



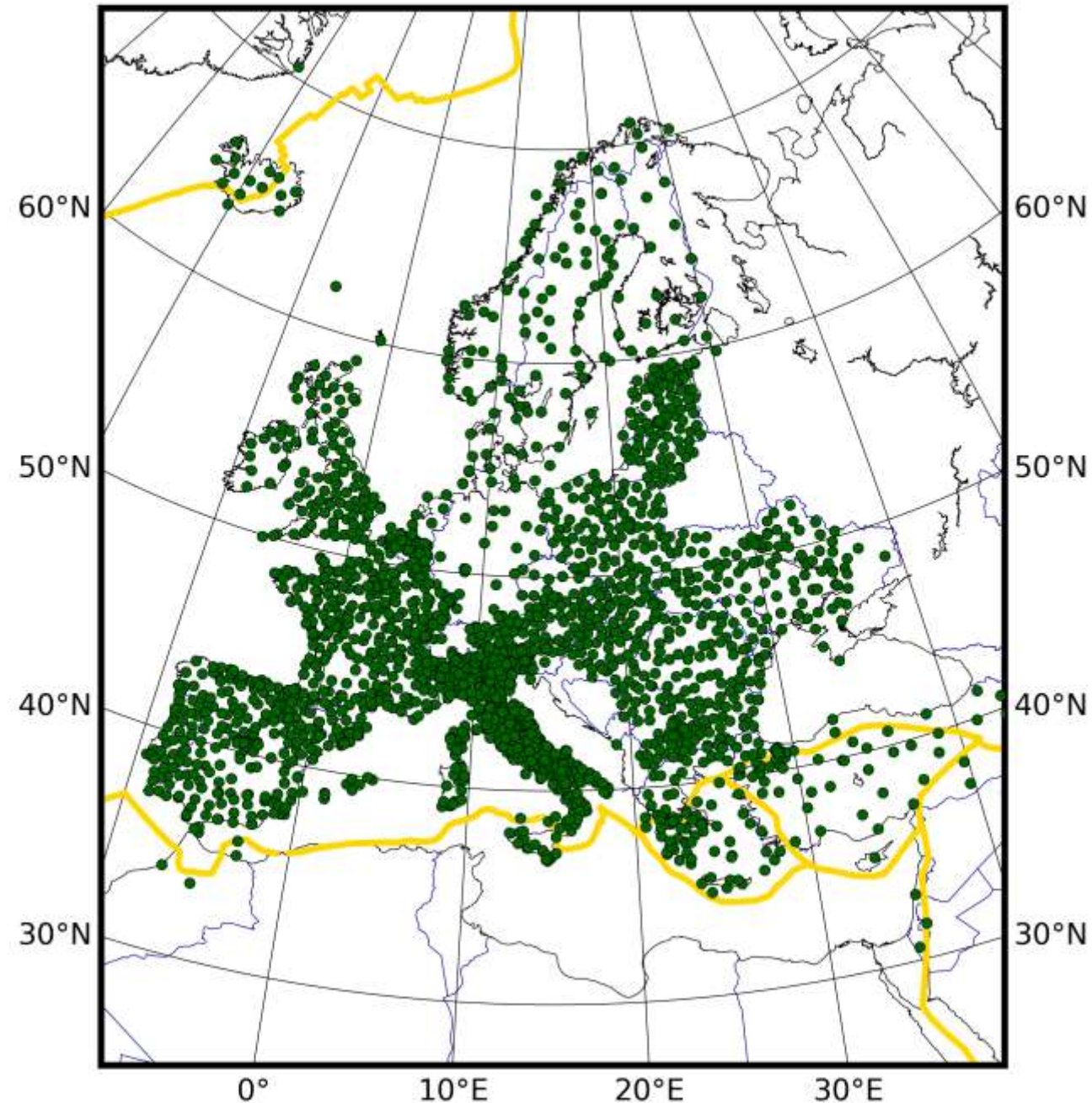
EUVEM2021 – A VELOCITY MODEL FOR EUROPE: APPLICATION OF LEAST-SQUARES COLLOCATION

REBEKKA STEFFEN, HOLGER STEFFEN, AMBRUS KENYERES, MARTIN LIDBERG



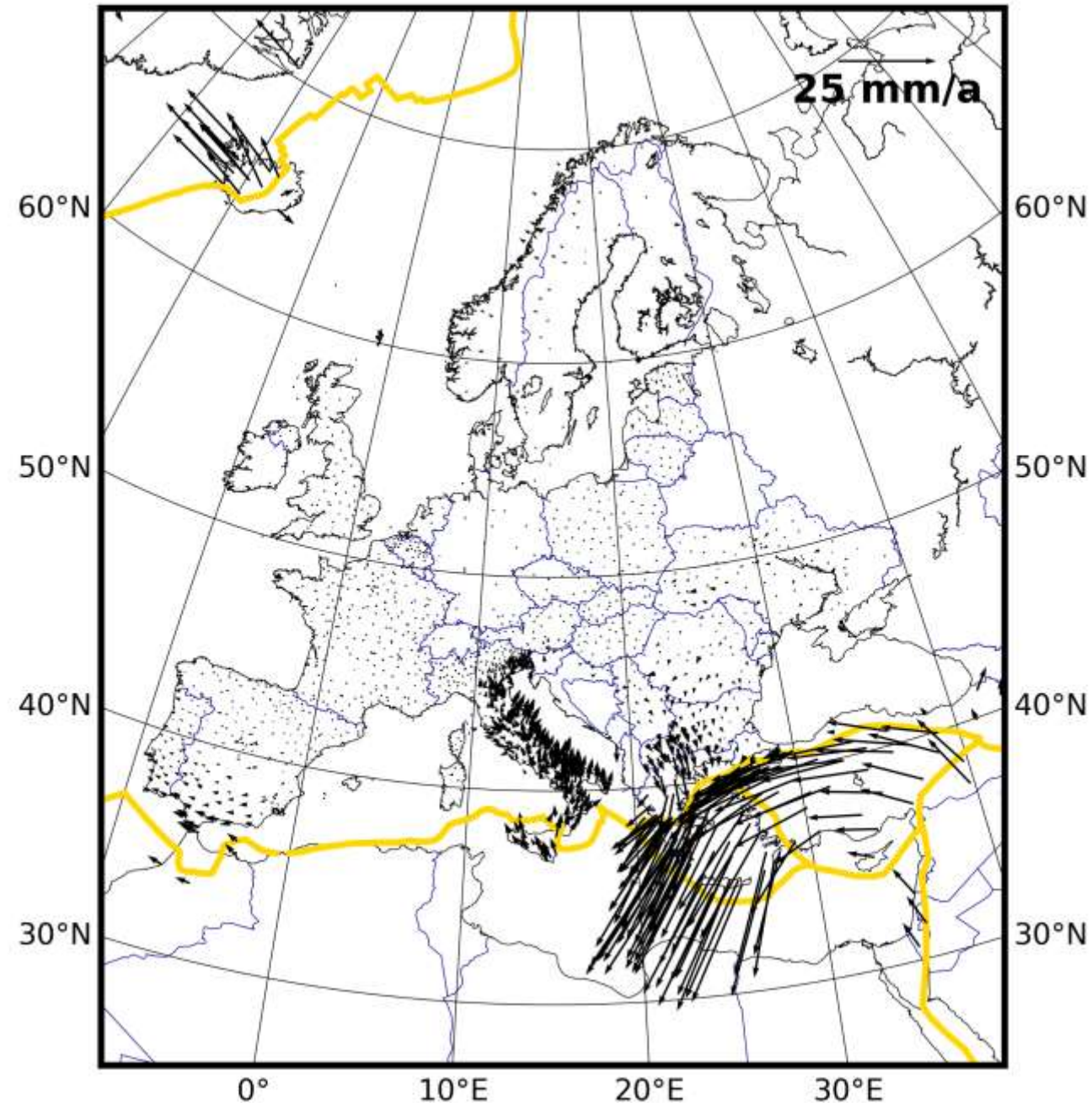
INTRODUCTION

- Dataset by Ambrus Kenyeres from January 2021 is used: "EPND_D2100_E2000NEU.VEL" (<https://epnd.sgo-penc.hu/>)
- Outliers have been removed

