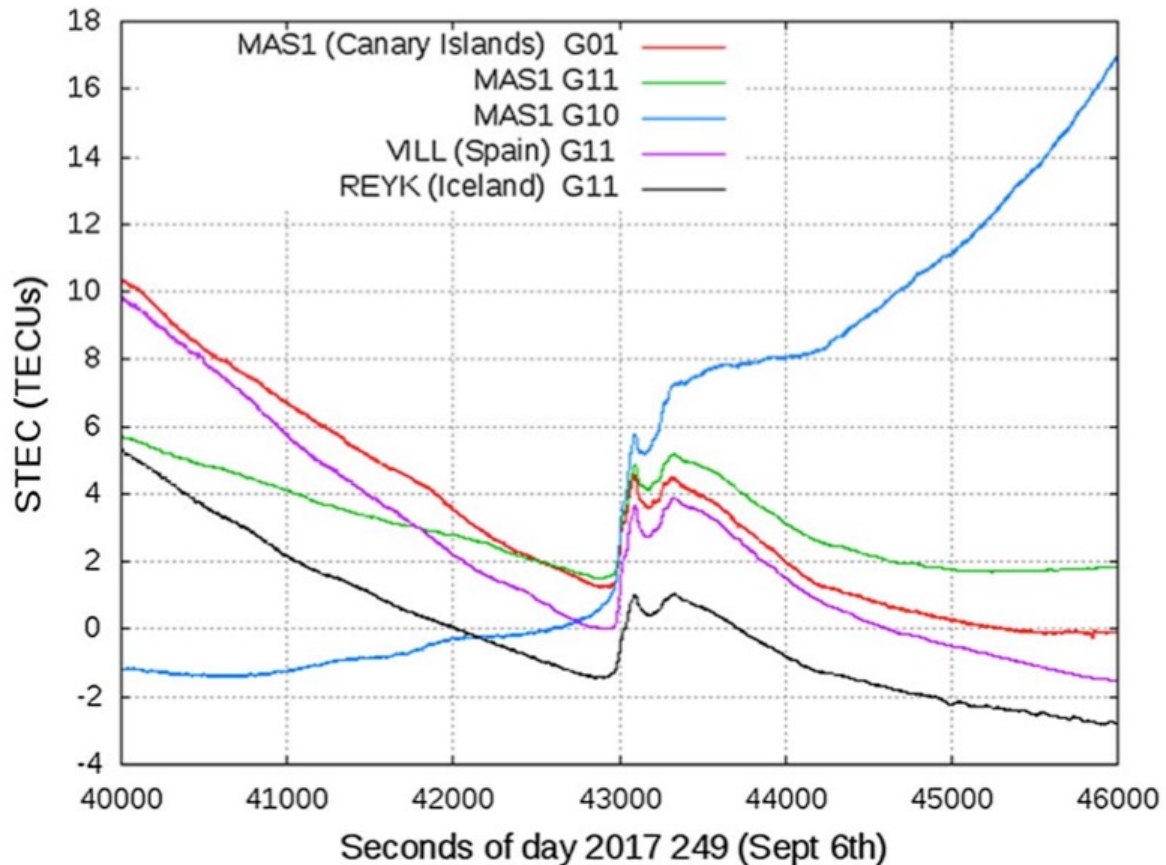
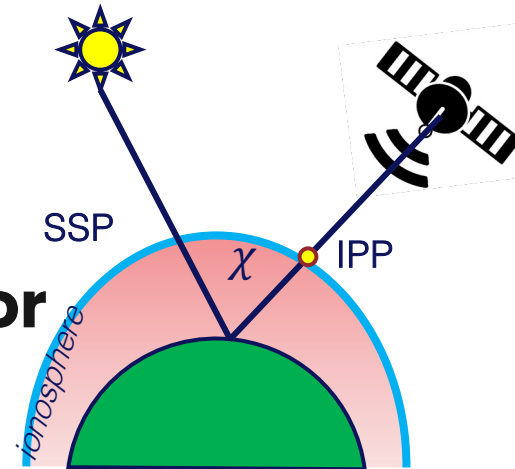
- ✓ up to 200 GNSS streams on a daily basis
- ✓ 5 seconds rate
- ✓ Multiconstellation: **GPS, GAL, GLO, BDS**
- ✓ 21 permanent stations profiled as **rover receivers** (users):
 - European sub-networks latitudes:
 - Mid (35° and 45°)
 - Mid-high (45° and 55°)
 - High (59° and 62°)

2. IONO4HAS tool

Ionospheric monitoring indexes: **GNSS solar flares detector**

$$L_{GF} = L1 - L2$$

Geometry-free: only frequency-dependent effects



Recent Solar activity

Forbes

FORBES > INNOVATION > SCIENCE

Watch Issued: Solar Storm May Overload Electric Grid, Put On Aurora Show

Los Angeles Times

SCIENCE & MEDICINE

Solar storm heading to Earth could disrupt communications and bring northern lights to California

THE Sun

UK Edition

Search

Sign in

News

Sport

Fabulous

TV

Showbiz

Money

Travel

Health

Tech

Motors

More

News

Phones & Gadgets

Gaming

Science

X drkstrong



Tech

SPACE 'ATTACK' Biggest solar storm in 19 years could cripple internet, phones & power grids TODAY as rare 'severe' flare warning issued

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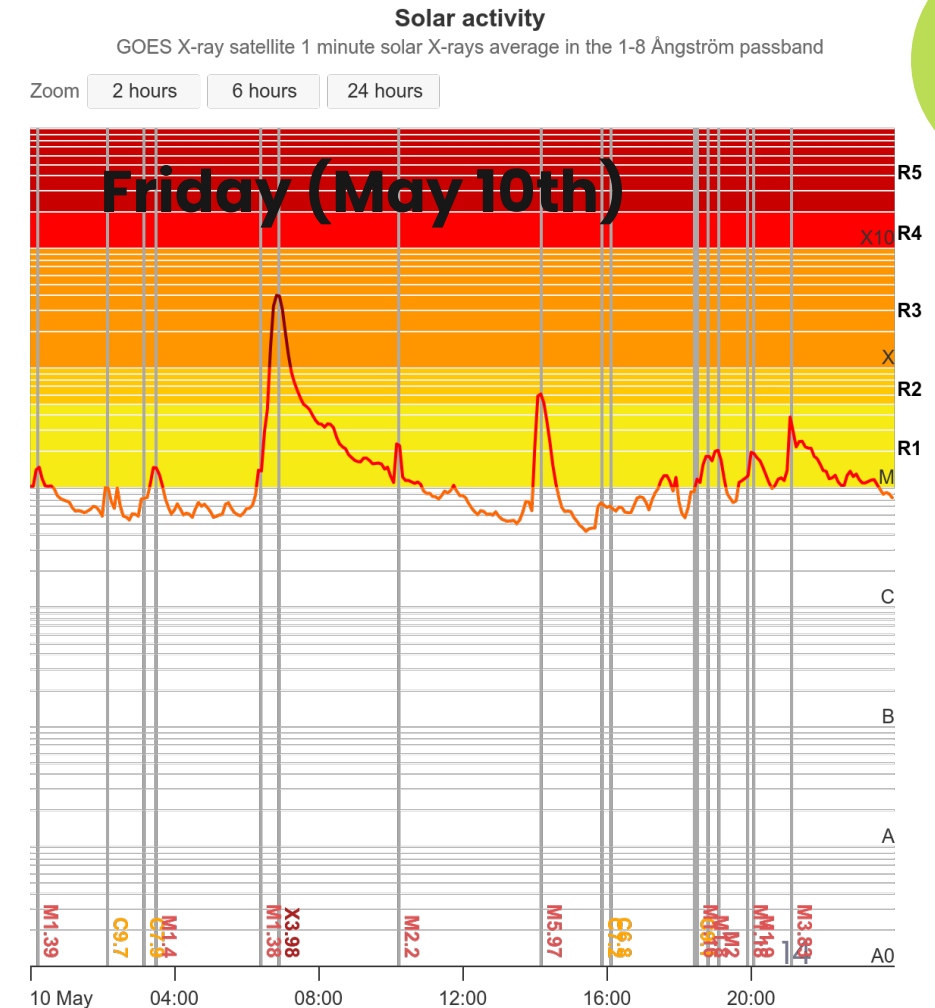
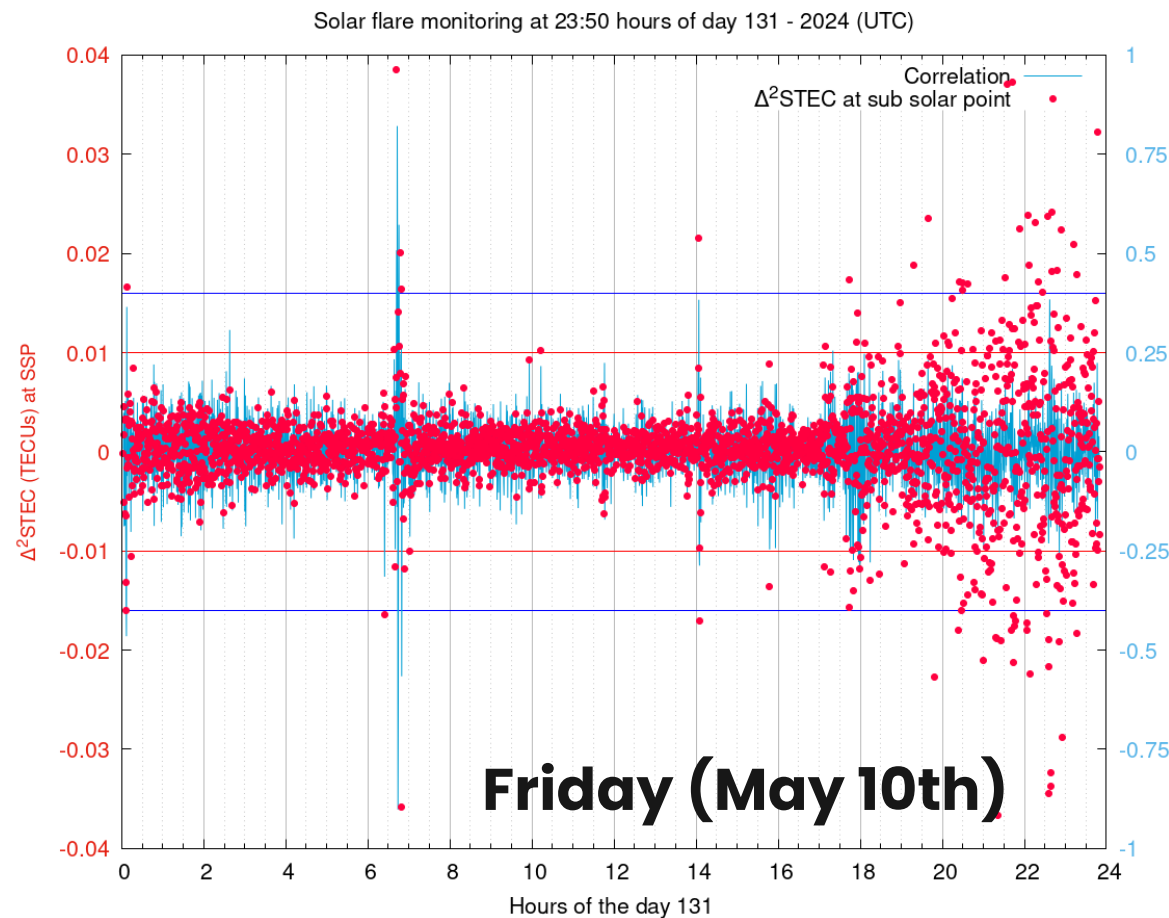


Co-funded by
the European Union

Curto JJ, Juan JM, Timote CC (2019) "[Confirming geomagnetic Sfs by means of a solar flare detector based on GNSS](#)" Journal of Space Weather and Space Climate 9:A42:1-15. [DOI 10.1051/swsc/2019040](#)

2. IONO4HAS tool

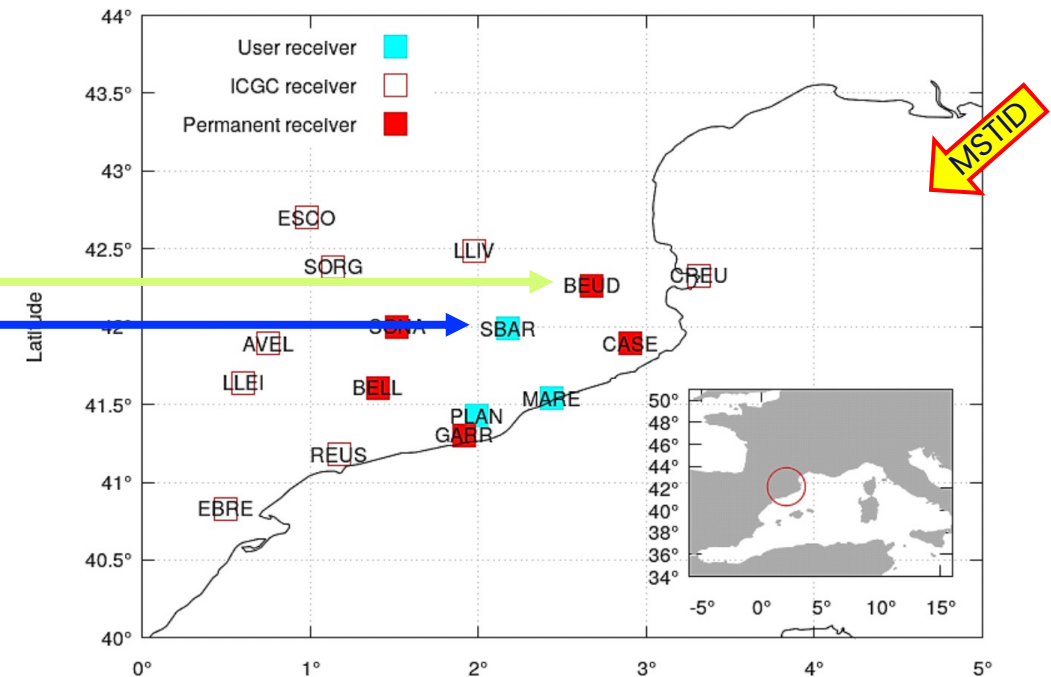
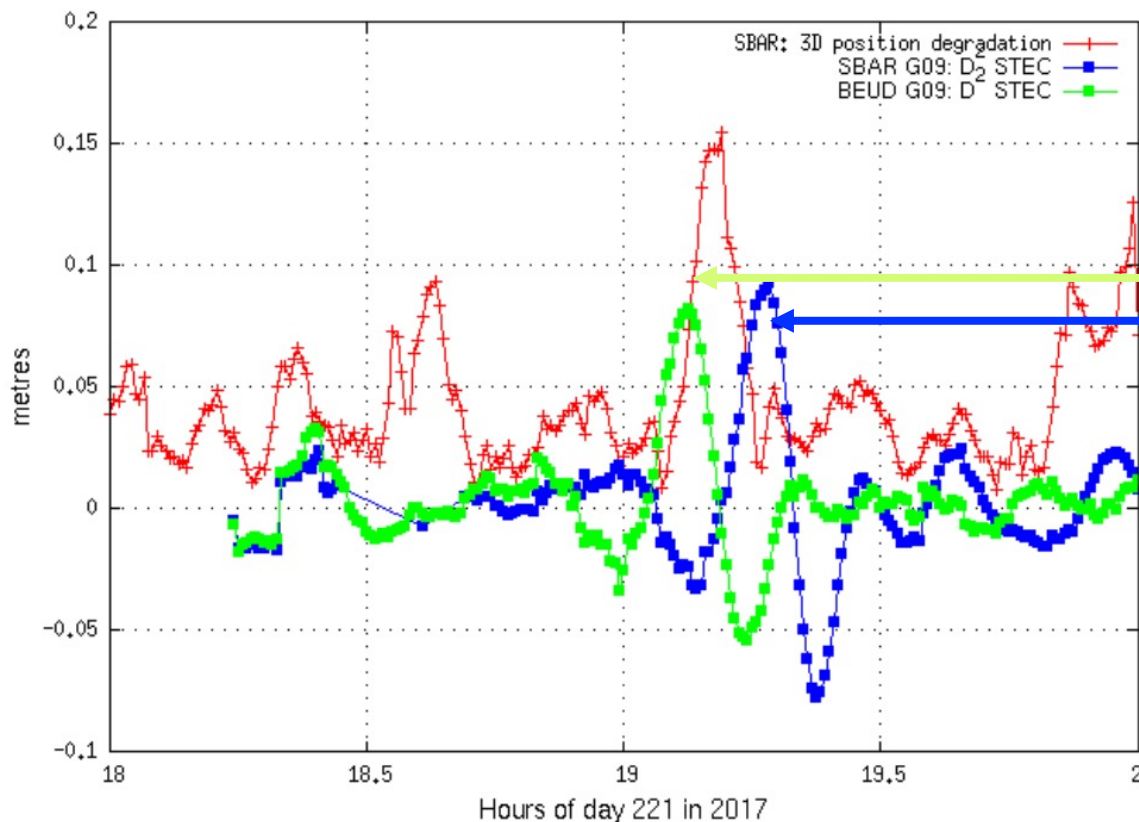
Ionospheric monitoring indexes: **GNSS solar flares detector**



