

EUREF 2006

Impact of antenna mounting on phase centre variation

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NETPOS

Governmental RTK network

- Topcon PG-A1 antennas 14 cm, 0.5 kg
- Topcon Odyssey RS receiver

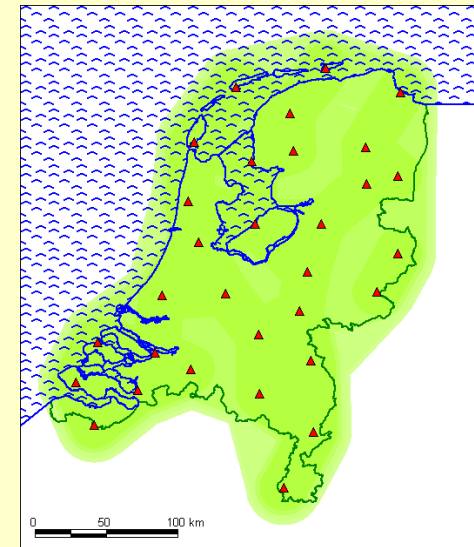


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Quality validation

Test measurements:

- 84 points of the passive GPS base network
- x 10 initialisations
- x 10 measurements



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Quality validation results

Precision (1 sigma):

- 6 mm longitude
- 9 mm latitude
- 17 mm height

Problem

Systematic height error of **31 mm**

- All measured height coordinates too high!
- Cause unknown
- Determination difficult

Solution

Antenna calibration with mount



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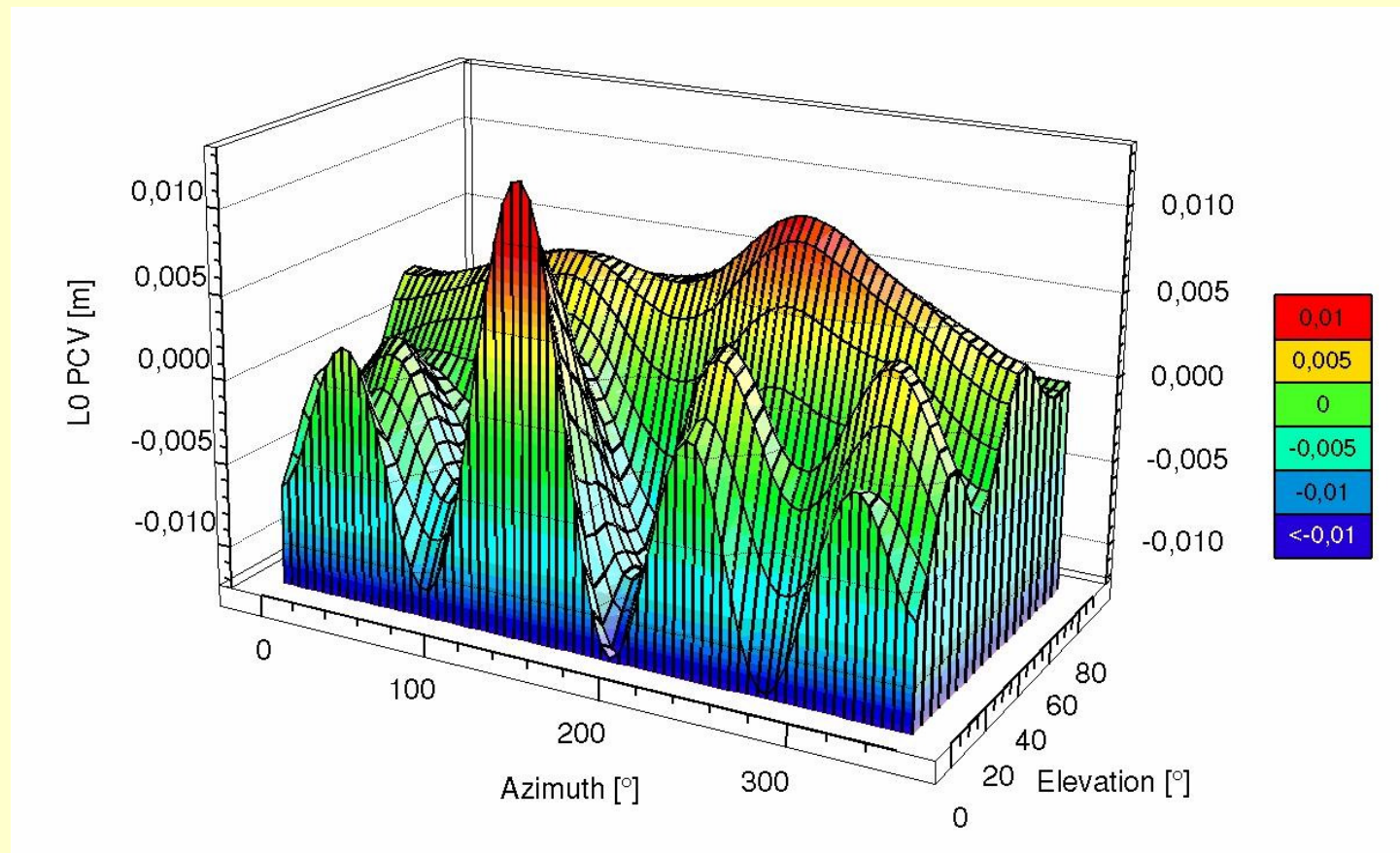
Calibration at Geo++