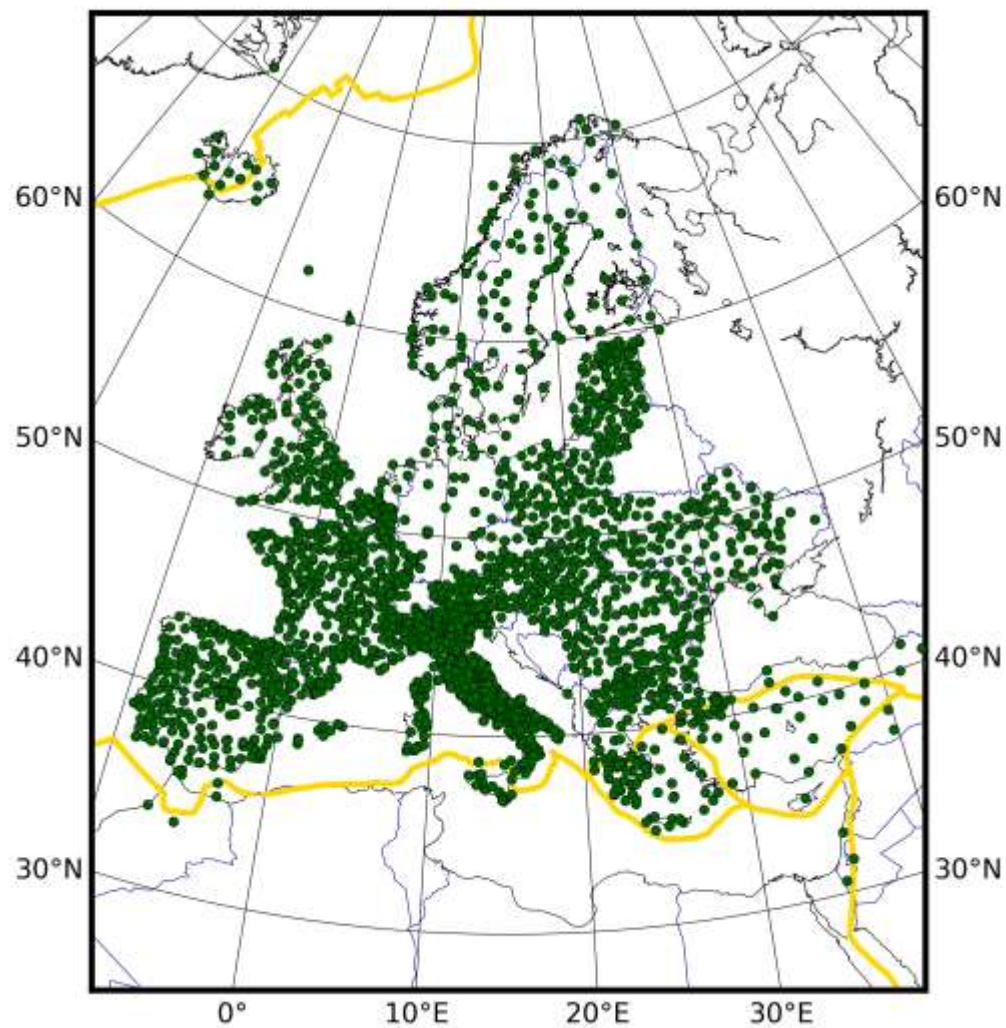


INTRODUCTION

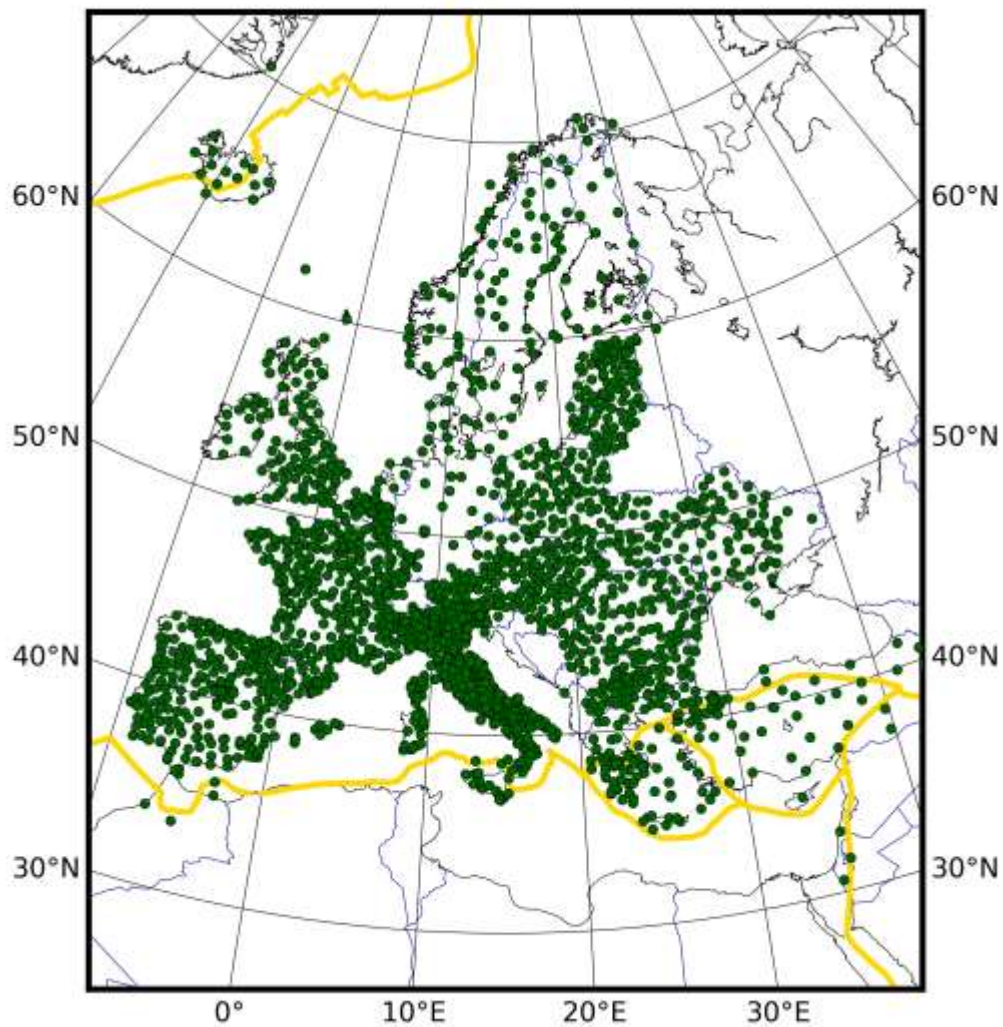
- Dataset by Ambrus Kenyeres from January 2021 is used: “EPND_D2100_E2000NEU.VEL” (<https://epnd.sgo-penc.hu/>)
- Outliers have been removed
- Observational uncertainties based on HECTOR are used



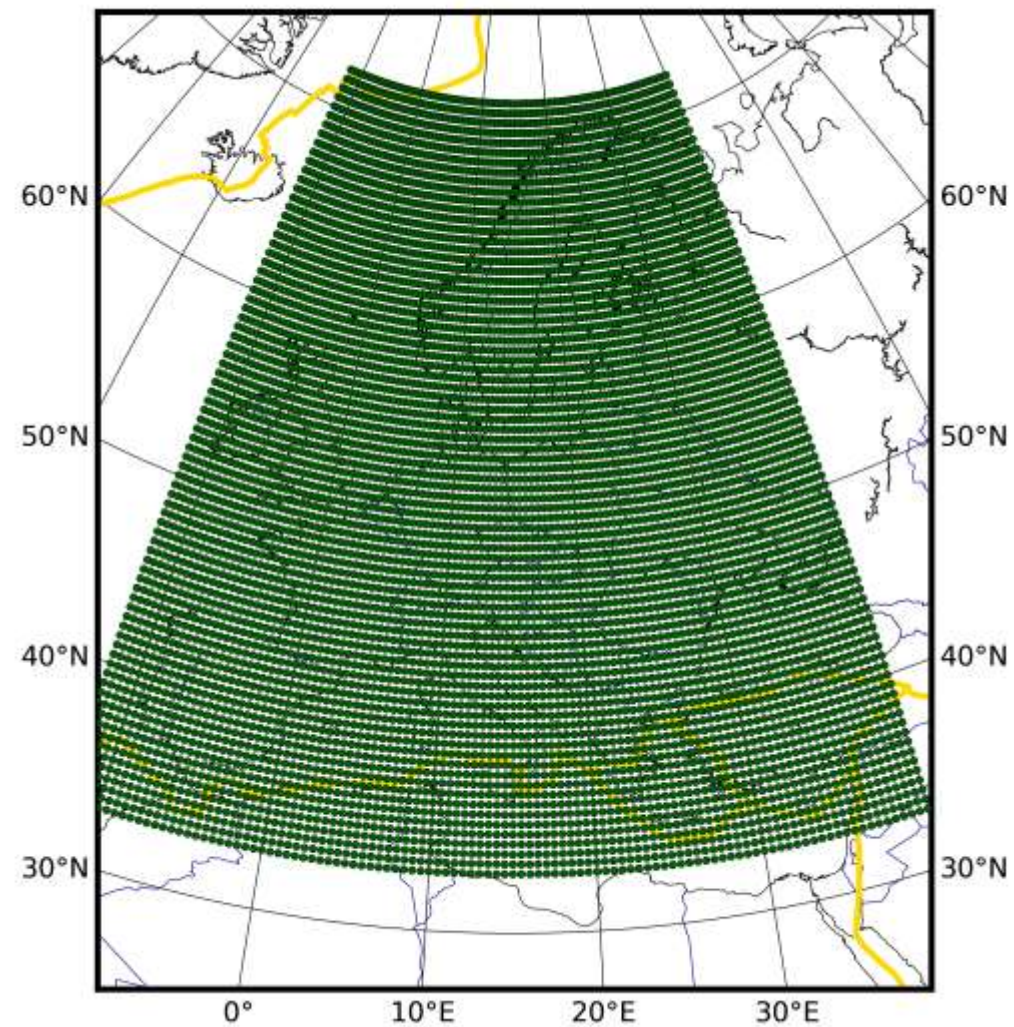
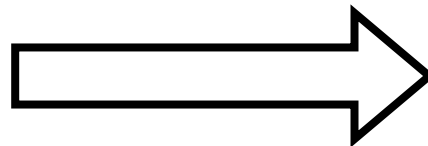
INTRODUCTION