2. IONO4HAS tool

Ionospheric monitoring indexes: **MSTID** index

Medium Scale Traveling Ionospheric Disturbances (**MSTID**) **potentially degrade** ionospheric mitigation of single-frequency users of **RTK** and **NRTK** services



Timoté, C. C., Juan, J. M., Sanz, J., González-Casado, G., Rovira-García, A., & Escudero, M. (2020). Impact of medium-scale traveling ionospheric disturbances on network real-time kinematic services: CATNET study case. *Journal of Space Weather and Space Climate*, 10, 29.

2. IONO4HAS tool

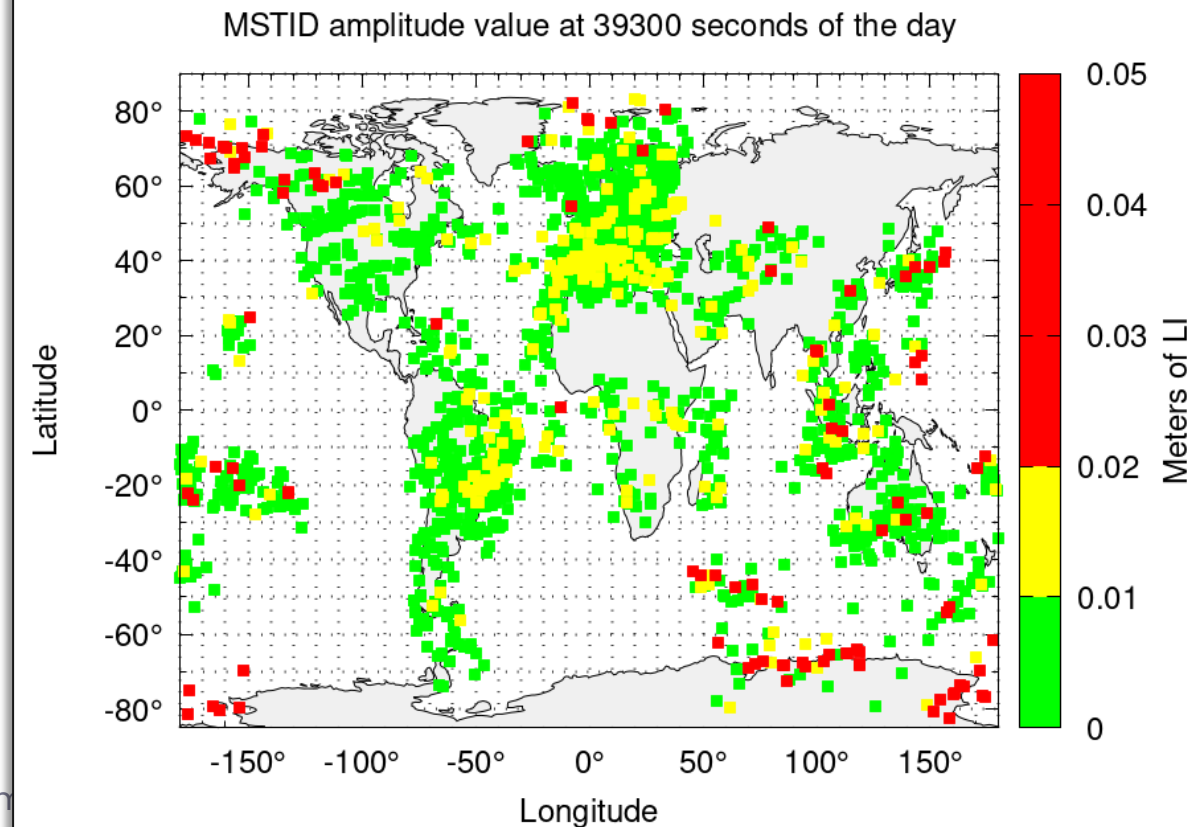
Ionospheric monitoring indexes: **MSTID index**

$$L_{GF} = L1 - L2$$

Geometry-free: only frequency-dependent effects

$$MSTID_{IDX}^2(t) = \frac{1}{20} \sum_{i=t-2\tau}^n (\Delta^2 STEC(i) / M(\epsilon))^2$$

$\Delta^2 STEC(t)$: $0.5 \cdot (STEC(t + \tau) + STEC(t - \tau) - 2 \cdot STEC(t))$
 τ : tuning parameter (MSTID periods of 10 min)
 $M(\epsilon)$ is an obliquity factor for mitigating larger values of $\Delta^2 STEC$



Recent Solar activity

The New York Times

Solar Storm Intensifies, Filling Skies With Northern Lights

Officials warned of potential blackouts or interference with navigation and communication systems this weekend, as well as auroras as far south as Southern California or Texas.

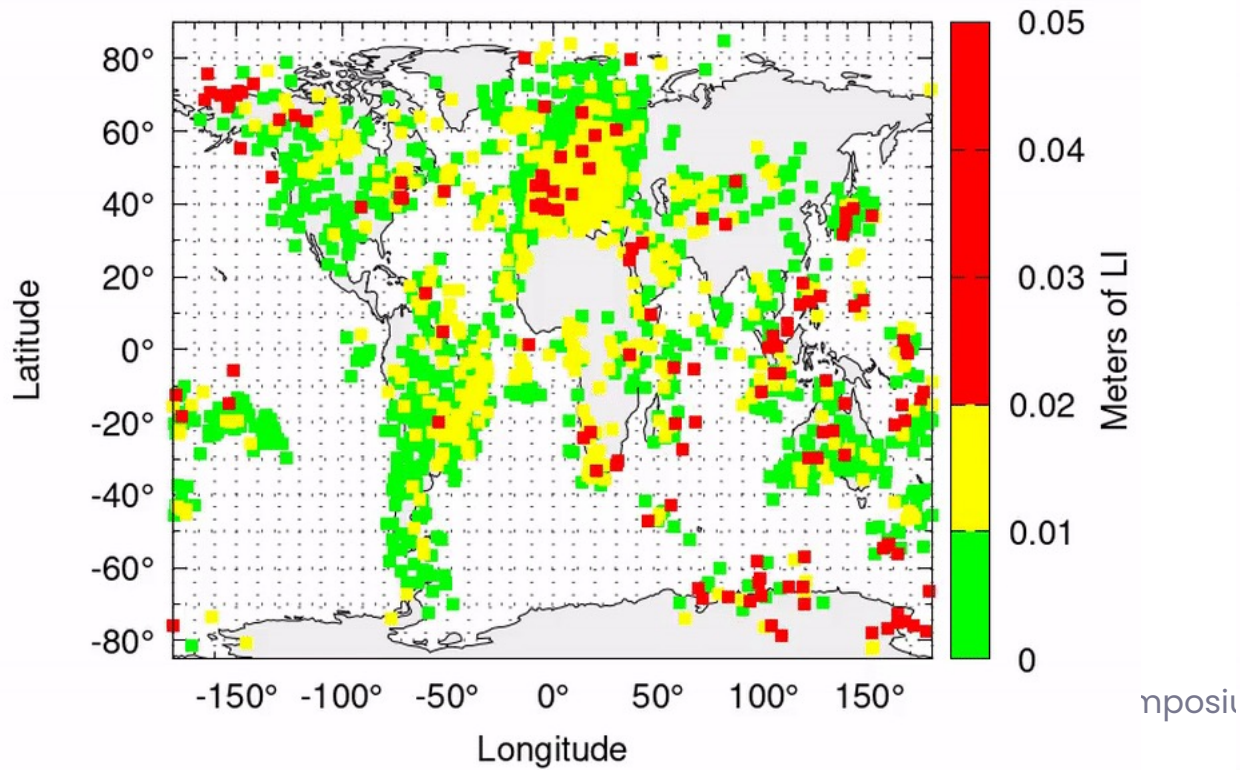
2. IONO4HAS tool

Ionospheric monitoring indexes: **MSTID index**

Thursday (May 9th)

From 12:00 to 23:59 (UTC)

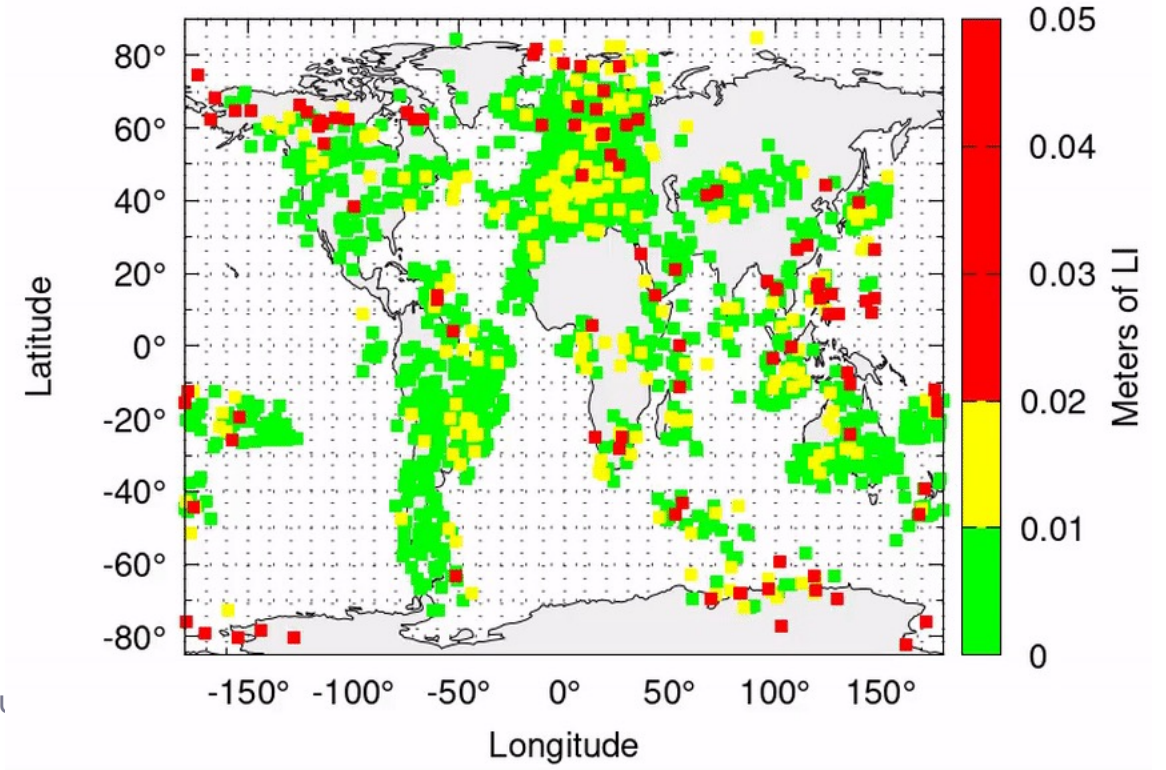
MSTID amplitude value at 43200 seconds of the day 9 - 05 - 2024



Friday (May 10th)

From 12:00 to 23:59 (UTC)