- Absolute calibration with robot



Calibration at Geo++

- Spherical harmonic expansion (degree 8, order 5)
- Accuracy (repeatability) 1 mm



Calibration results

Difference in calibration with and without mount:

	L1	L2
Mean:	3 mm	9 mm
Variation (max.):	3 mm	8 mm

Near field effect

Influence of mounting and direct environment on phase centre variation (PCV)

Mainly caused by:

- Very long periodic multipath
- Electromagnetic interaction

Near field effect

Large due to:

- Antenna mount
- Antenna type



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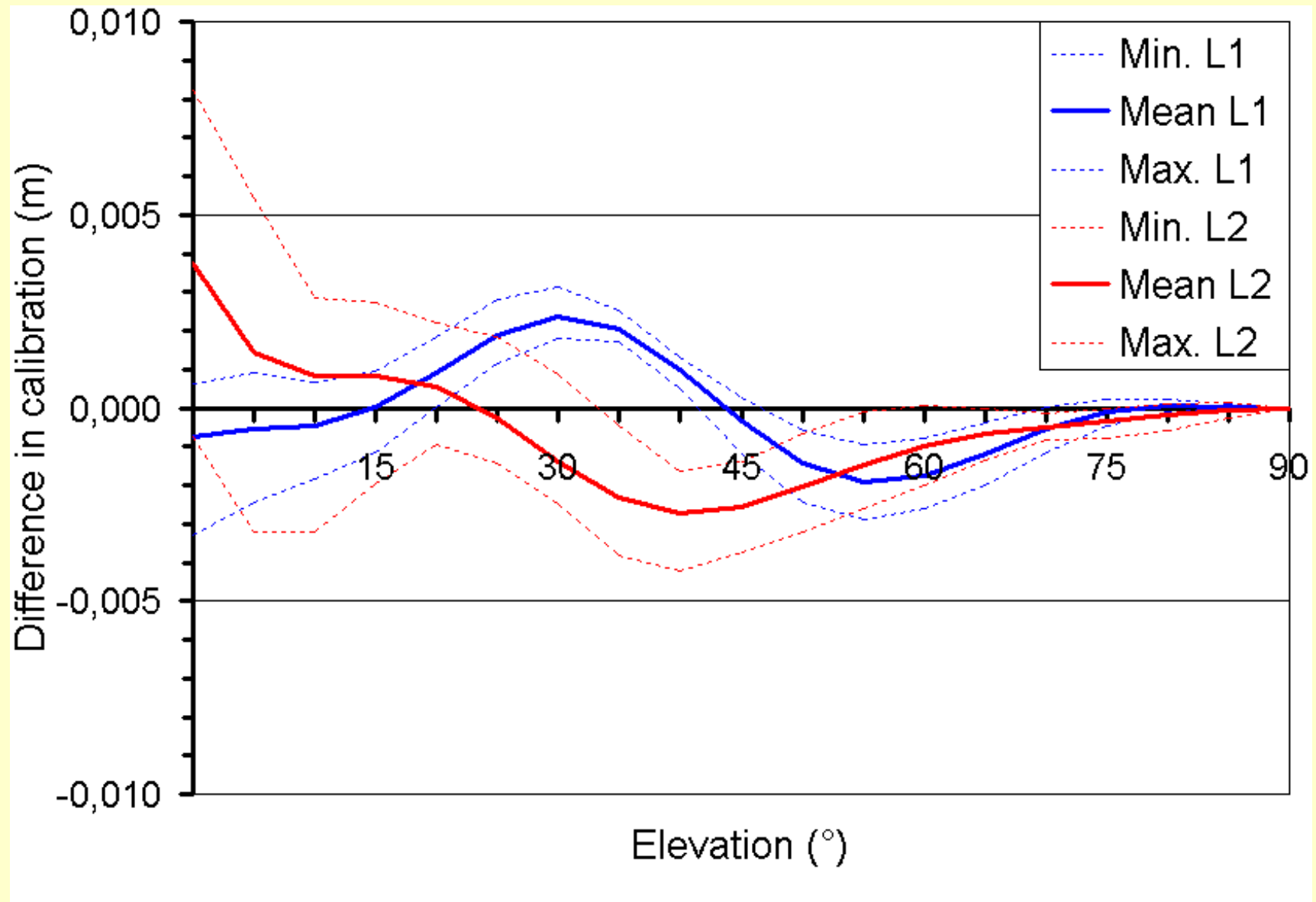
Impact on rover positioning