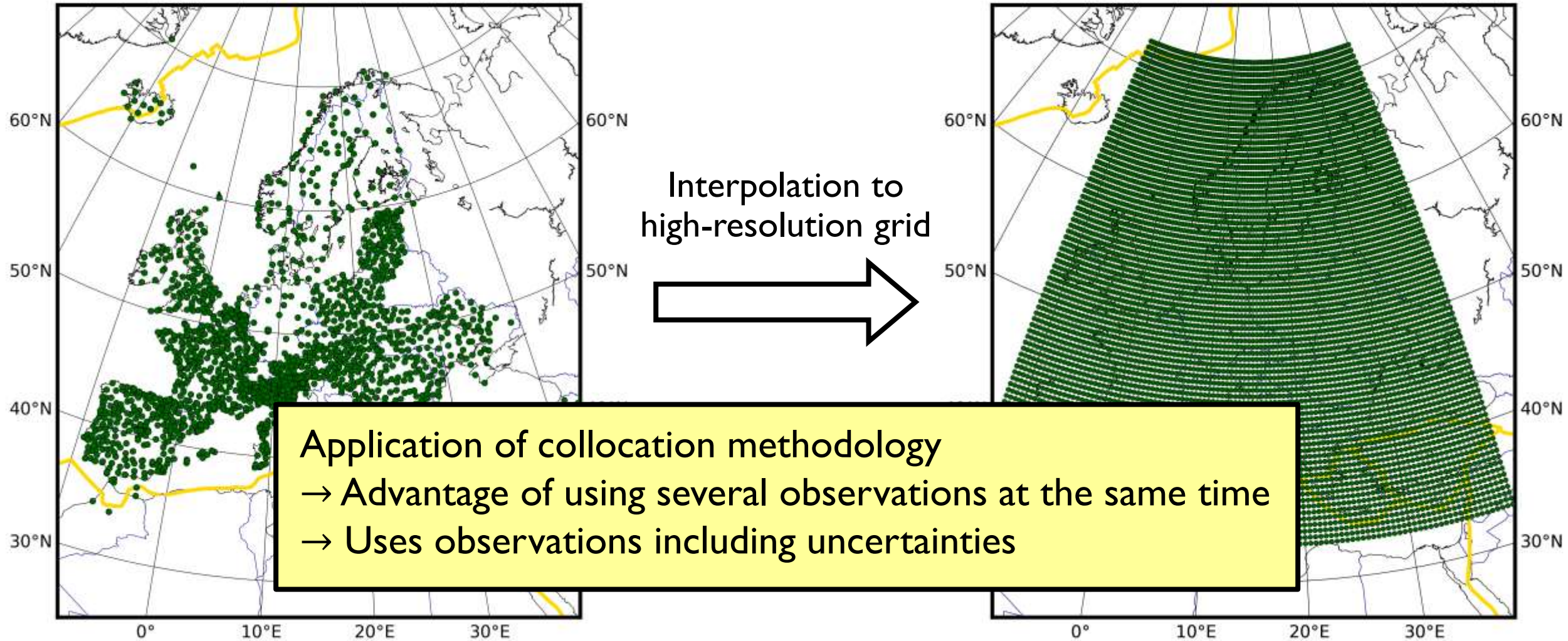
INTRODUCTION



Interpolation to
high-resolution grid



INTRODUCTION

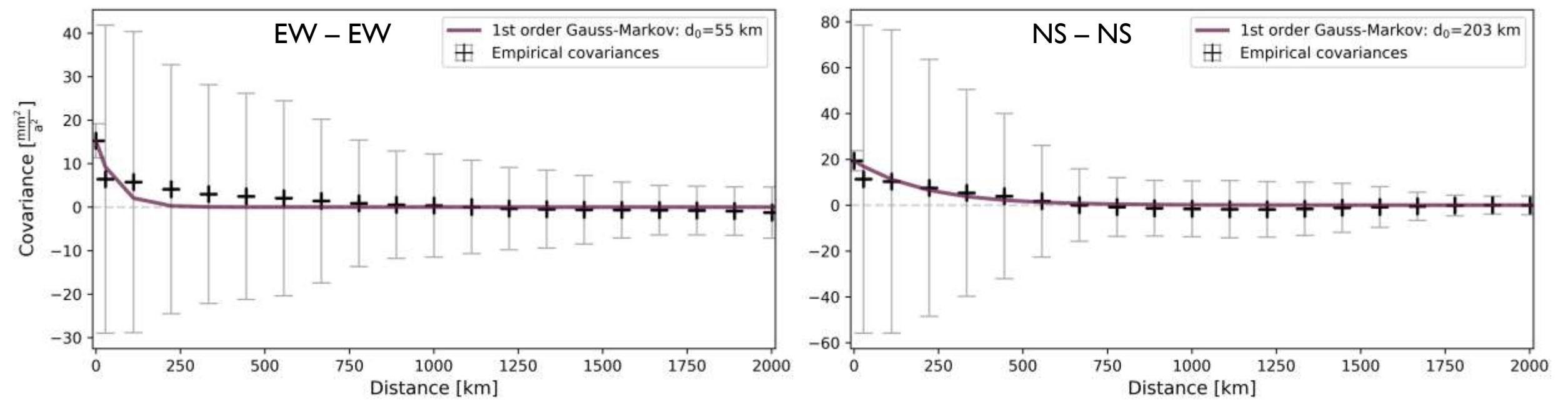


COLLOCATION (SHORT SUMMARY)

- Velocity data are filtered and interpolated (prediction) using least-squares collocation (LSC, based on Moritz, 1980)
- Collocation is done for the east-west and north-south component at the same time as well as considering the correlation between the components (following Legrand, 2007, and Steffen et al., to be submitted): HV-LSC
- Plate-boundary constraints are used as well (HV-LSC-ex)
- Interpolation is done on a $0.1^\circ \times 0.1^\circ$ grid
- Collocation depends on the distance between the points and the choice of the covariance function $\rightarrow C_0$ (signal covariance) and d_0 (correlation length) need to be determined