MSTID amplitude value at 43200 seconds of the day 10 - 05 - 2024



2. IONO4HAS tool

Ionospheric monitoring indexes: **AATR computation**

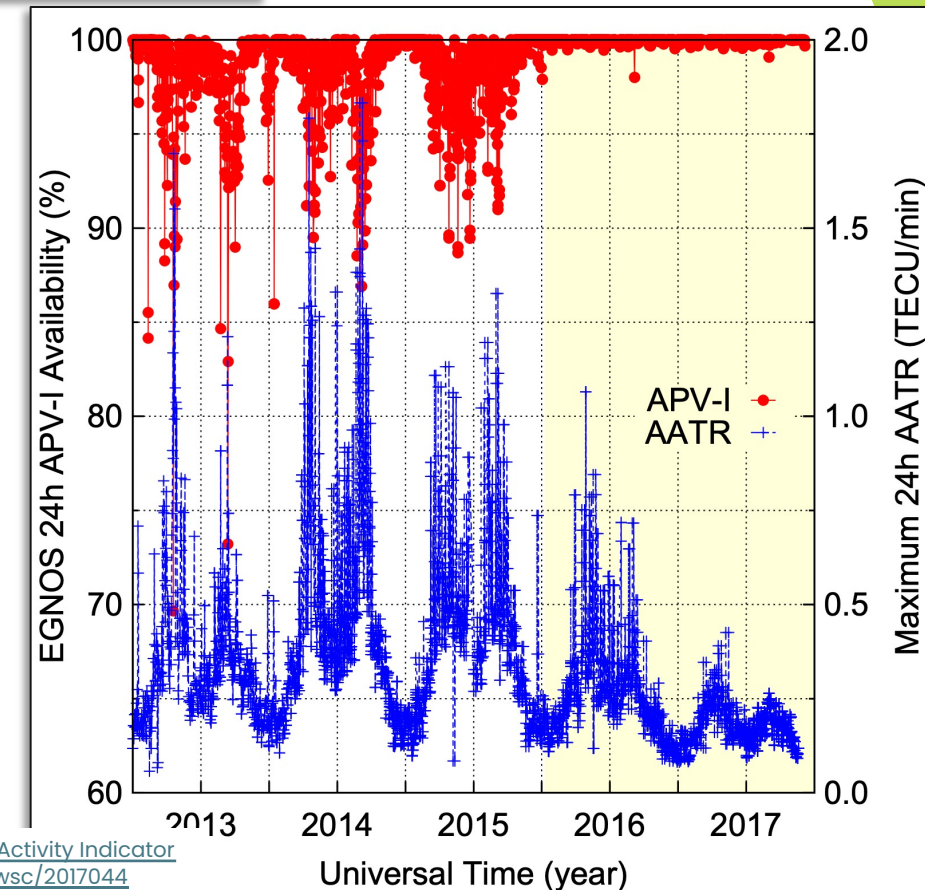
$$L_{GF} = L1 - L2$$

Geometry-free: only frequency-dependent effects

Along-Arc TEC Ratio is defined as:

$$AATR_i^j(t) = \frac{1}{(M(\epsilon))^2} \frac{\Delta STEC_i^j(t)}{\Delta t}$$

$$\Delta STEC_i^j(t) = (LI_i^j(t) - LI_i^j(t - \Delta t))$$



2. IONO4HAS tool

Ionospheric monitoring indexes: **AATR computation**

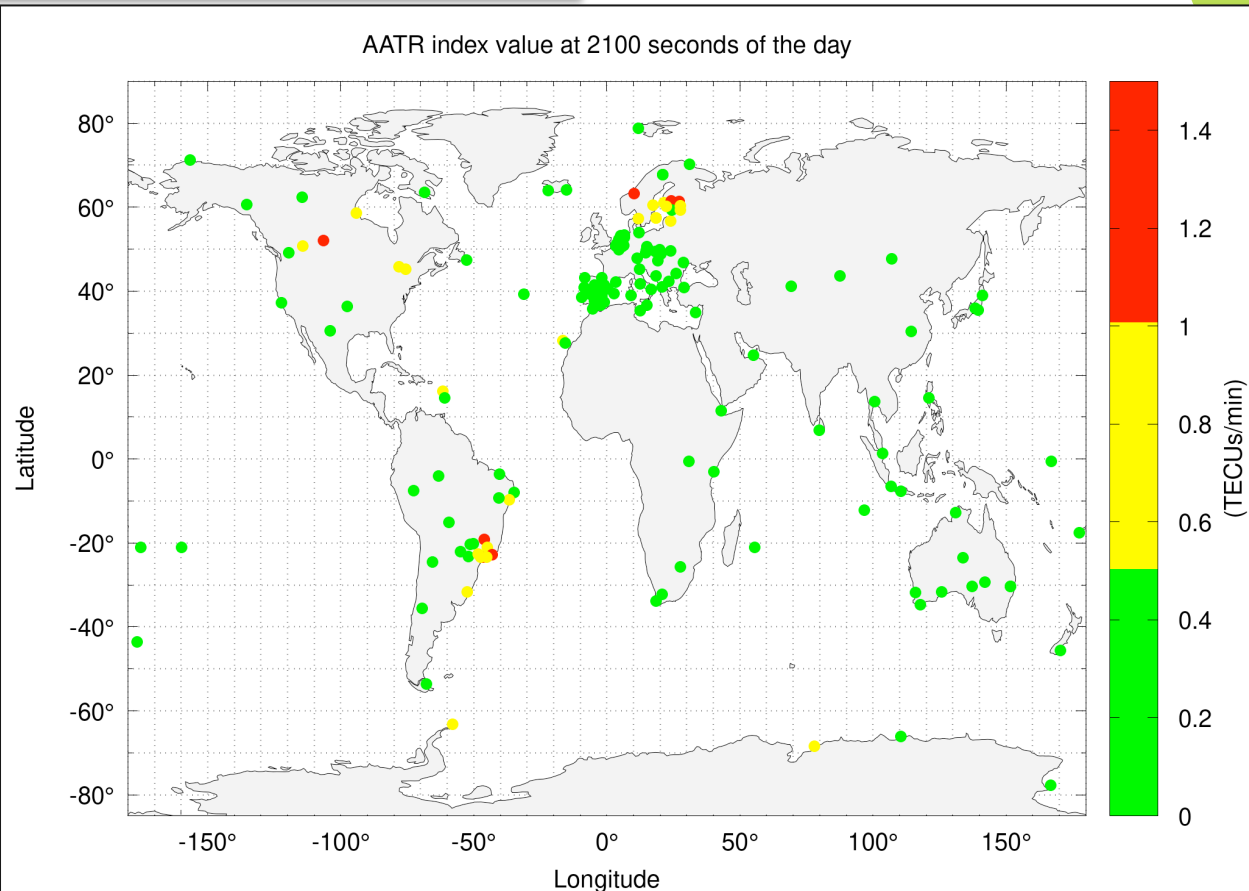
$$L_{GF} = L1 - L2$$

Geometry-free: only frequency-dependent effects

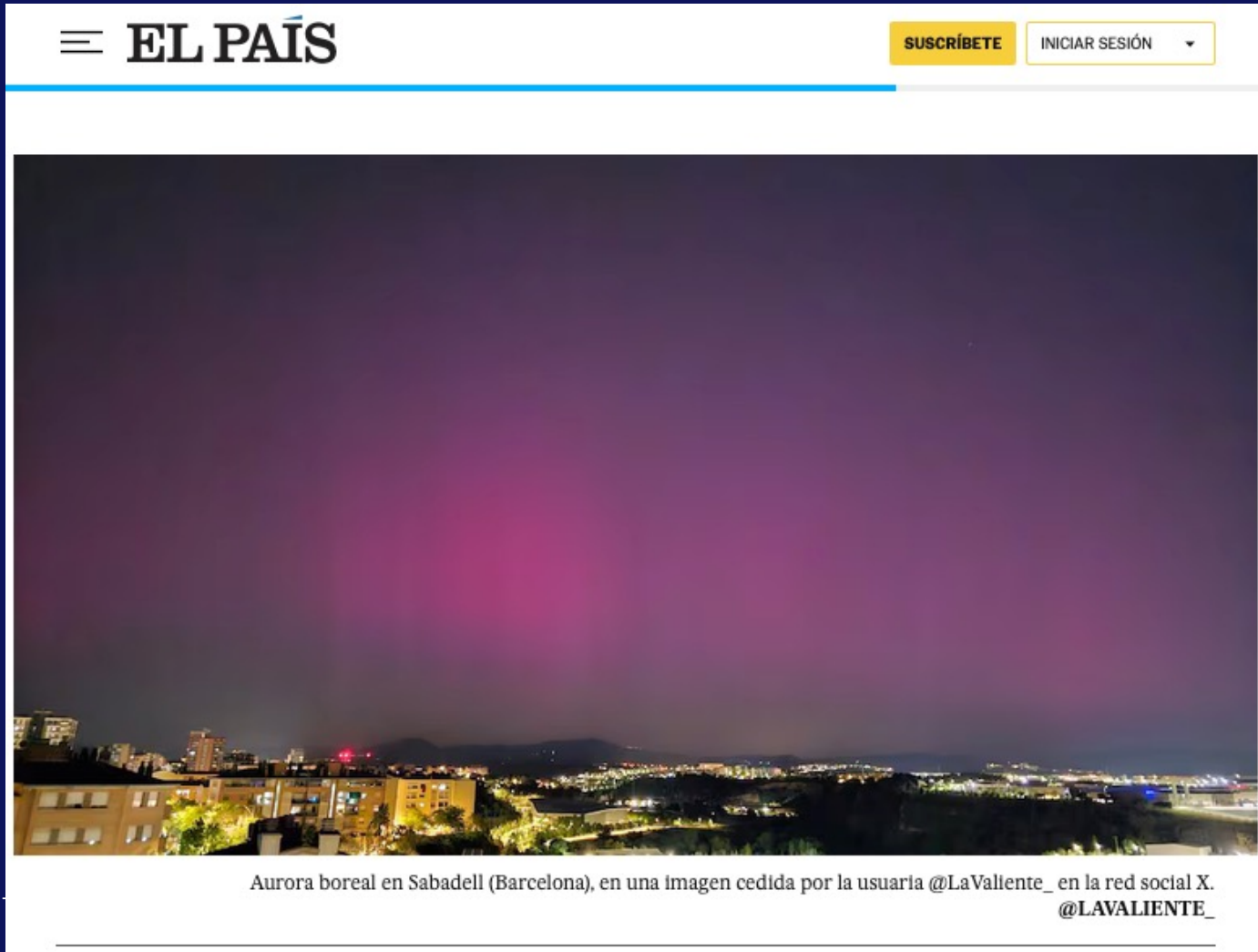
Along-Arc TEC Ratio is defined as:

$$AATR_i^j(t) = \frac{1}{(M(\epsilon))^2} \frac{\Delta STEC_i^j(t)}{\Delta t}$$

$$\Delta STEC_i^j(t) = (LI_i^j(t) - LI_i^j(t - \Delta t))$$



Recent Solar activity



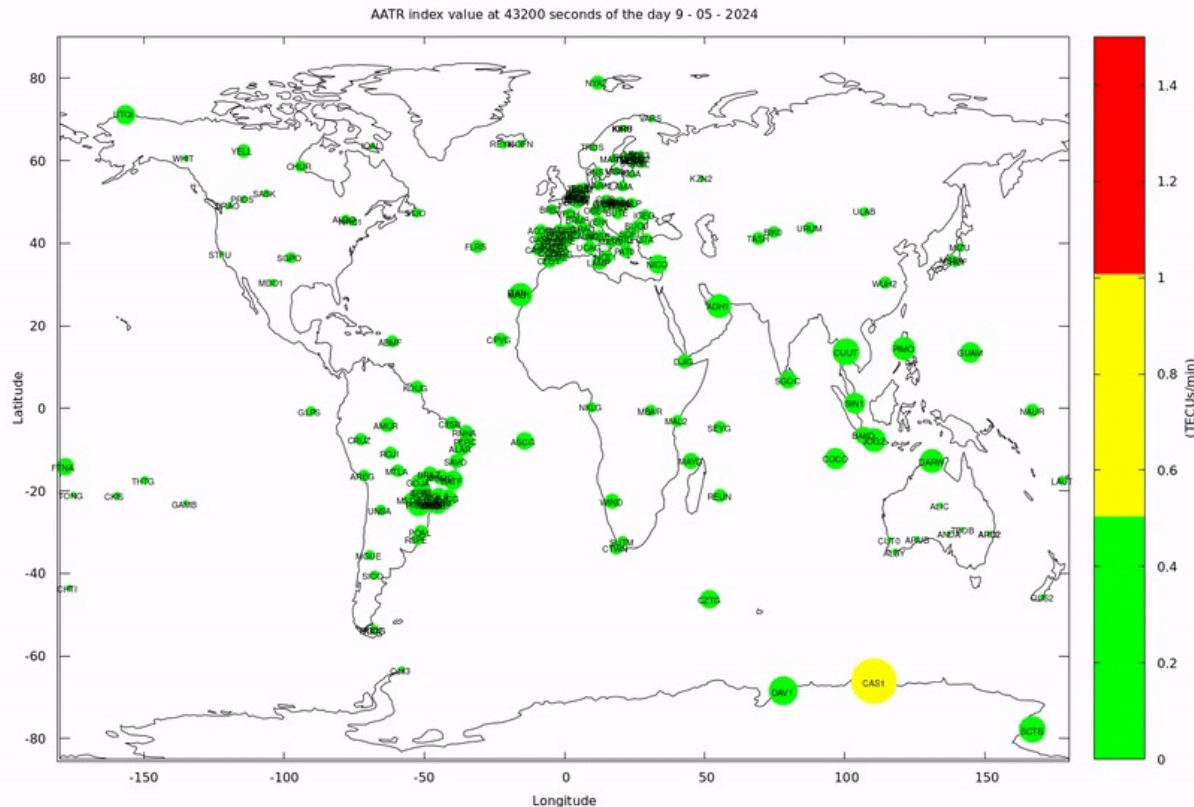
ents which reflects the views
information contained therein.

2. IONO4HAS tool

Ionospheric monitoring indexes: **AATR index**

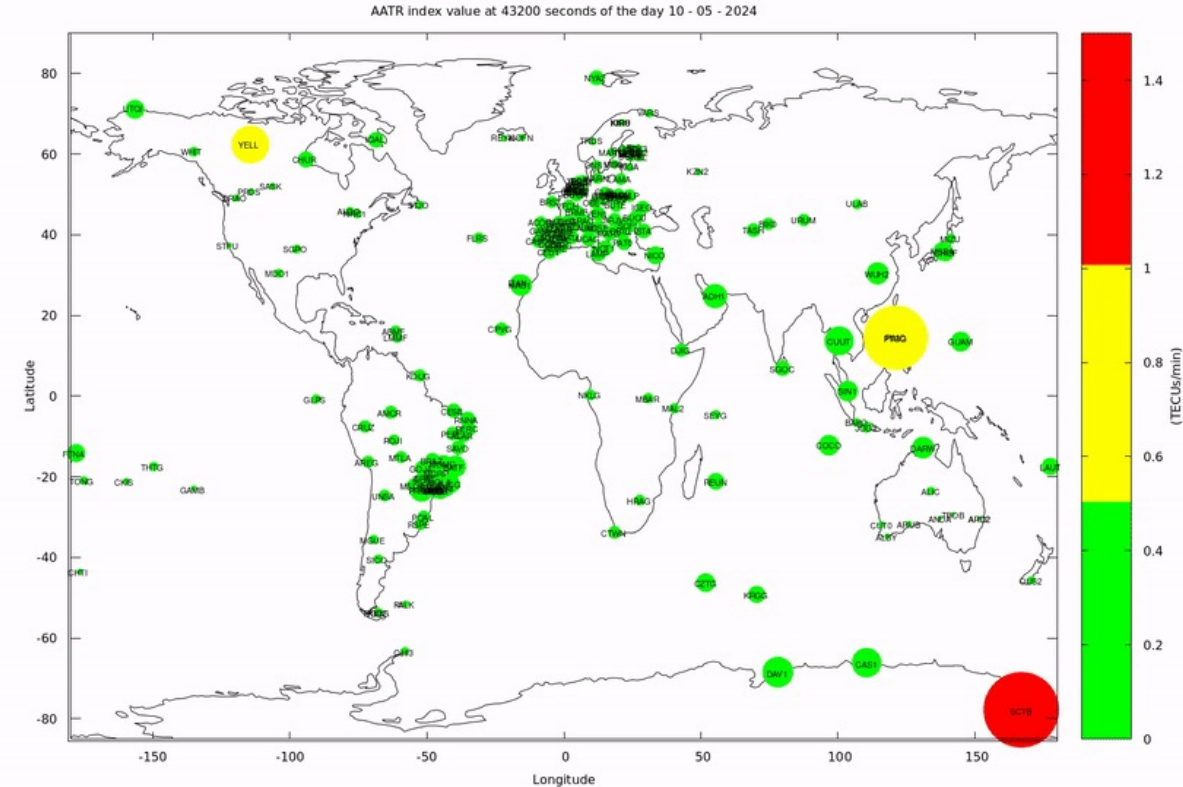
Thursday (May 9th)

From 12:00 to 23:59 (UTC)



Friday (May 10th)

From 12:00 to 23:59 (UTC)



2. IONO4HAS tool

ESA Space Weather Service Network <https://swe.ssa.esa.int/>

THE EUROPEAN SPACE AGENCY


Welcome to the ESA Space Weather Service Network
Please note that all ESA-SWE Services are under review/construction

Expert Service Centres / ESC Ionospheric Weather / techtide-federated /

Federated products from the Ionospheric Group of the National Observatory of Athens (NOA)

Perturbation maps
GNSS TEC gradient
LSTID detector maps
LSTID station plots
LSTID activity index
AATR indicator maps
AATR daily plots
CDSS Doppler shift
MSTID index maps
MSTID daily plots
TID activity report
Acknowledgements

Warning and Mitigation Technologies for Travelling Ionospheric Disturbances Effects (TechTIDE) is a Real-Time (RT) warning system that provides the results of complementary Travelling Ionospheric Disturbance (TID) detection methodologies and many potential drivers to help users assess the risks and develop mitigation techniques tailored to their applications.