- Effect on mean cancelled out
- Effect on variation (9 mm) amplified (31 mm)

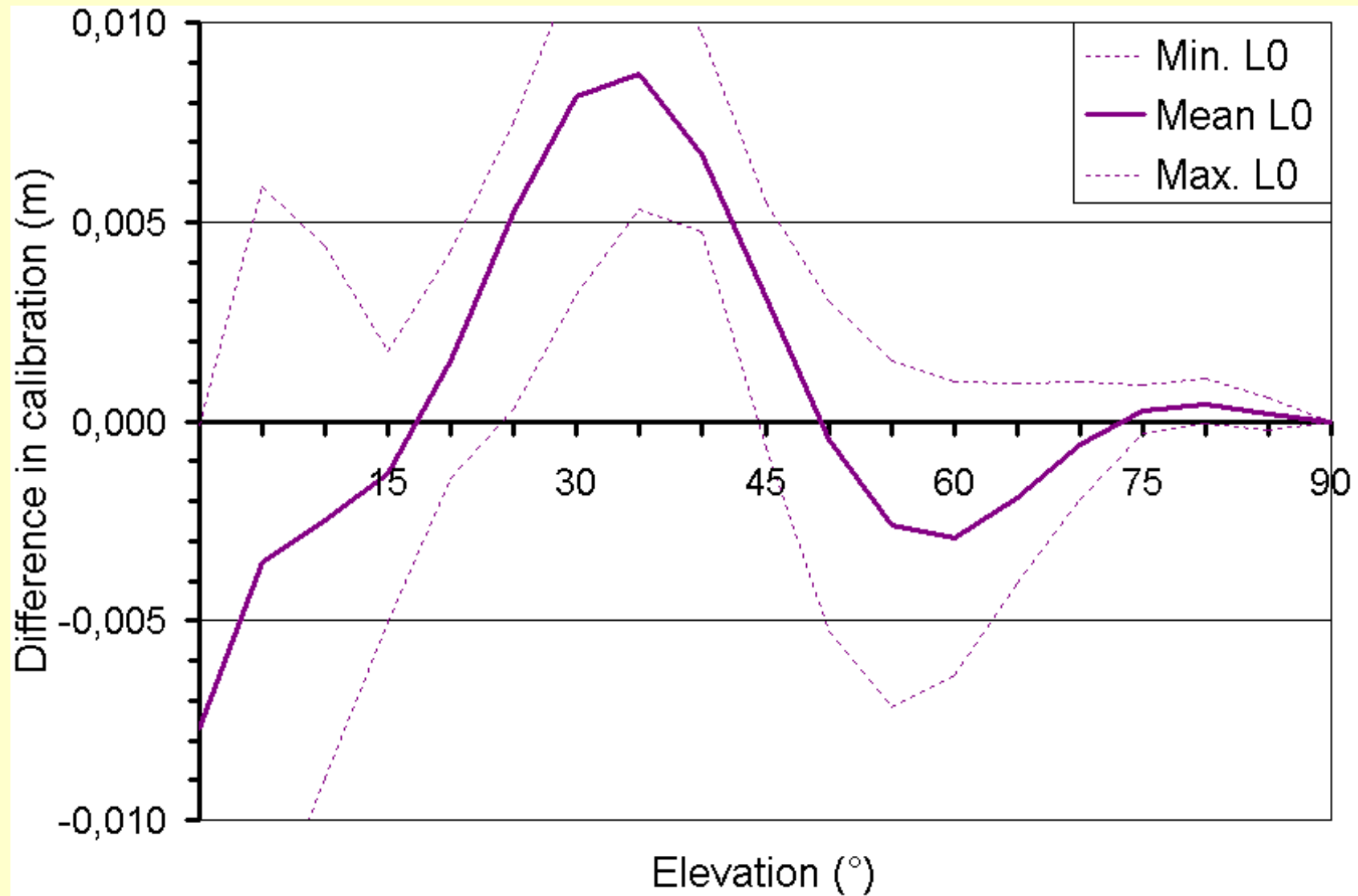
Amplification

- Ionosphere free linear combination 3 x larger
due to different influence on L1 and L2
- Tropospheric modelling
due to mixing up PCV and troposphere
- Effect of satellite geometry
due to unmodelled PCV

Different influence on L1 and L2



Ionosphere free linear combination



Conclusions

- Near field effect of mounting on phase centre
- Impact on rover positioning $> 3 \times$
- Solution: calibration with mount
- Relevant for all users of reference stations
- *Kadaster* will calibrate all new antennas including the mount

Questions?