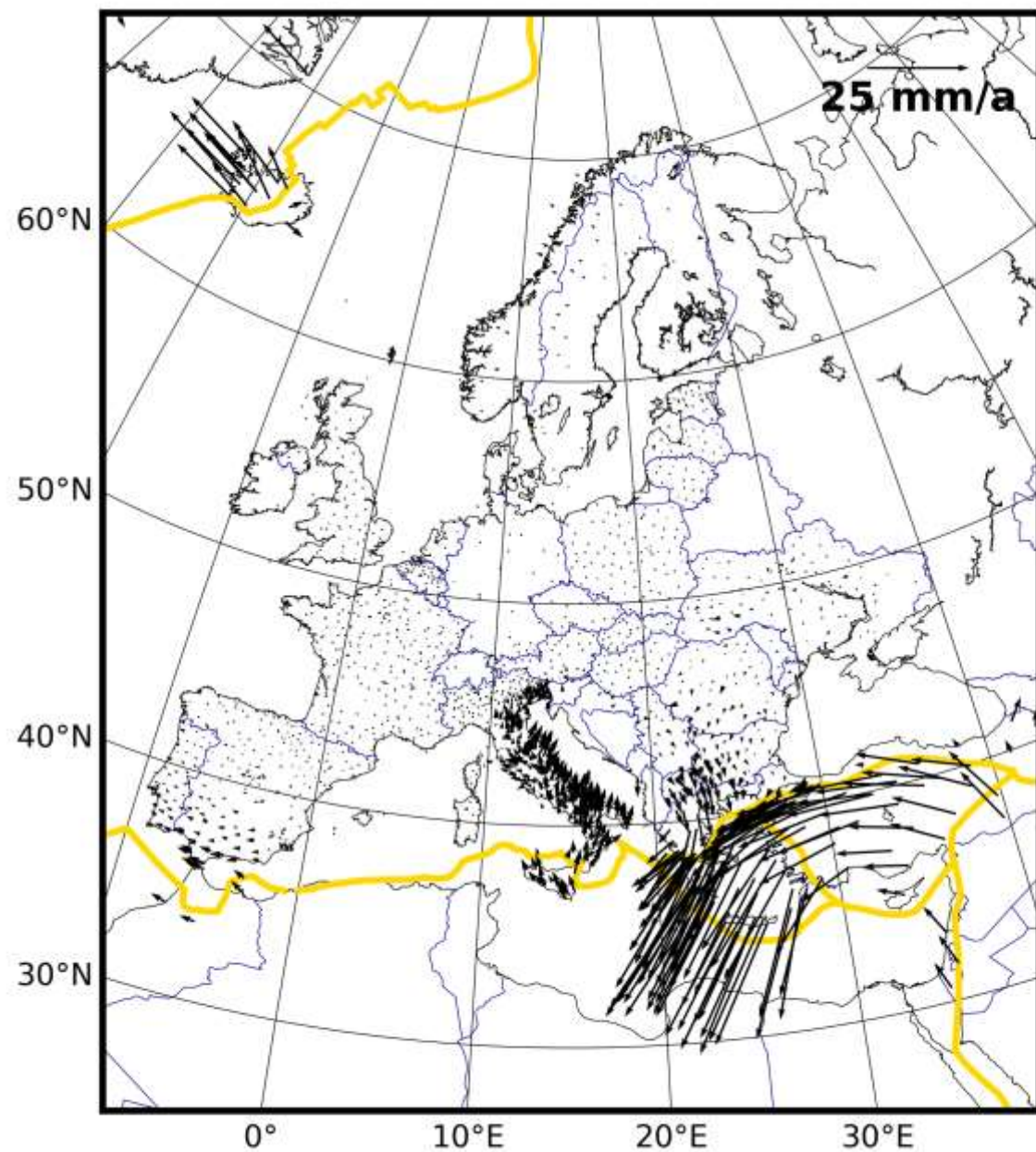
COVARIANCE FUNCTION

Gauss-Markov 1st order used: $K(d) = C_0 \cdot e^{-d/d_0}$

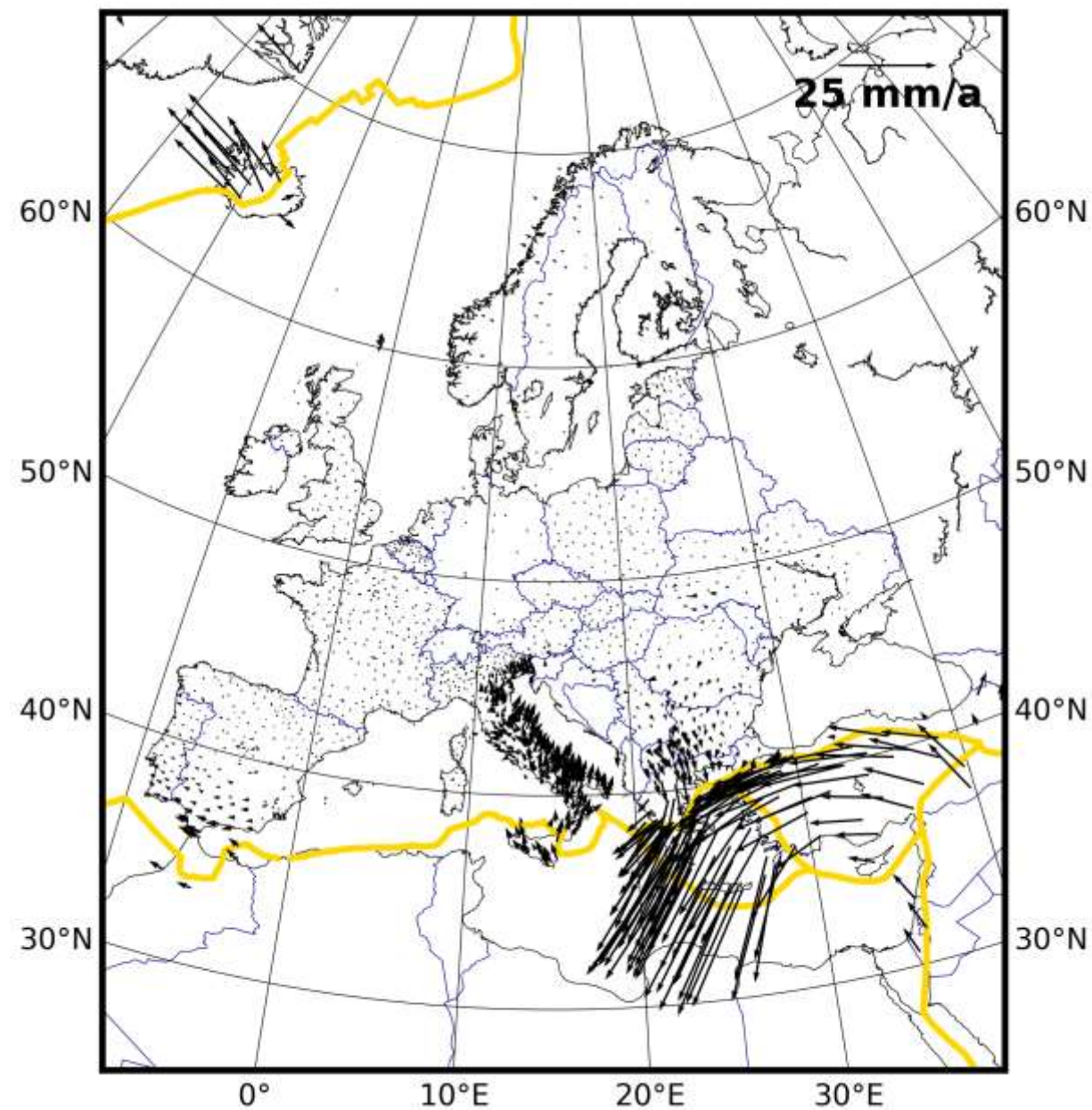


	C_0 [mm²/a²]	d_0 [km]
EW – EW	15.234	55 ± 19
NS – NS	19.360	203 ± 20
Final	17.297	129

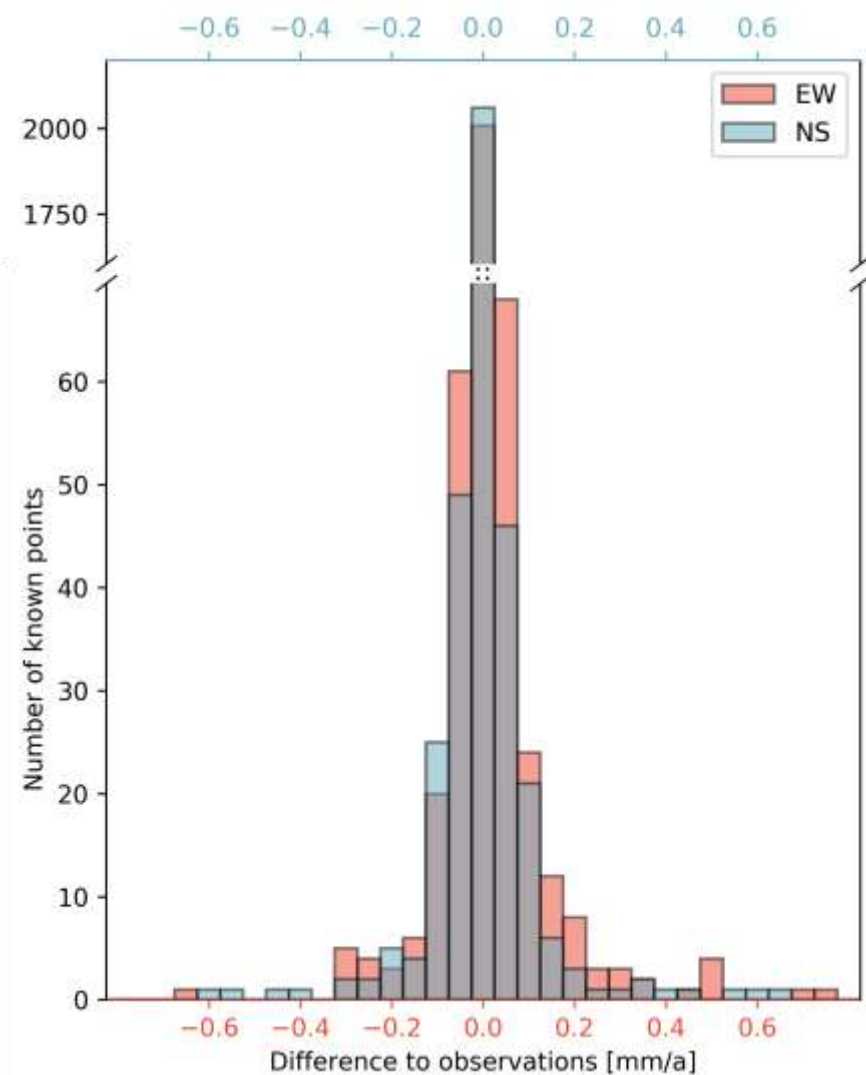
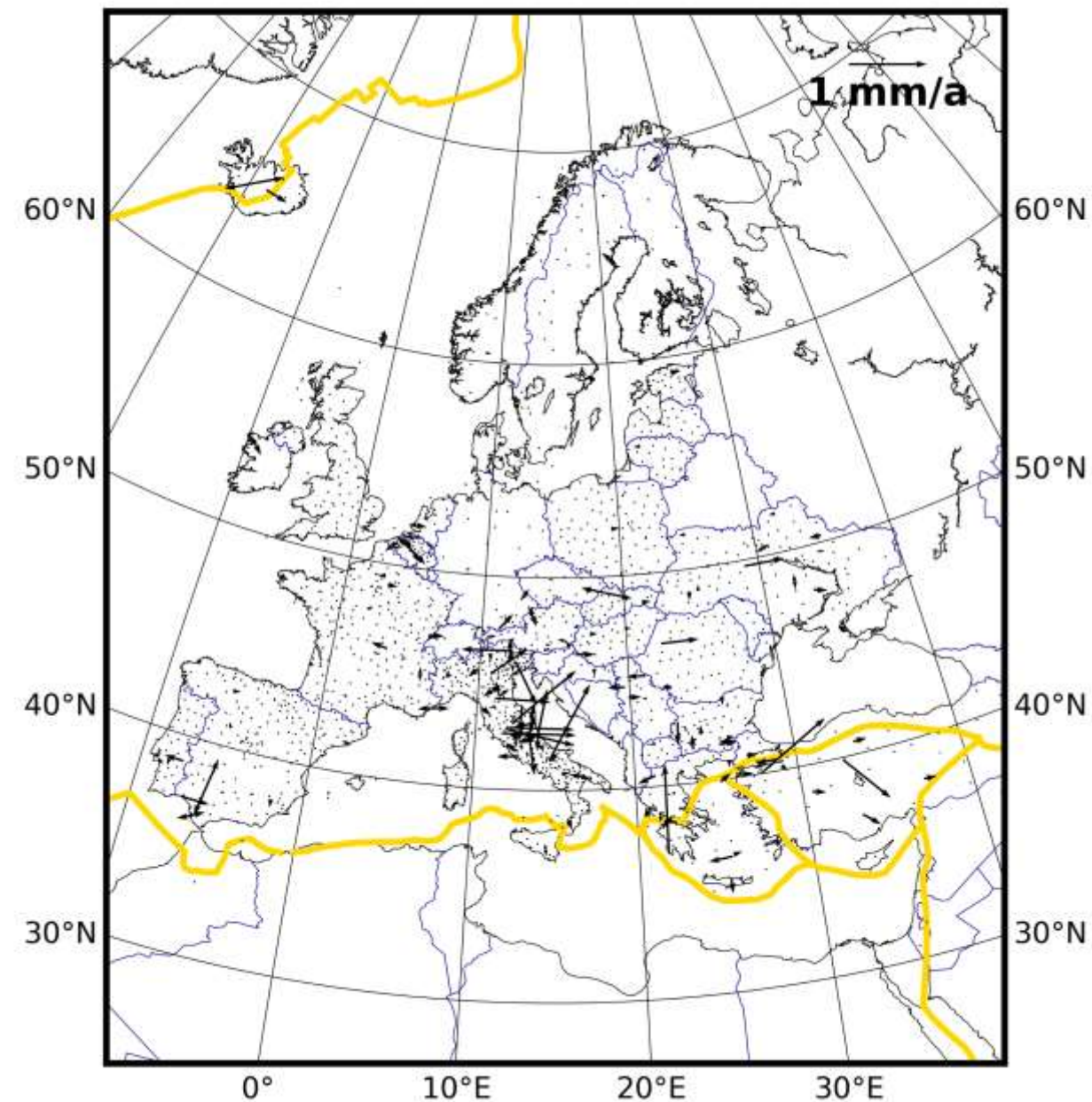
Original velocity field