The TechTIDE methodologies are able to detect in real time activity caused by both large-scale and medium-scale TIDs and characterize background conditions and external drivers, as an additional information required by the users to assess the criticality of the ongoing disturbances in RT.

TechTIDE methodologies are based on the exploitation of data collected in RT from Digisondes, Global Navigation Satellite System (GNSS) receivers and Continuous Doppler Sounding System (CDSS) networks. The results are obtained and provided to users in RT.

The TechTIDE is provided by the National Observatory of Athens.

View TID Activity | Reference Date: 2024-06-02T20:42:00 UTC

TID Indicators	Date	Critical Characteristic	Current value of critical characteristics	Activity level	Activity icon
AATR	2024-06-02T19:50:00	AATR at polar, high, medium and low latitudes	0.12	LOW	
GNSS TEC Gradient	2024-06-02T20:30	TEC gradient amplitude in high latitudes	2.958	STRONG	

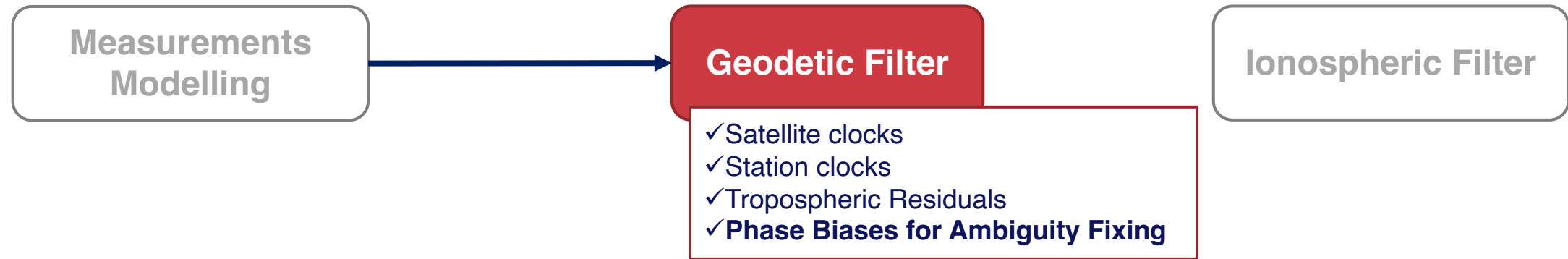
2.2

Geodetic Filter

IONO4HAS ionospheric correction tool

2. IONO4HAS tool

Geodetic Filter



1

B_{IF} ambiguity in the Ionospheric-free combination

B_{IF}

2

B_{WL} ambiguity in the Wide lane combination

B_{WL}

B_{GF} ambiguity in the Geometry-free combination

$$B_{GF} = \alpha[B_{WL} - B_{IF}]$$

Main input of the ionospheric module

$$L_{GF_{rec}}^{sat} - B_{GF_{rec}}^{sat} = STEC_{rec}^{sat} + DCB_{rec} + DCB^{sat}$$

Unambiguous carrier phases

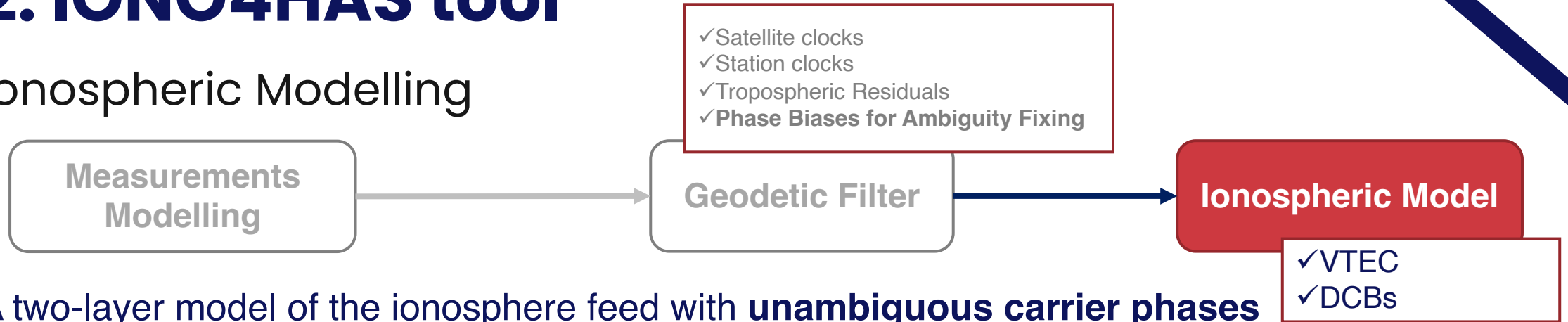
2.3

Ionospheric Modelling Module

IONO4HAS ionospheric correction tool

2. IONO4HAS tool

Ionospheric Modelling

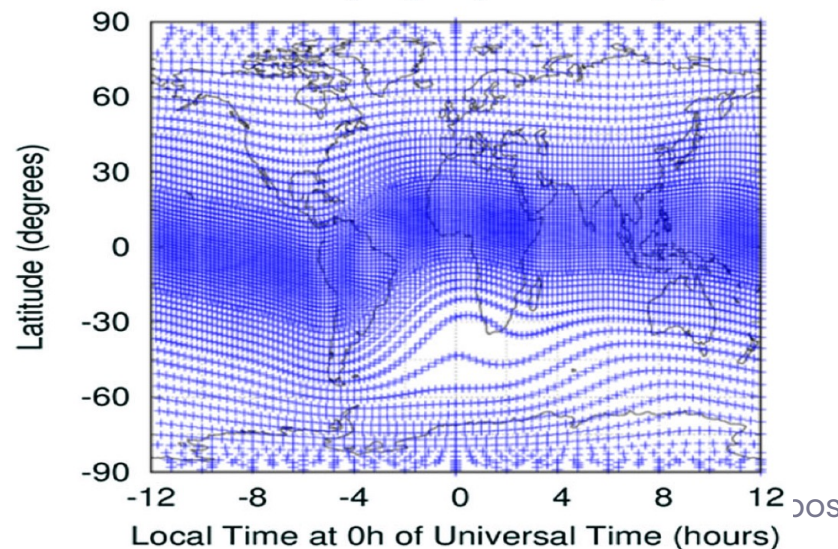


A two-layer model of the ionosphere feed with unambiguous carrier phases

First layer

main ionospheric content

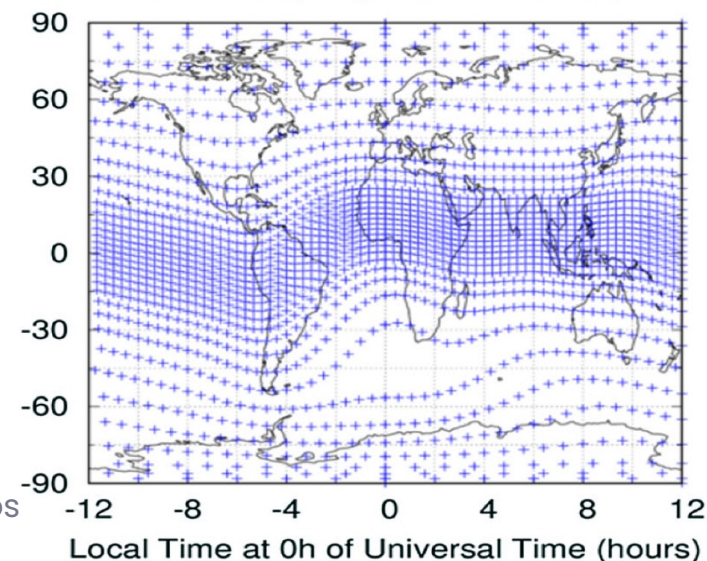
First layer grid (h = 270 km)



Second layer

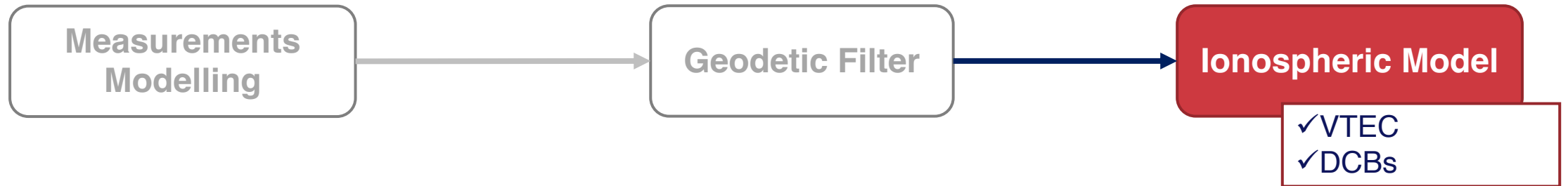
plasmapheric content

Second layer grid (h = 1600 km)



2. IONO4HAS tool

Ionospheric Modelling



The unambiguous carrier-phase measurements can be separated in the ionospheric delay term (STEC) and a constant part (hardware biases).

$$L_{GF_{rec}}^{sat} - B_{GF_{rec}}^{sat} = \mathbf{STEC}_{rec}^{sat} + DCB_{rec} + DCB^{sat}$$

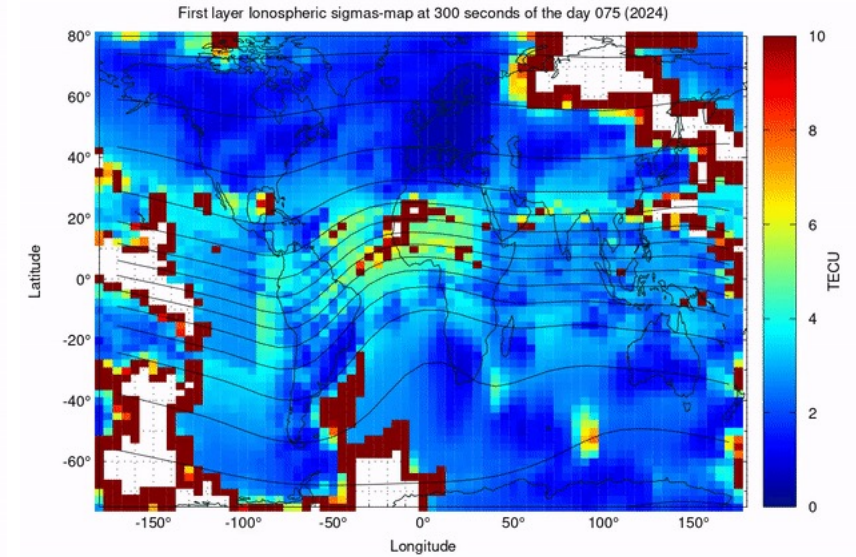
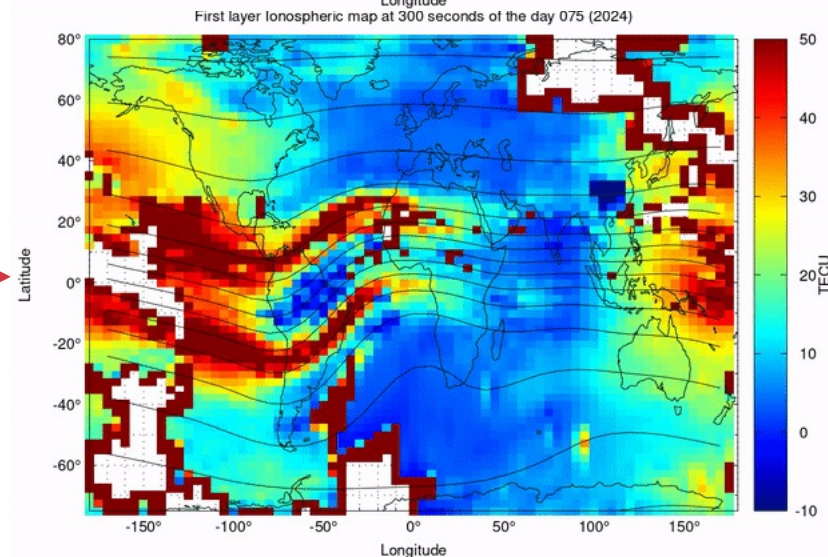
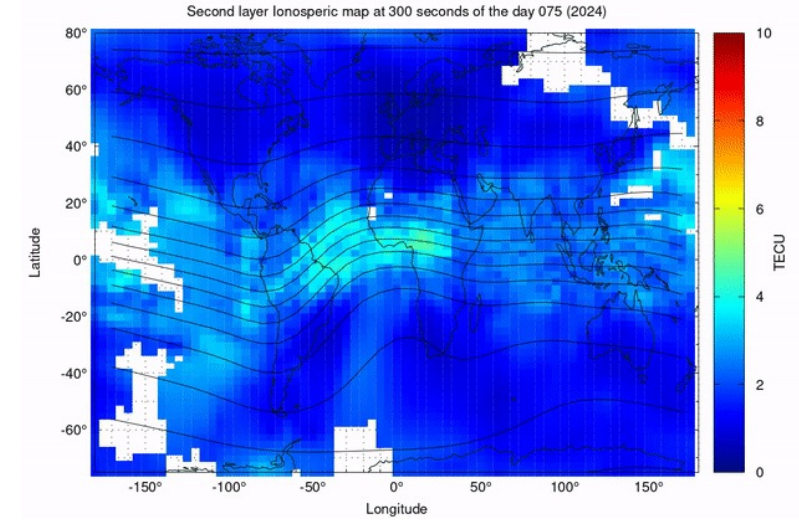
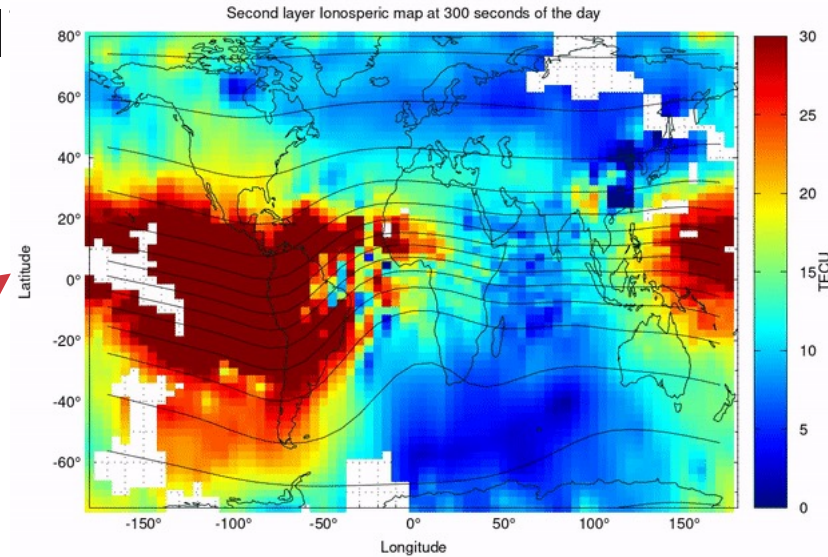
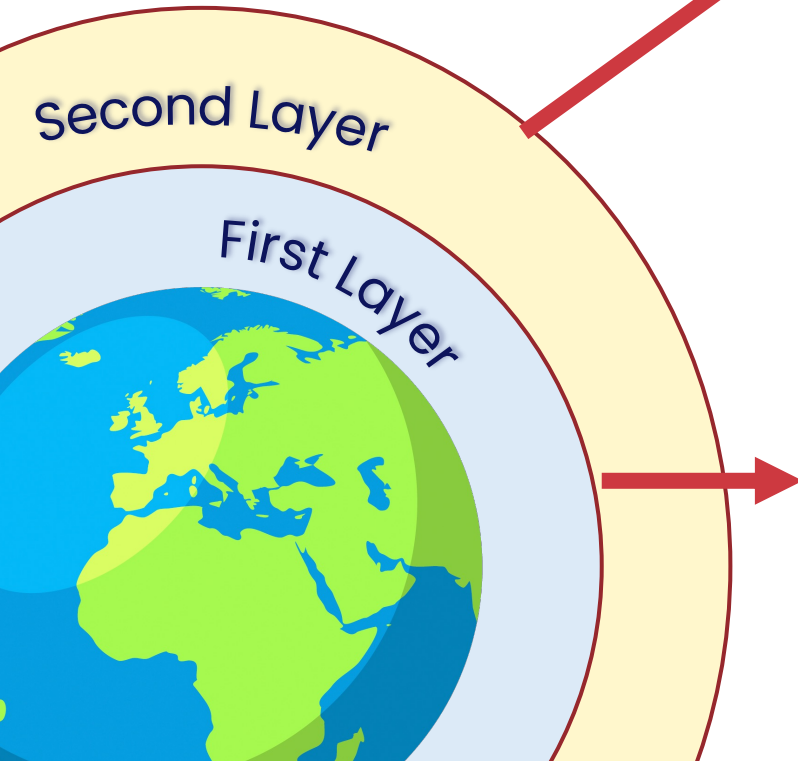
$$\mathbf{STEC}_{rec}^{sat} = M_1(\epsilon) \sum_{i=1}^4 \alpha_i \cdot V_i + M_2(\epsilon) \sum_{j=1}^4 \beta_j \cdot V_j$$

2. IONO4HAS tool

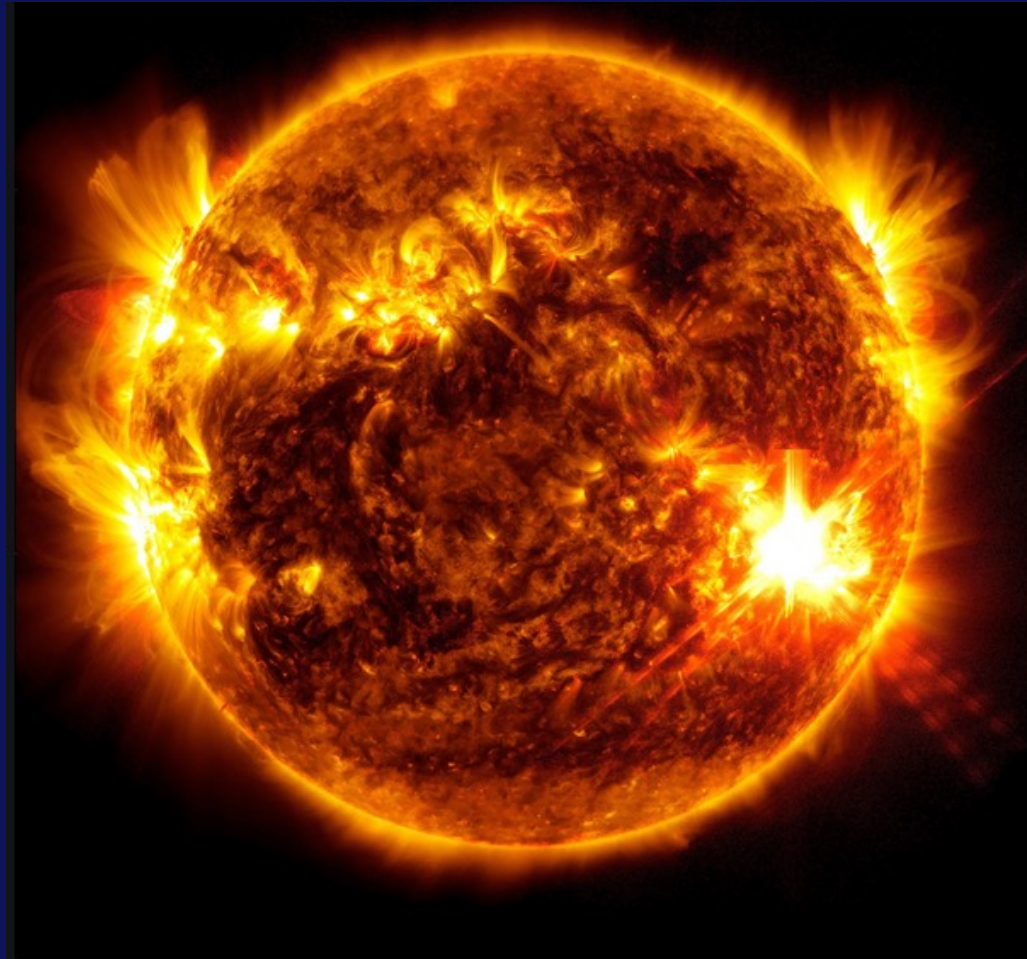
Ionospheric Modell

V (Vertical Electron Content)

SIGMA_V



Recent Solar activity



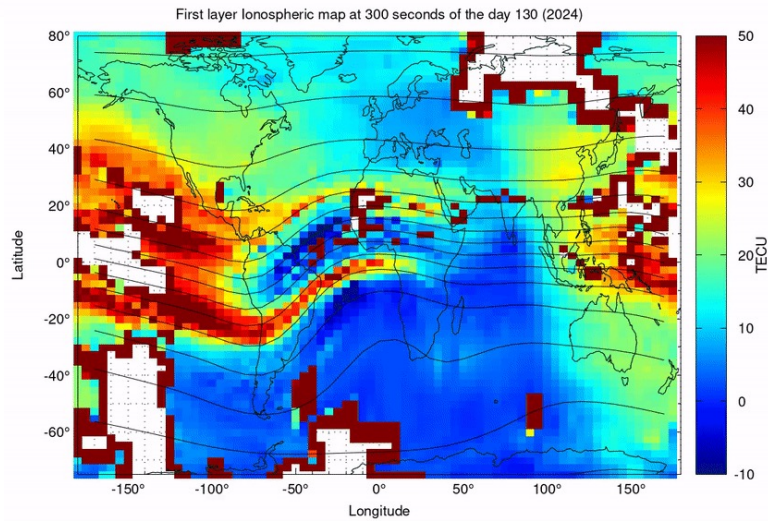
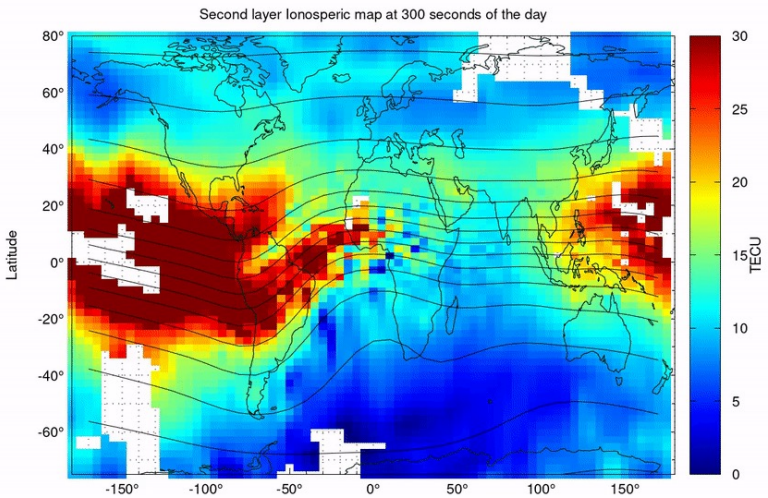
The European Space Agency (ESA) and NASA's Solar Dynamics Observatory (SDO) captured this image of an X5.8 solar flare peaking at 9:23 p.m. EDT on May 10, 2024. The image shows a subset of extreme ultraviolet light that highlights the extremely hot material in flares.

NASA SDO

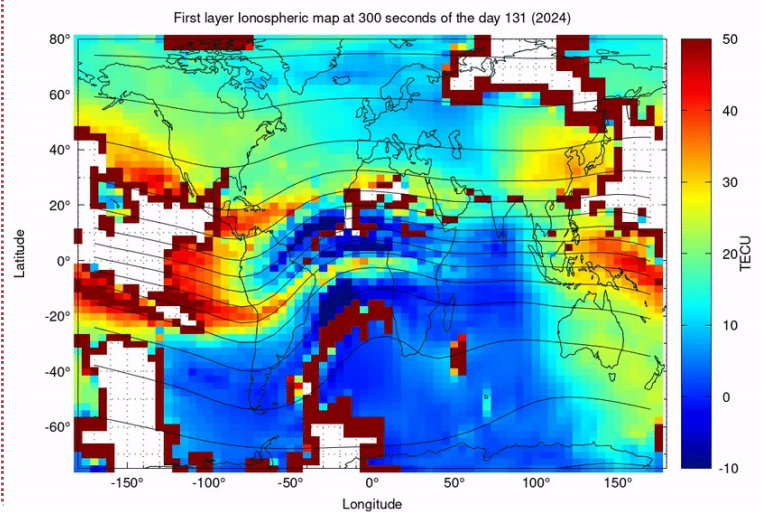
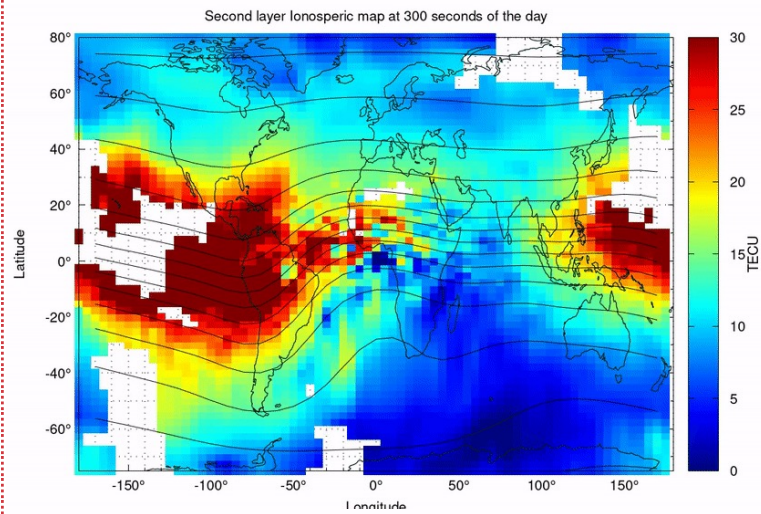
statement of the contents which reflects the views
be made of the information contained therein.

2. IONO4HAS tool

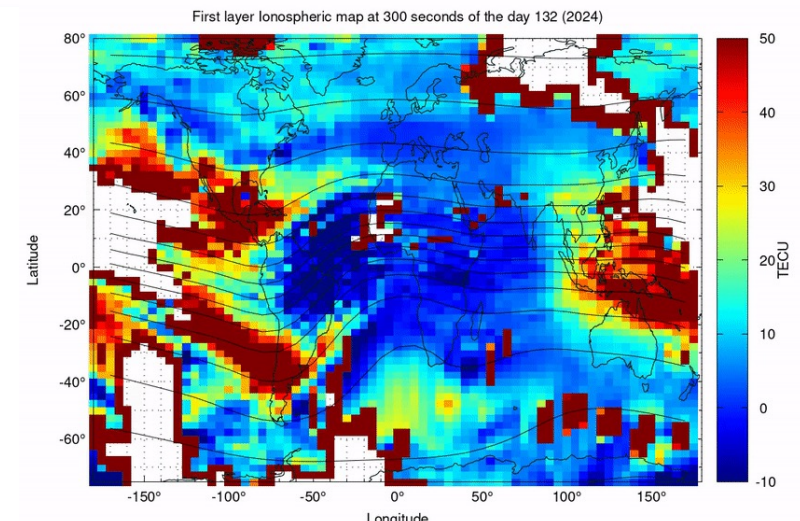
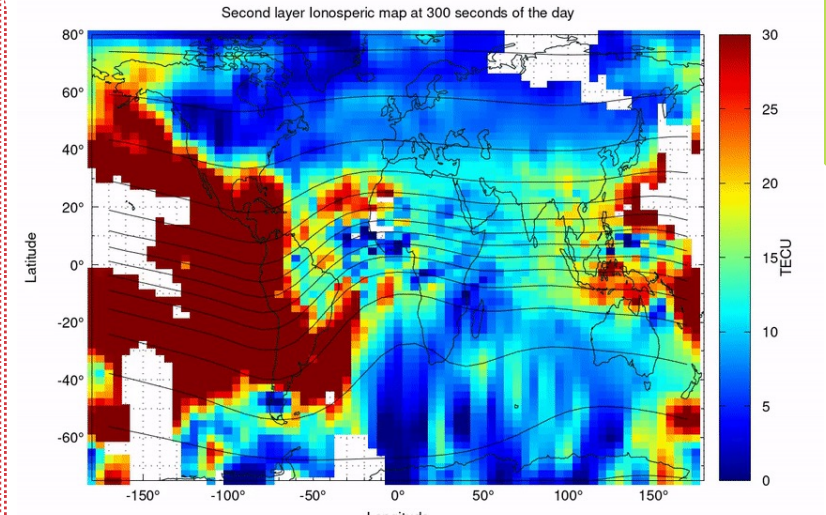
Thursday (09-05)