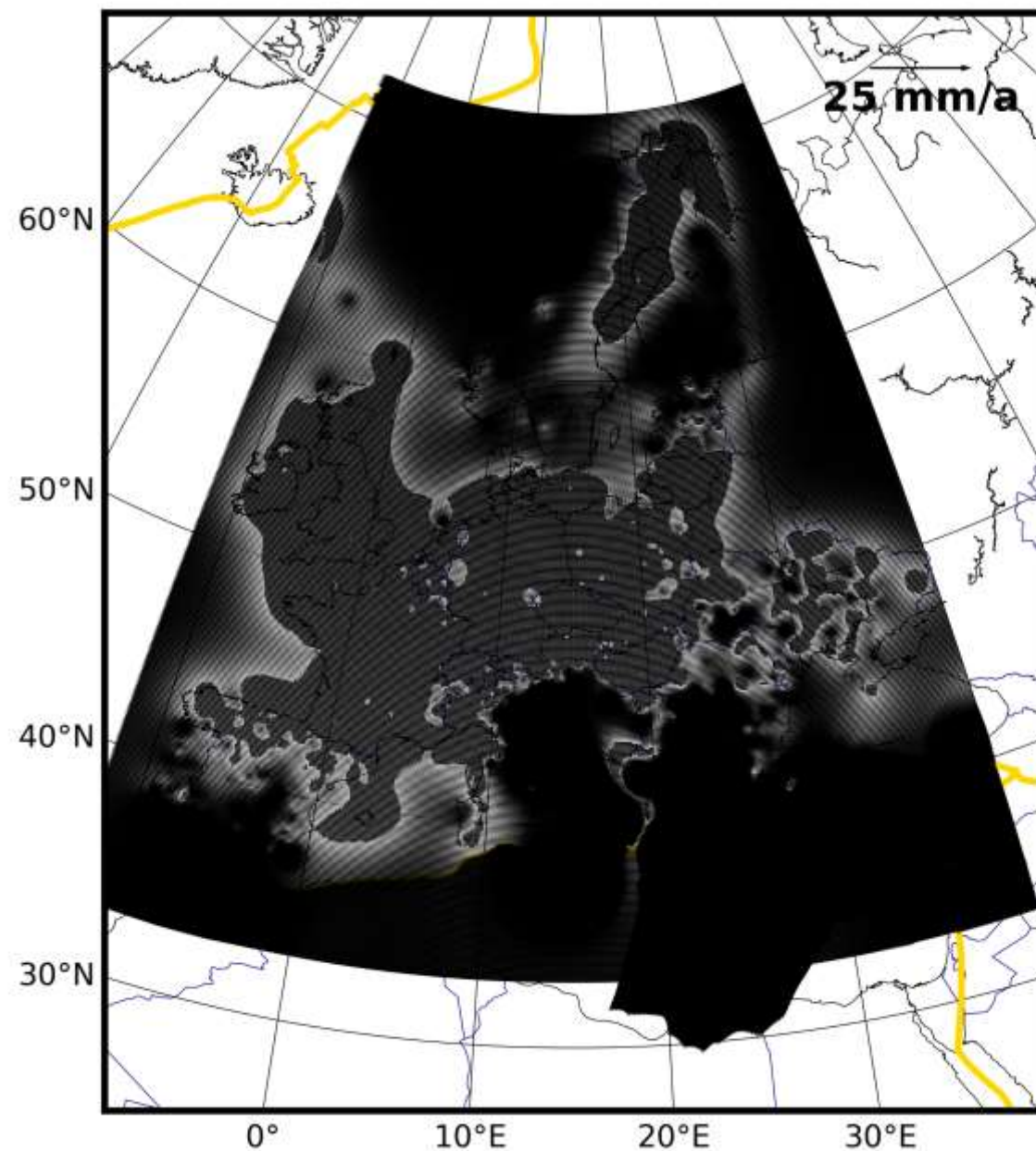
Filtered velocity field from HV-LSC-ex



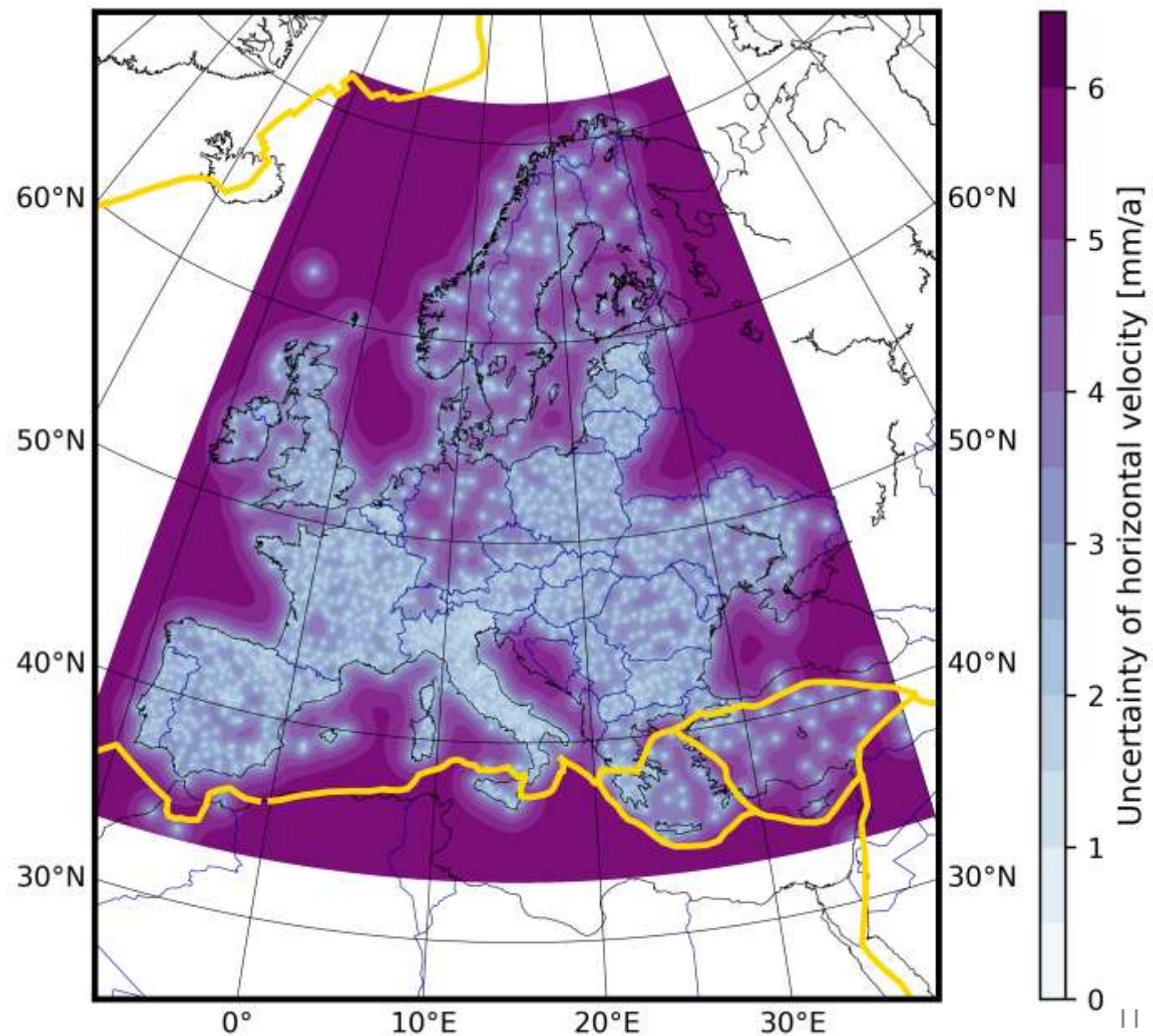
Difference



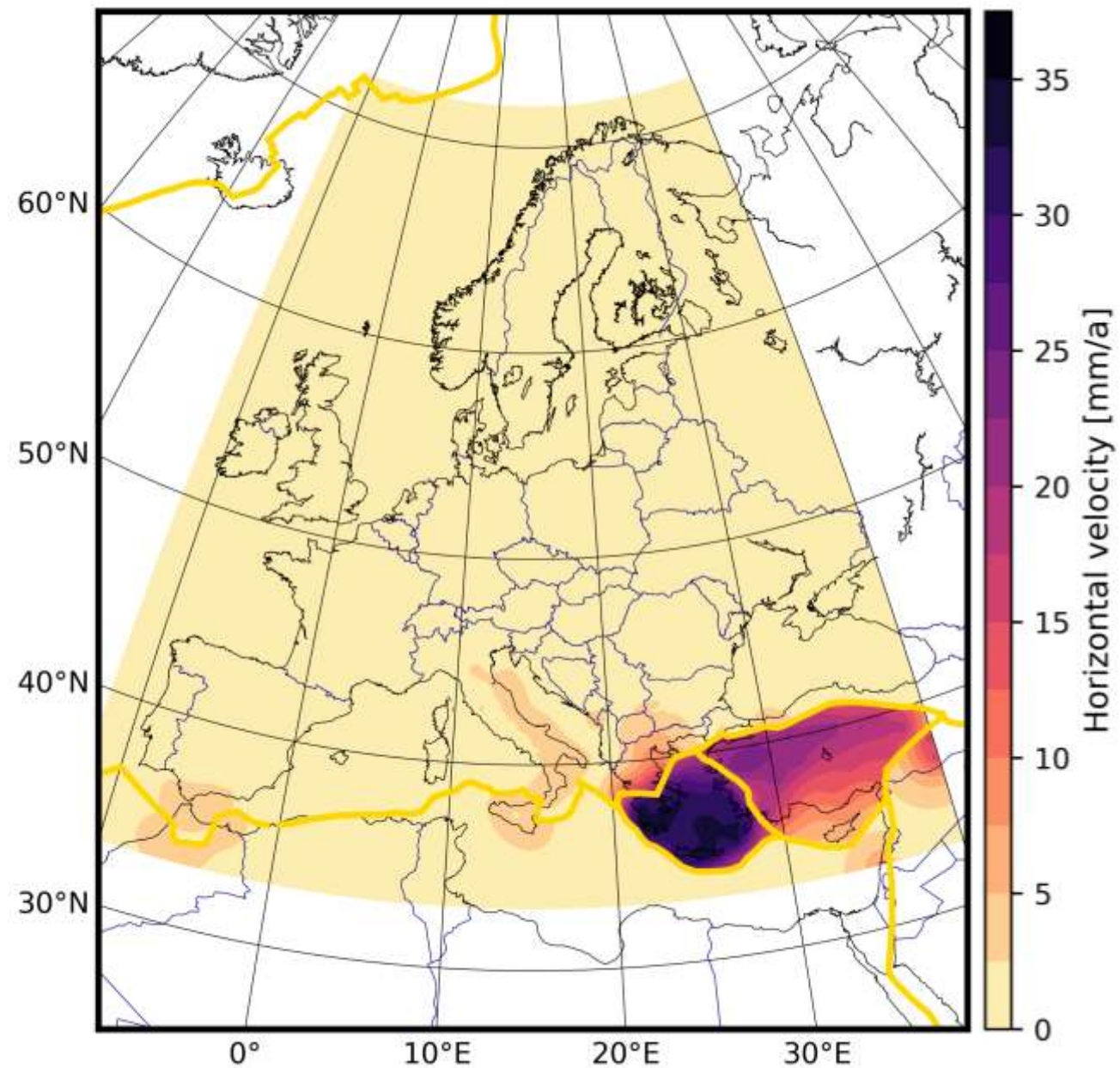