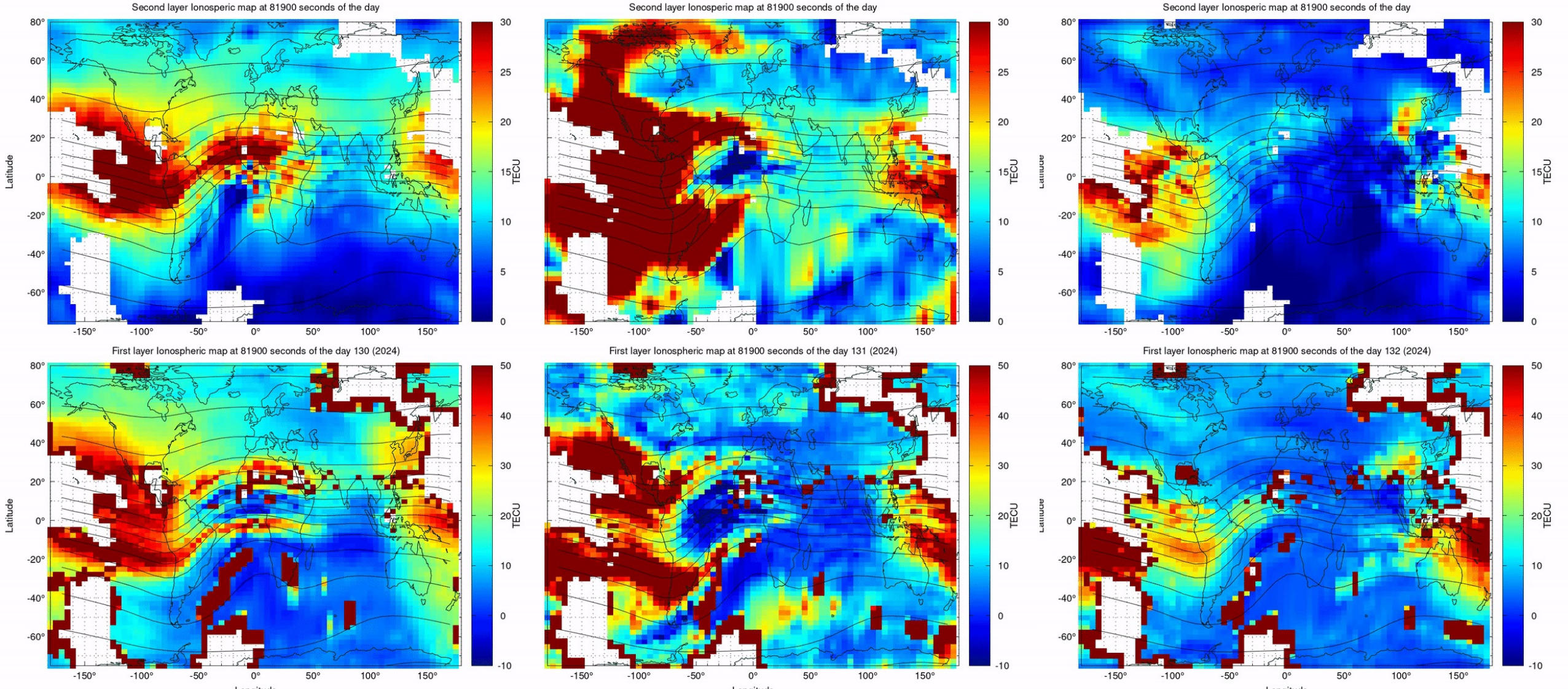
Friday (10-05)



Saturday (11-05)



2. IONO4HAS tool



3

Assessment of the IONO4HAS ionospheric corrections

3. Assessment of the IONO4HAS

Main goal: To define a single-epoch positioning test to link the user error positioning directly to ionospheric corrections.

Wide-lane combination

$$L_{w_{rcv}}^{sat} = \frac{f_i L_{i_{rcv}}^{sat} - f_j L_{j_{rcv}}^{sat}}{f_i - f_j}$$

$$L_{w_{rcv}}^{sat} = \underbrace{\rho_{rcv}^{sat}}_{\substack{\text{Geometric} \\ \text{Range}}} + \underbrace{c(T_{rcv} - T^{sat})}_{\substack{\text{Sat. and} \\ \text{Rec. clock} \\ \text{offsets}}} + \underbrace{Trop_{rcv}^{sat}}_{\substack{\text{Trop.} \\ \text{delay}}} + \underbrace{\alpha_w(I_{rcv}^{sat} + DCB_{rcv} + DCB^{sat})}_{\substack{\text{Iono. delay, sat. and rec.} \\ \text{Differential Code Biases}}} + \underbrace{\lambda_w(N_{w_{rcv}}^{sat} + \delta_{w_{rcv}} + \delta_w^{sat})}_{\substack{\text{Carrier Phase Ambiguity:} \\ \text{1 integer, 2 real.}}} + \underbrace{\epsilon_{LW}}_{\substack{\text{noise} \\ \text{and other} \\ \text{non-} \\ \text{modelled} \\ \text{terms.}}}$$

3. Assessment of the IONO4HAS

Main goal: To define a single-epoch positioning test to link the user error positioning directly to ionospheric corrections.

$$L_{w_{rcv}}^{sat} = \underbrace{\rho_{rcv}^{sat}}_{\downarrow} + c(\underbrace{\hat{T}_{rcv}}_{\downarrow} - T^{sat}) + \underbrace{Trop_{rcv}^{sat}}_{\downarrow} + \alpha_w(I_{rcv}^{sat} + DCB_{rcv} + DCB^{sat}) + \lambda_w(\underbrace{N_{w_{rcv}}^{sat}}_{\downarrow} + \delta_{w_{rcv}} + \underbrace{\delta_w^{sat}}_{\downarrow}) + \epsilon_{LW}$$

$$\rho_{rcv}^{sat} = \rho_{0_{rcv}}^{sat} + G\Delta r$$

$$Trop_{rcv}^{sat} = Trop_{0_{rcv}}^{sat} + M(e)\underbrace{ZTrop_{rcv}}$$

$$\Delta r = r_{rcv} - r_{0_{rcv}}$$

**Terms computed by
the Geodetic Filter**

$$\Delta L_{w_{rcv}}^{sat} - \alpha(I_{rcv}^{sat} + DCB^{sat}) = G\Delta r + c\hat{T}_{rcv} + M(e)_{rcv}^{sat} \cdot ZTrop_{rcv} + \epsilon_{LW}$$

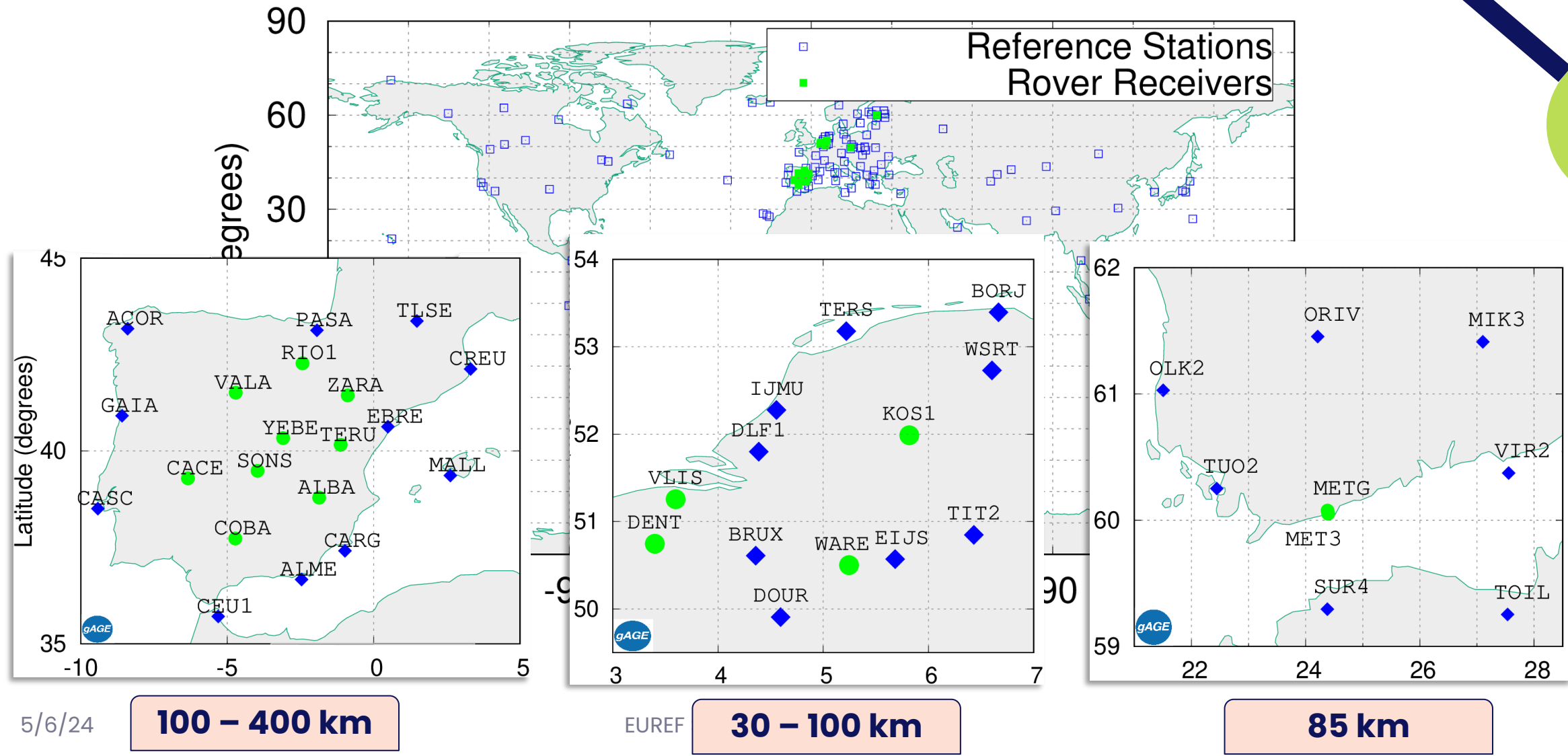
Direct link between ionospheric corrections and rover positioning error.

Note that $c\hat{T}_{rcv} = cT_{rcv} + \delta_{w_{rcv}} + \alpha_w DCB_{rcv}$

4

Results

4. Results

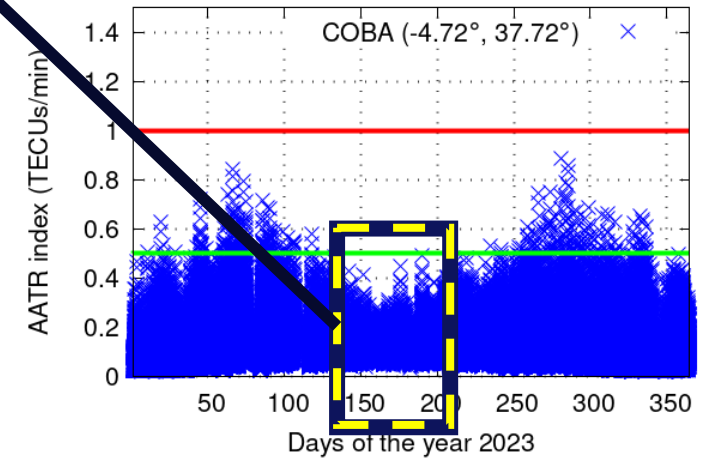
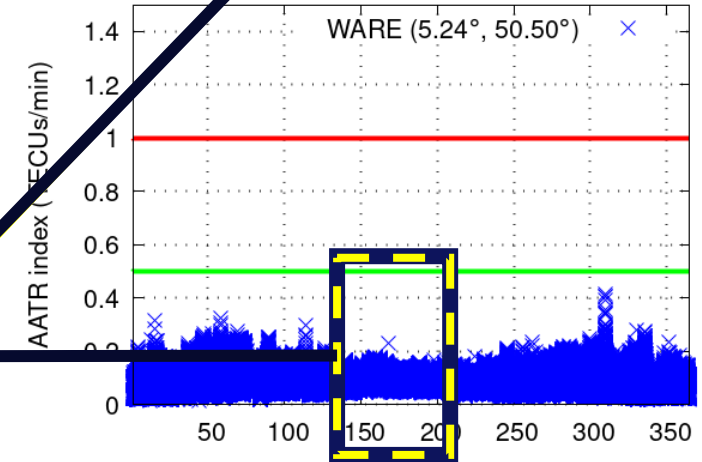
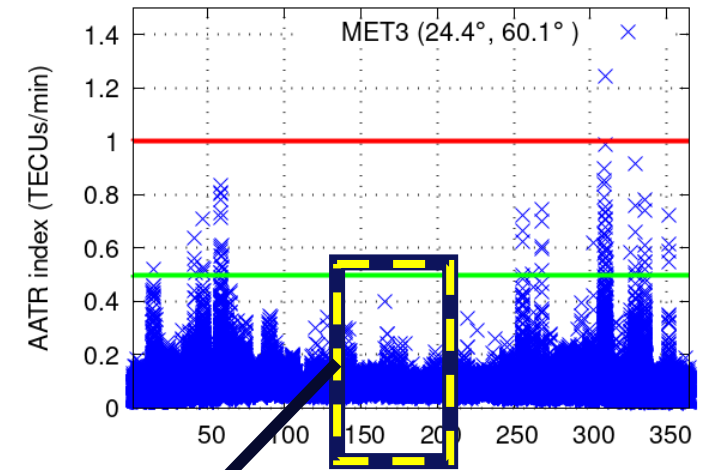
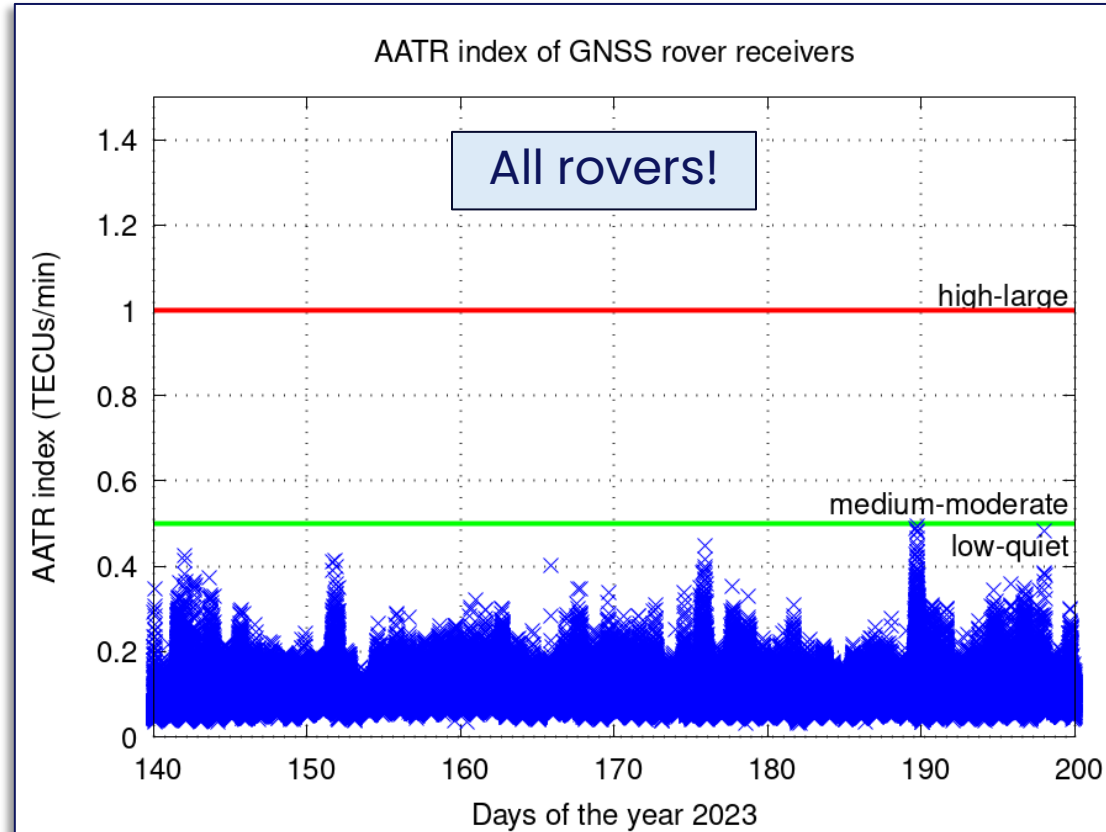


4. Results

Data window: from DoY 140 up to 200 (2023)

Ionospheric activity characterization using the Along Arc TEC Ratio (AATR index)

A period with nominal ionosphere is selected to test the prototype

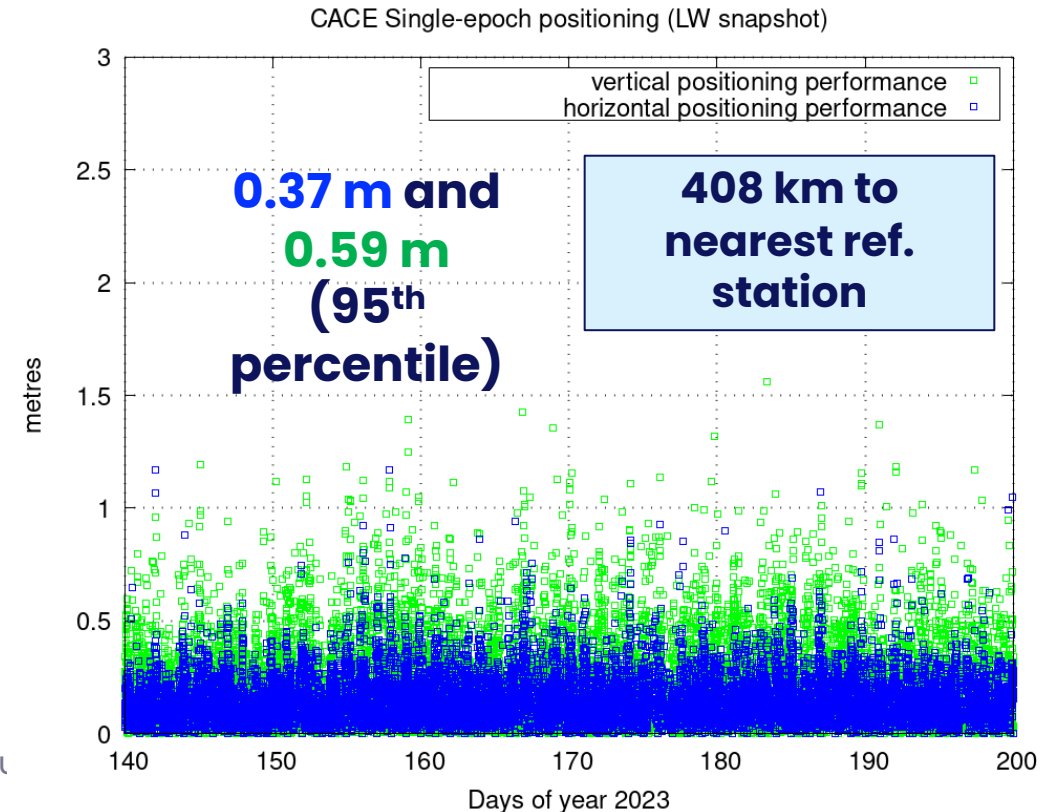
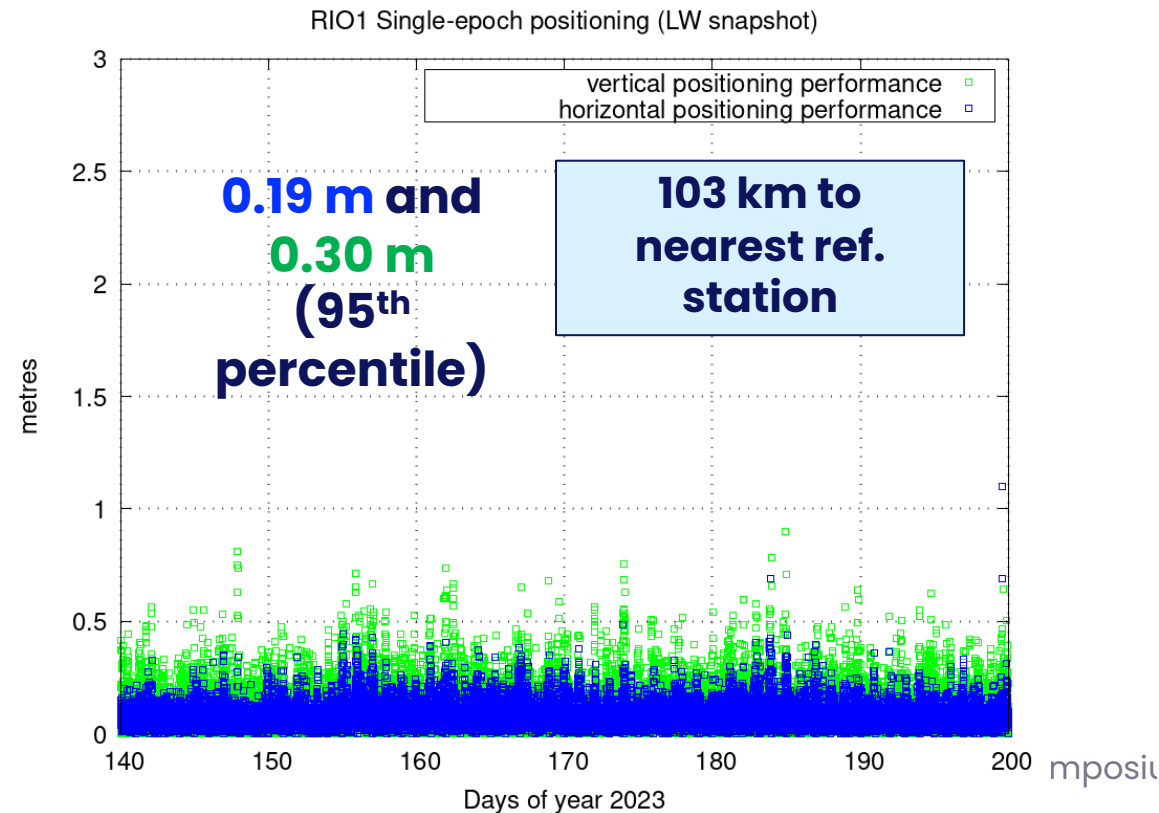


4. Results

Real-time validation of ionospheric corrections

**Position error due
strictly to
ionospheric
mismodelling**

Instantaneous positioning error (no convergence time)



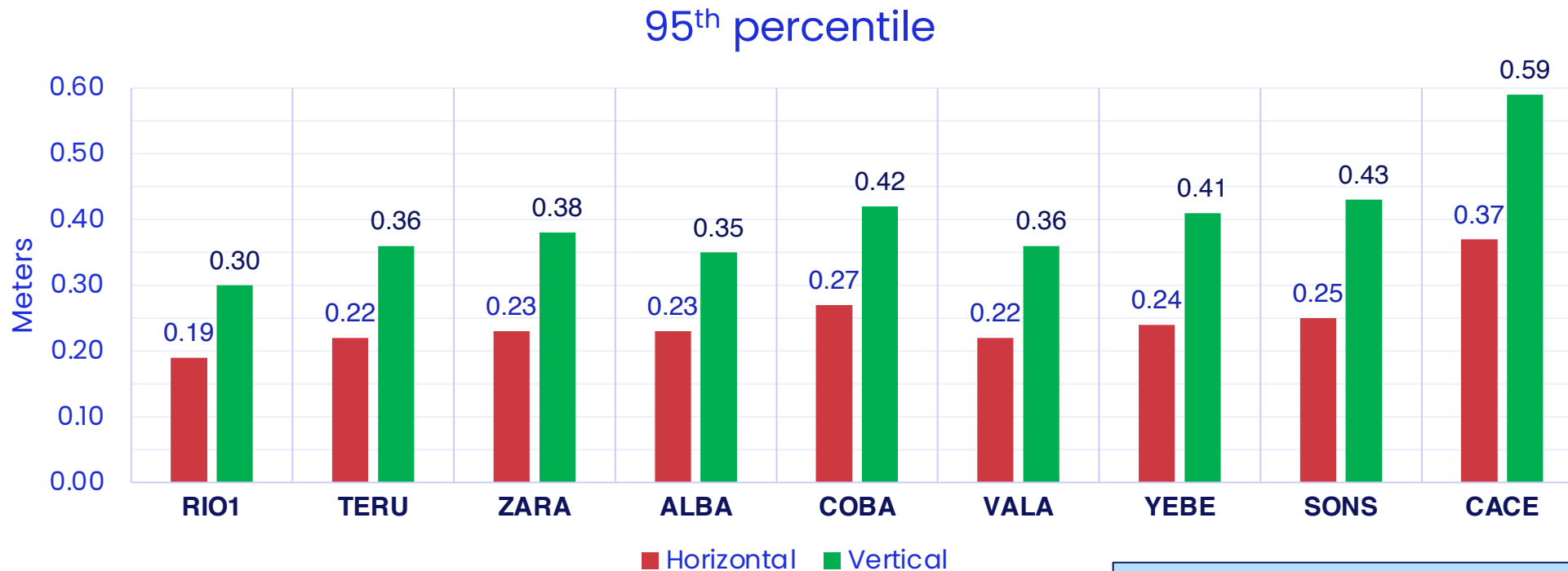


Requirement
GALILEO HAS
hor. 20 cm
ver. 40 cm
In 100 s

4. Results

Real-time validation of ionospheric corrections through the 95th percentile

Instantaneous positioning error (no convergence time): **10 to 30 cm (hor)**, **20 to 50 cm (ver)**.



Network Baseline: **100 – 400 km**

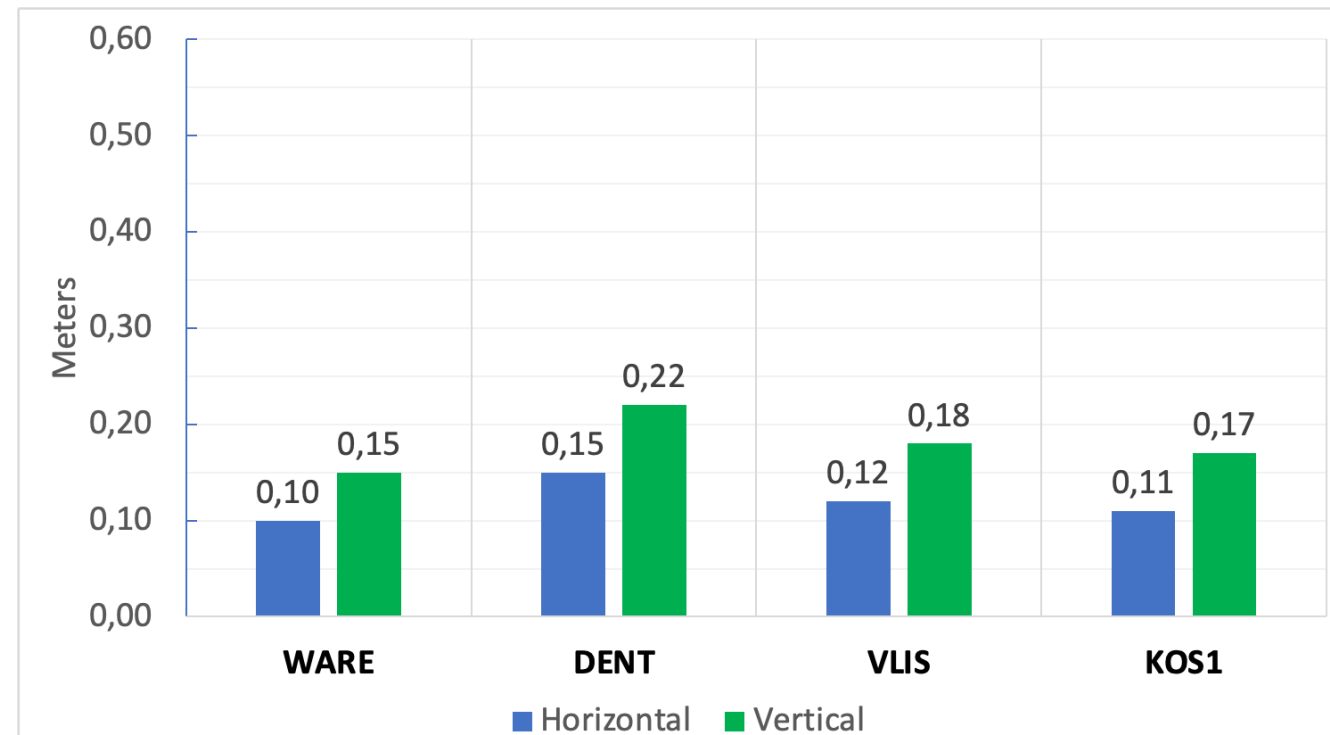
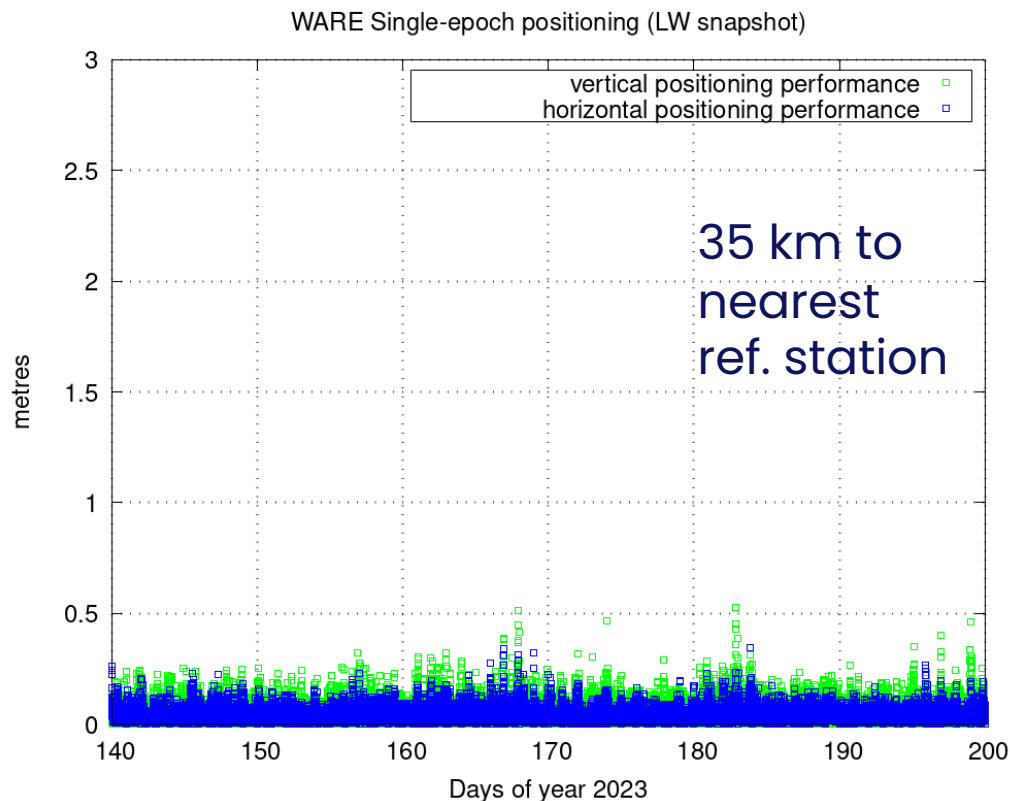
Positioning error related with distance of the user receiver to nearest ref. receiver