Interpolated velocity field using HV-LSC-ex



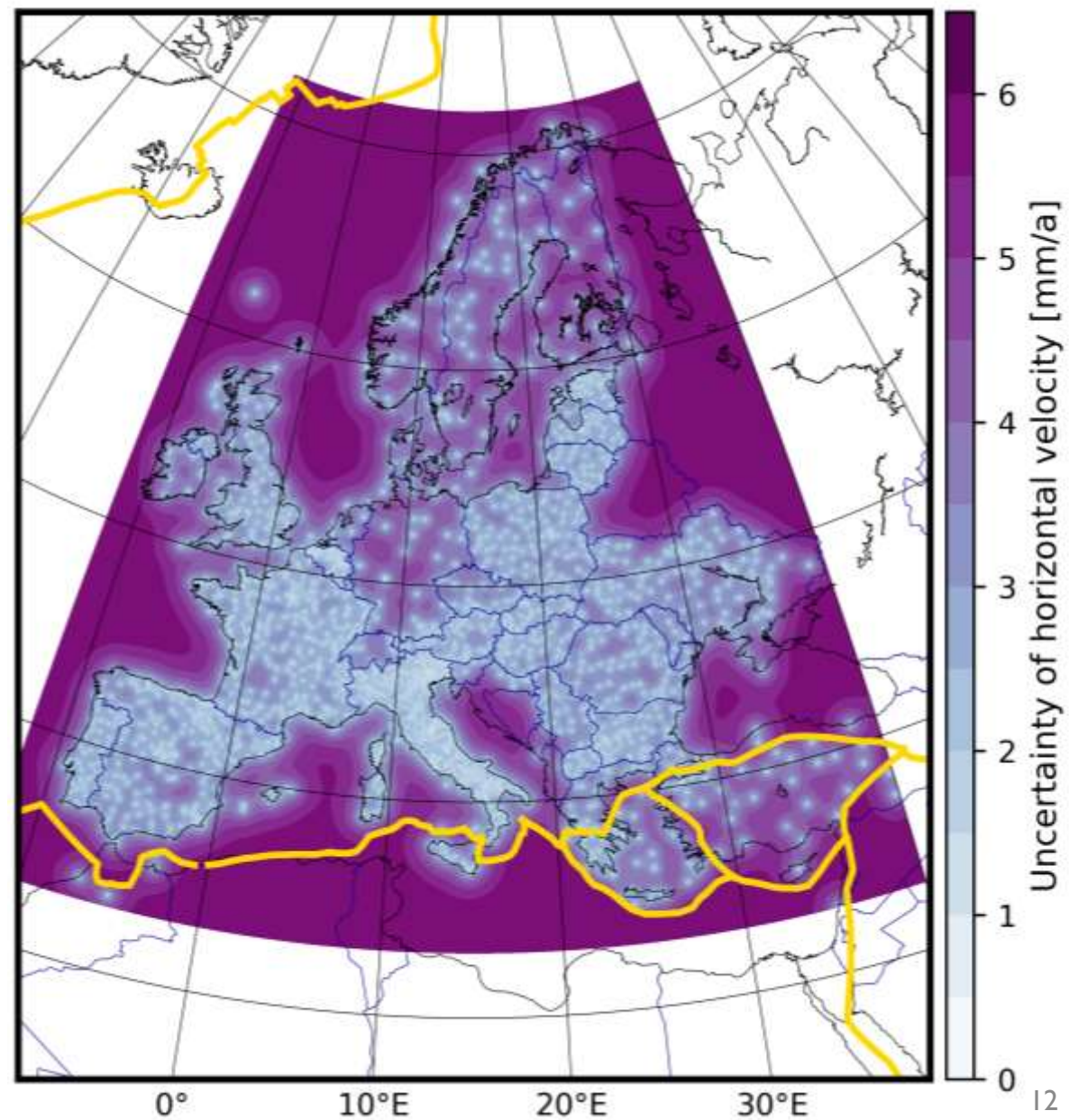
Uncertainty using HV-LSC-ex



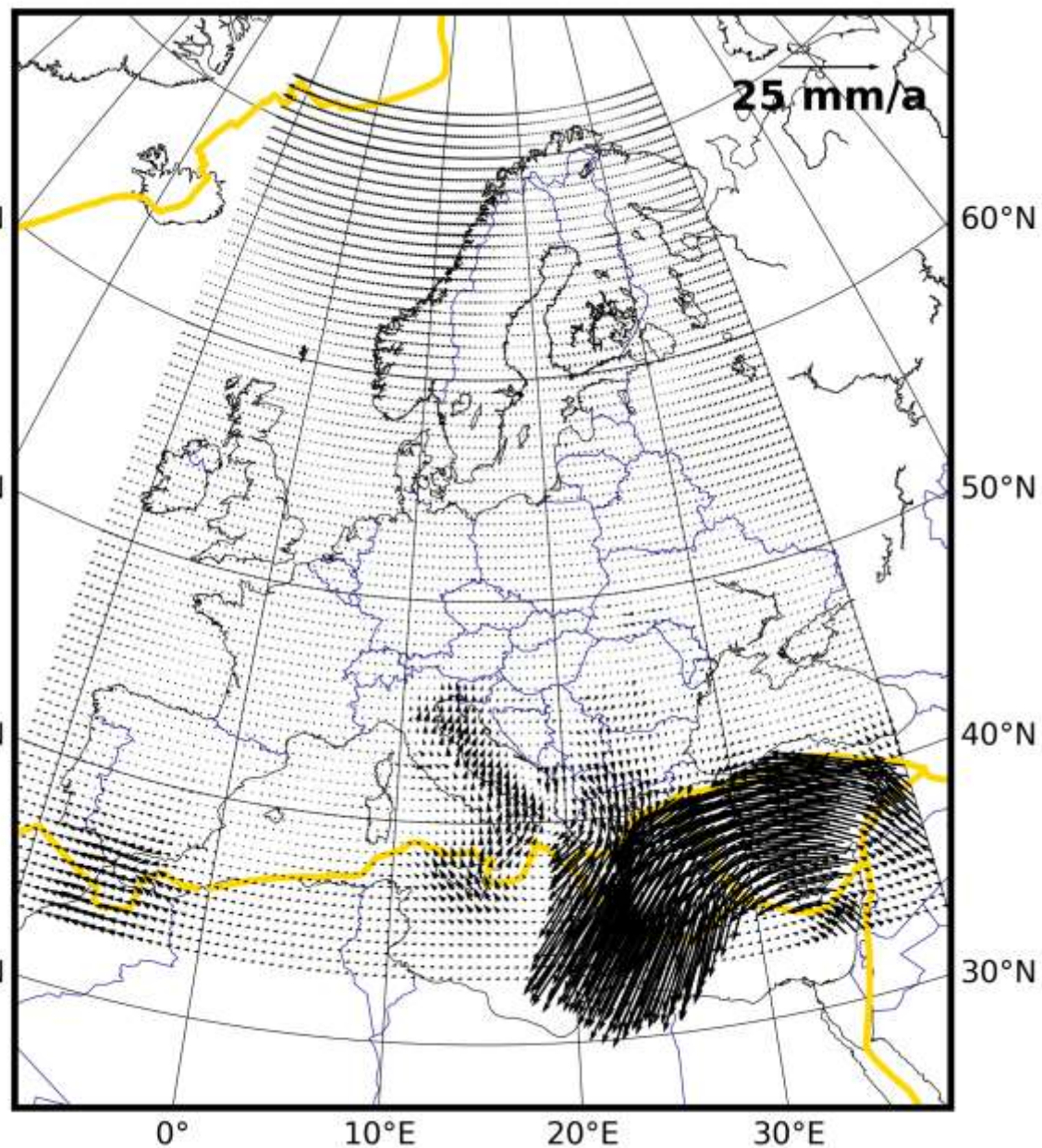
Interpolated velocity field using HV-LSC-ex