4. Results

Real-time validation of ionospheric corrections through the 95th percentile

Instantaneous positioning error (no convergence time): **10 to 15 cm (hor)**, **15 to 22 cm (ver)**

**Requirement
GALILEO HAS
hor. 20 cm
ver. 40 cm
In 100 s**



symposium 2024

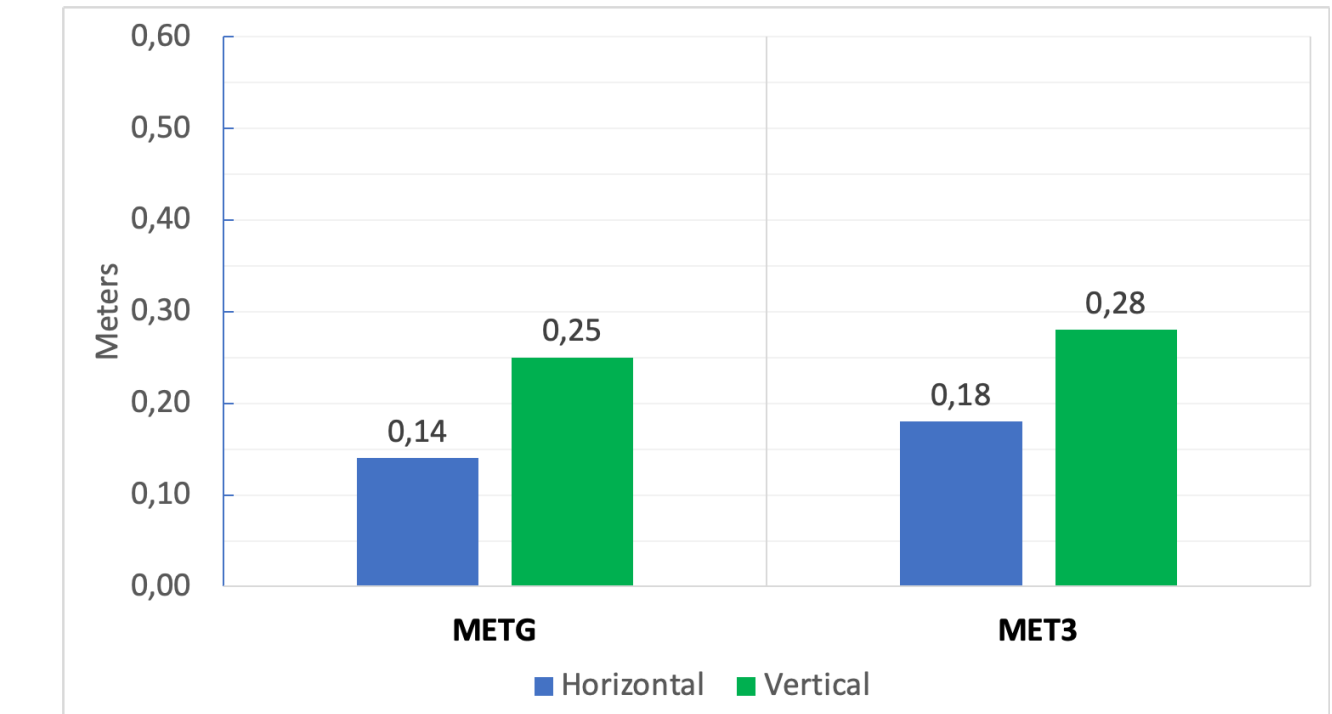
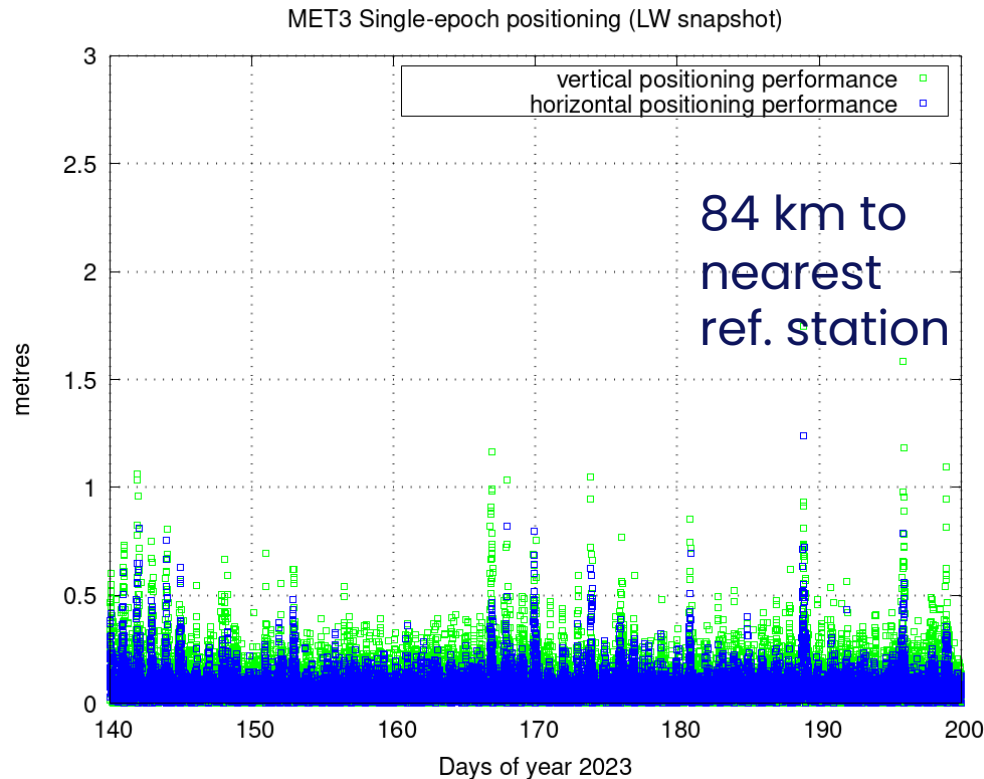
Network Baseline: 30 – 100 km

4. Results

Real-time validation of ionospheric corrections through the 95th percentile

Instantaneous positioning error (no convergence time): **14 to 18 cm (hor)**, **25 to 28 cm (ver)**

Requirement
GALILEO HAS
hor. 20 cm
ver. 40 cm
In 100 s



Network Baseline: **85 km**

4. Results

Timote, C. C., Juan, J. M., Sanz, J., Rovira-García, A., González-Casado, G., Orús-Pérez, R., ... & Blonski, D. (2024). Ionospheric corrections tailored to Galileo HAS: validation with single-epoch navigation. *GPS Solutions*, 28(2), 93.

Single-epoch (first epoch) comparison strategies:

$$\Delta P_{IF} = \mathbf{G}\Delta\mathbf{r} + c(T_{rcv}) + M(e)_{rcv}^{sat} \cdot ZTrop_{rcv} + E_{IF}$$

$$\Delta L_{IF} = \mathbf{G}\Delta\mathbf{r} + c(T_{rcv}) + M(e)_{rcv}^{sat} \cdot ZTrop_{rcv} + \lambda_N w^{sat} + B_c^j + \epsilon_{IF}$$

NO-IONO

Classical PPP

Single-epoch solution is driven the **Code IF**

$$\Delta L_{w_{rcv}}^{sat} - \alpha(I_{rcv}^{sat} + DCB^{sat}) = \mathbf{G}\Delta\mathbf{r} + cT_{rcv} + M(e)_{rcv}^{sat} \cdot ZTrop_{rcv} + \epsilon_{Lw}$$

IGRG

IGS corrections

$$\Delta L_{w_{rcv}}^{sat} - \alpha(I_{rcv}^{sat} + DCB^{sat}) = \mathbf{G}\Delta\mathbf{r} + cT_{rcv} + M(e)_{rcv}^{sat} \cdot ZTrop_{rcv} + \epsilon_{Lw}$$

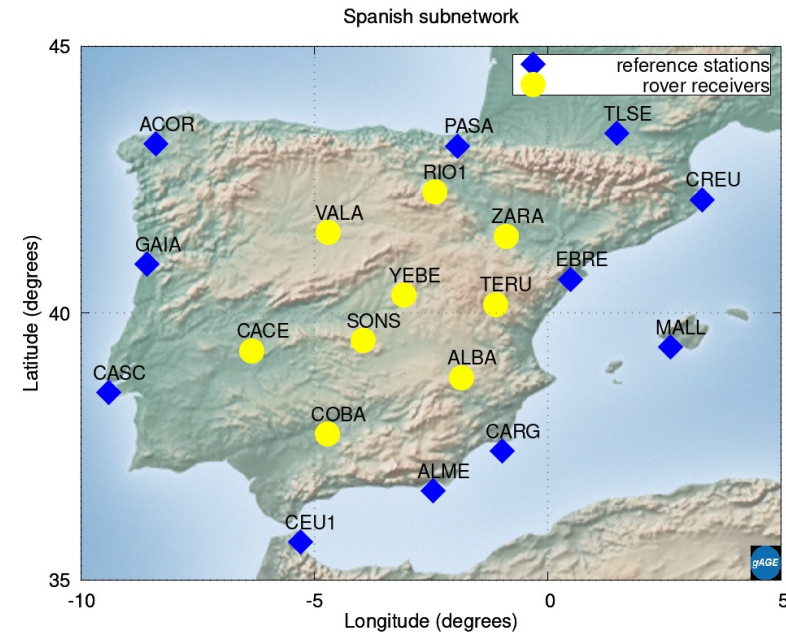
IONO4HAS

IONO4HAS corrections

4. Results

Validation with other products in single-epoch PPP

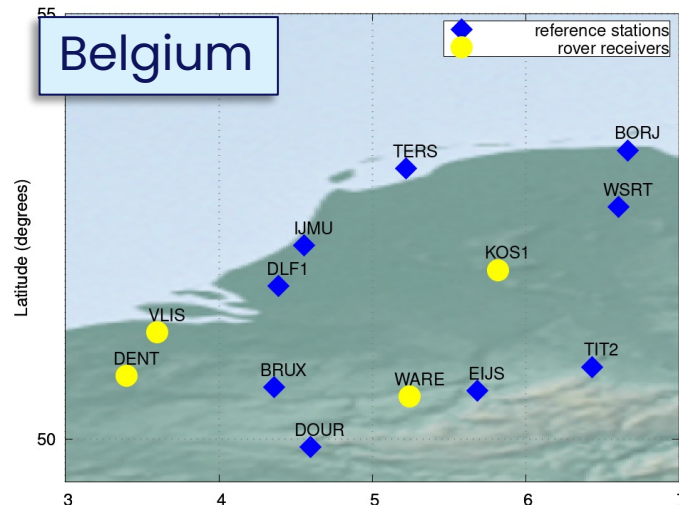
Iberian Peninsula



	95 th percentile horizontal error (m)			95 th percentile vertical error (m)		
	NO-IONO	IGRG	IONO4HAS	NO-IONO	IGRG	IONO4HAS
RIO1	2.05	0.58	0.19	3.06	0.91	0.32
TERU	1.70	0.61	0.21	2.59	1.07	0.41
ZARA	1.83	0.60	0.19	3.04	1.00	0.32
ALBA	2.20	0.56	0.23	3.46	0.95	0.37
COBA	1.65	0.61	0.25	2.72	1.06	0.41
VALA	1.53	0.57	0.22	2.33	0.90	0.37
YEBE	2.06	0.65	0.22	3.29	1.15	0.46
SONS	1.77	0.62	0.25	2.95	1.10	0.45
CACE	2.32	0.71	0.32	3.98	1.22	0.52

4. Results

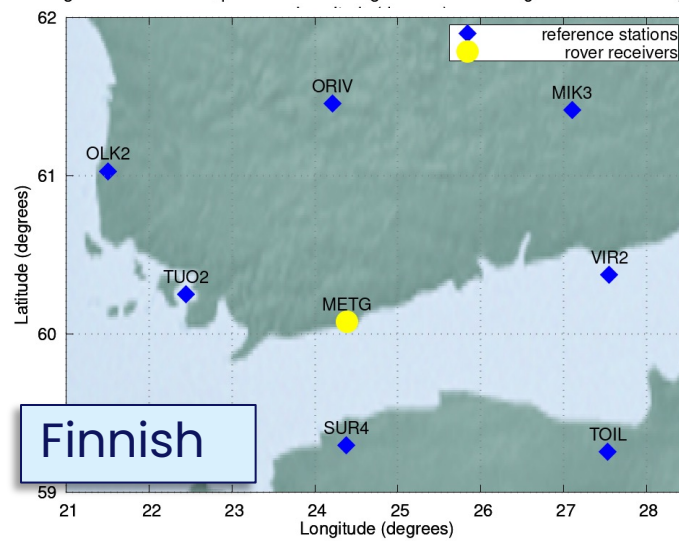
Validation with other products in single-epoch PPP



WARE
VLIS
DENT
KOS1

95 th percentile horizontal error (m)		
NO-IONO	IGRG	IONO4HAS
1.25	0.56	0.12
1.61	0.54	0.13
1.23	0.57	0.14
1.23	0.59	0.12

95 th percentile vertical error (m)		
NO-IONO	IGRG	IONO4HAS
1.94	0.92	0.18
2.50	0.85	0.20
1.97	0.94	0.21
2.07	1.00	0.19



METG
MET3

95 th percentile horizontal error (m)		
NO-IONO	IGRG	IONO4HAS
0.86	0.37	0.18
1.59	0.61	0.19

95 th percentile vertical error (m)		
NO-IONO	IGRG	IONO4HAS
1.30	0.59	0.26
2.70	1.08	0.29

5

gAGE RT products portal

5. gAGE RT products portal

<https://server.gage.upc.edu/iono4has/>

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<https://gage.upc.edu/en>



Thank you!

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www.spacesuite-project.eu

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