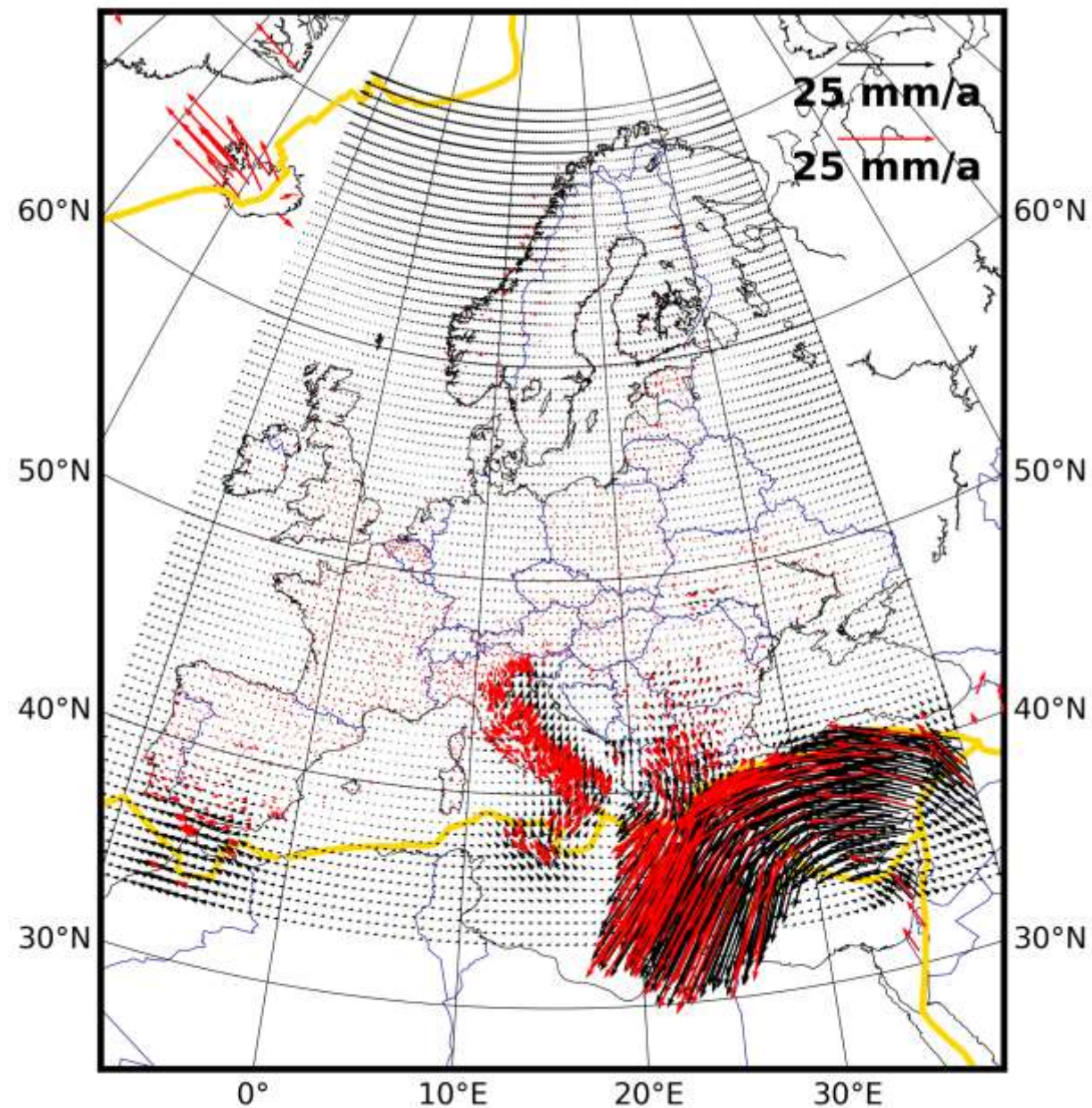
Uncertainty using HV-LSC-ex



Lower resolution of $0.5^\circ \times 0.5^\circ$



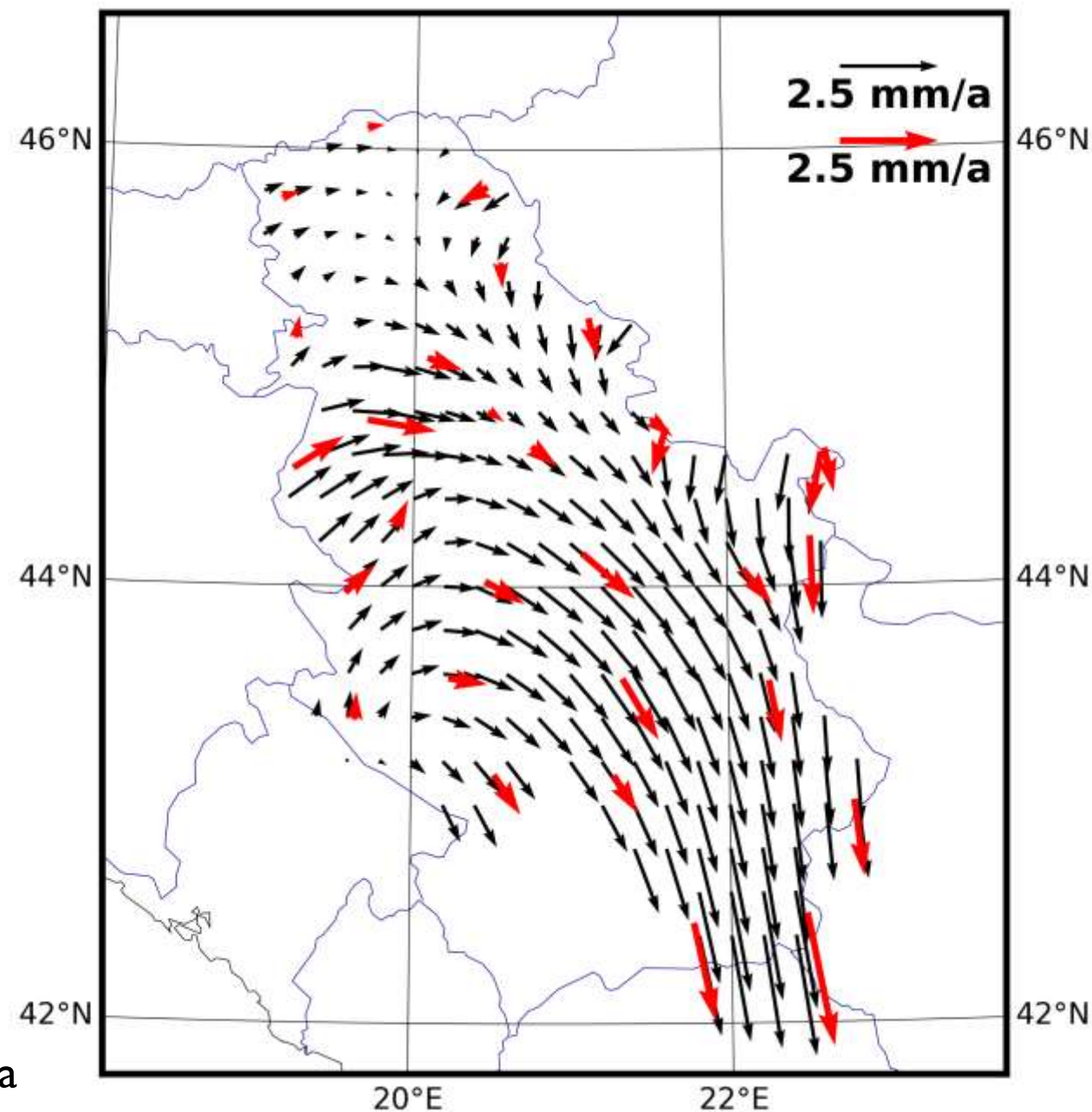
Comparison to observations (in red)



A FEW EXAMPLES - SERBIA

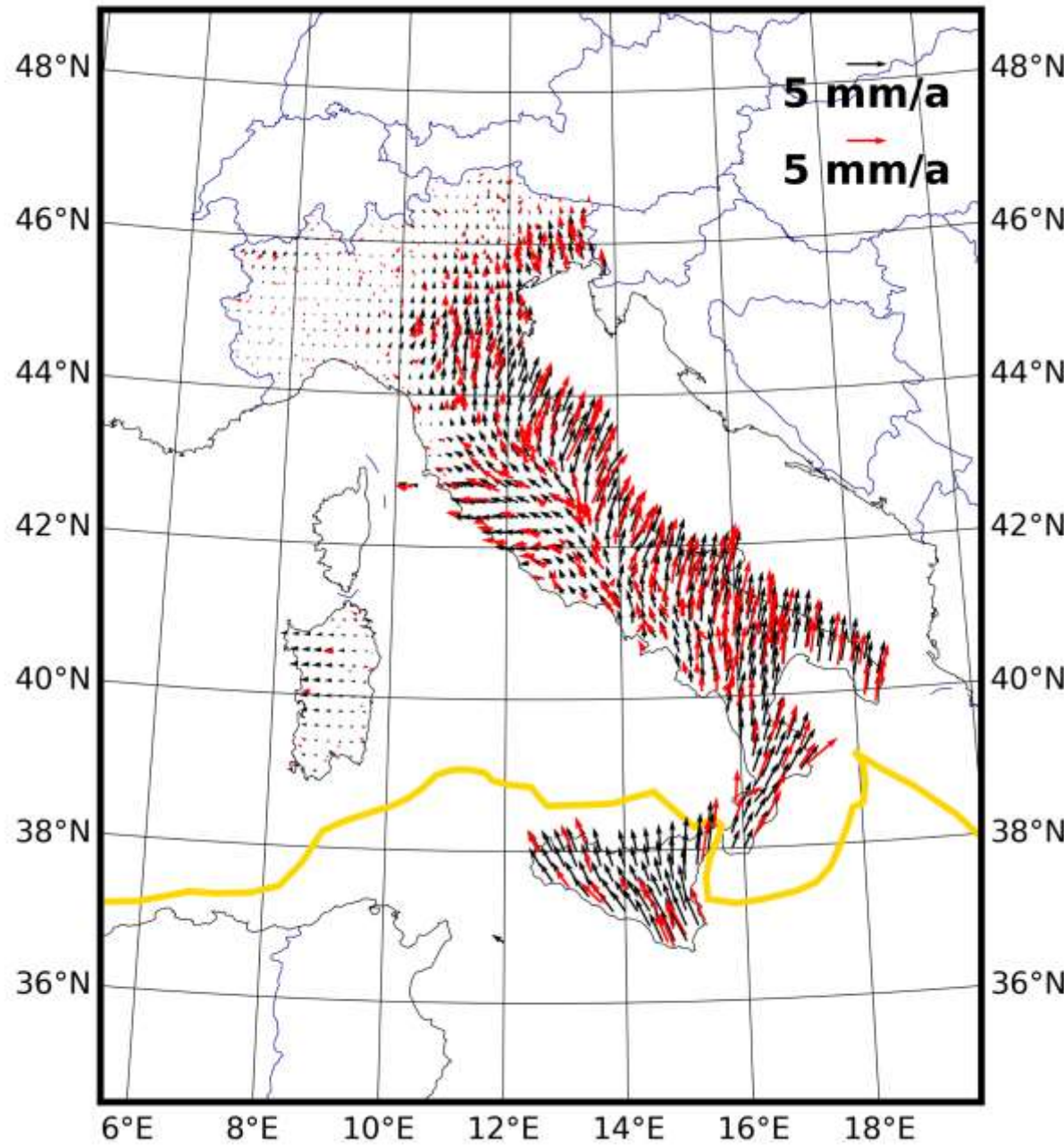
Red – original data

Black – collocated data



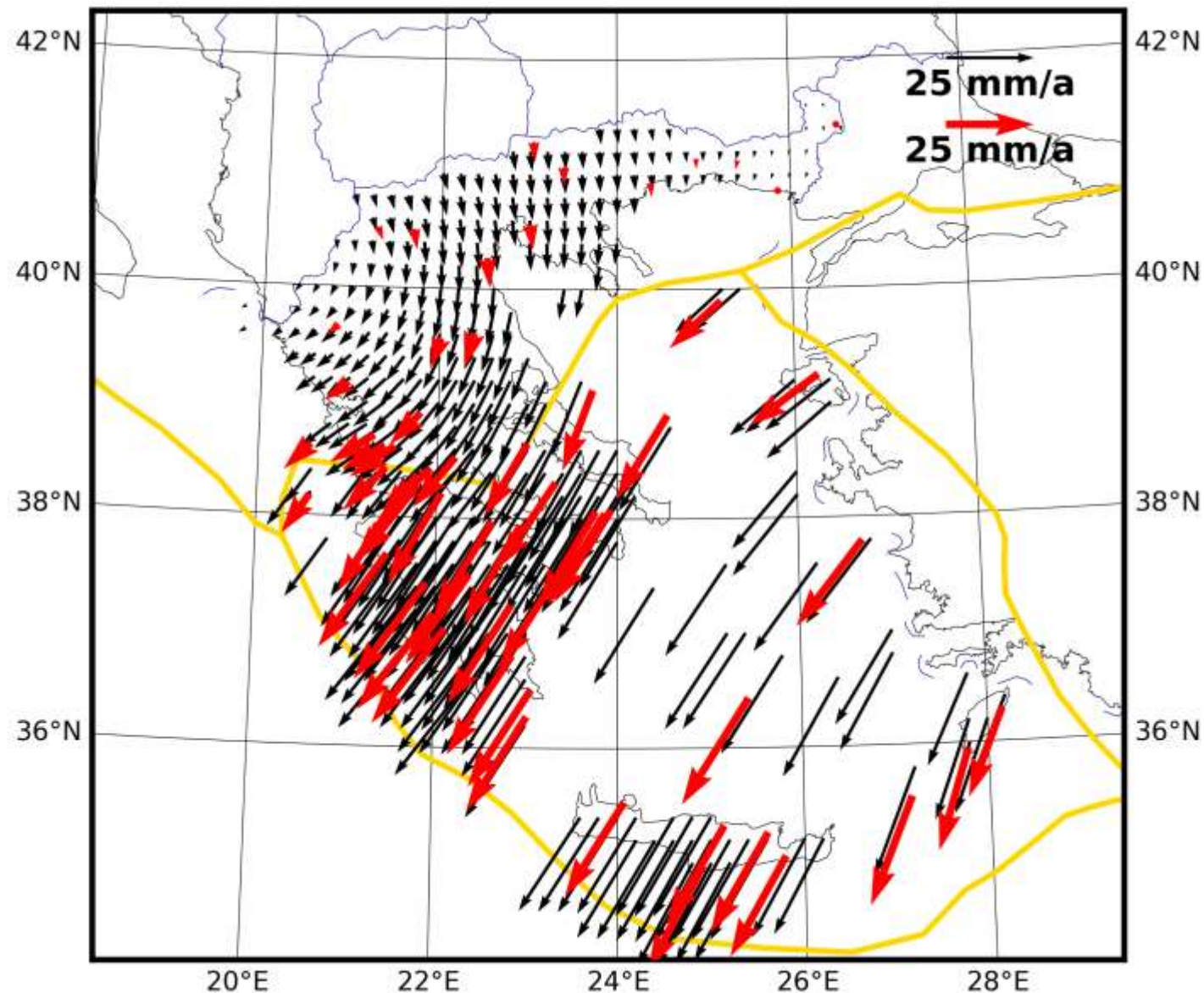
A FEW EXAMPLES - ITALY

Red – original data
Black – collocated data

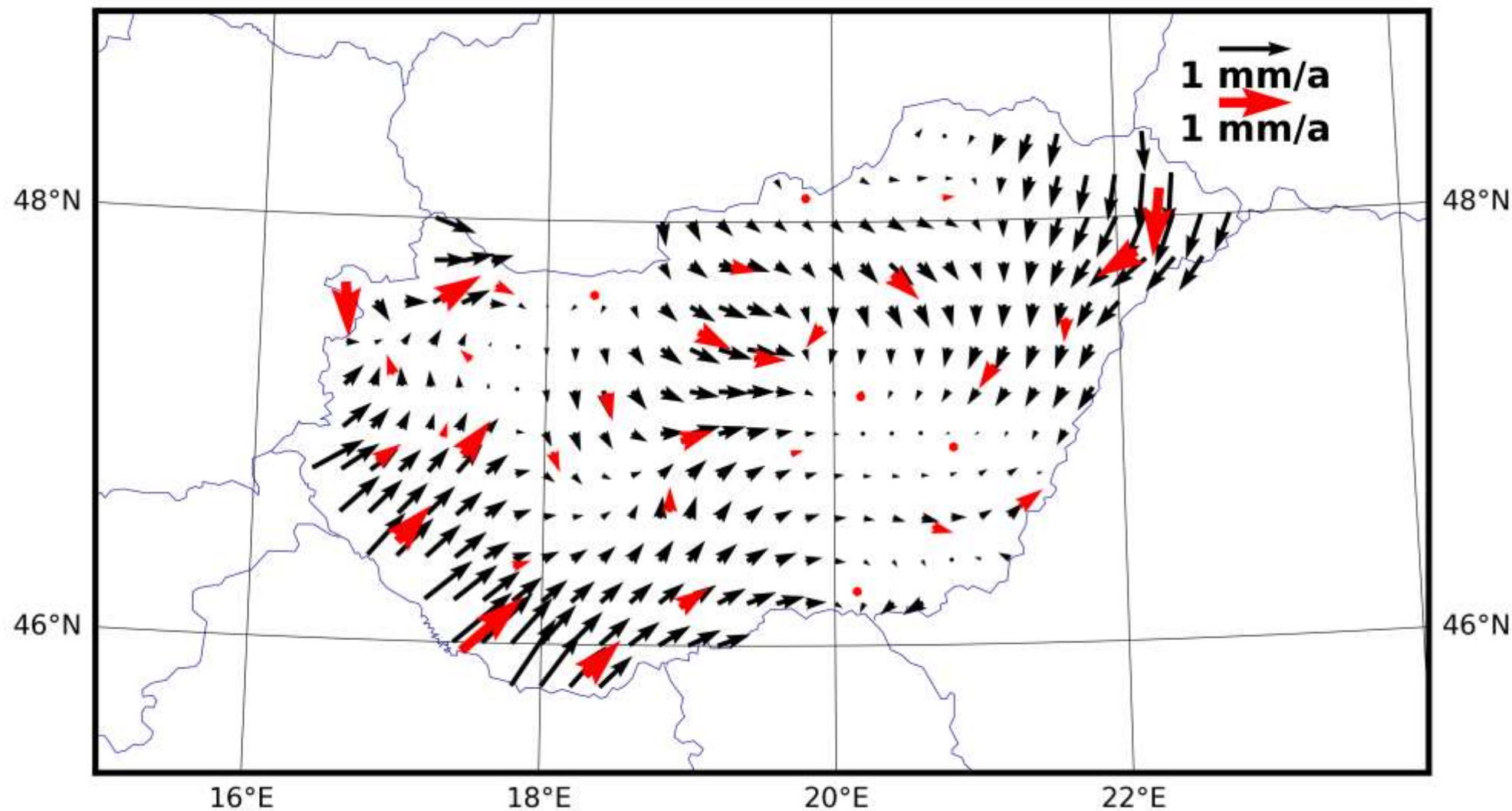


A FEW EXAMPLES - GREECE

Red – original data
Black – collocated data



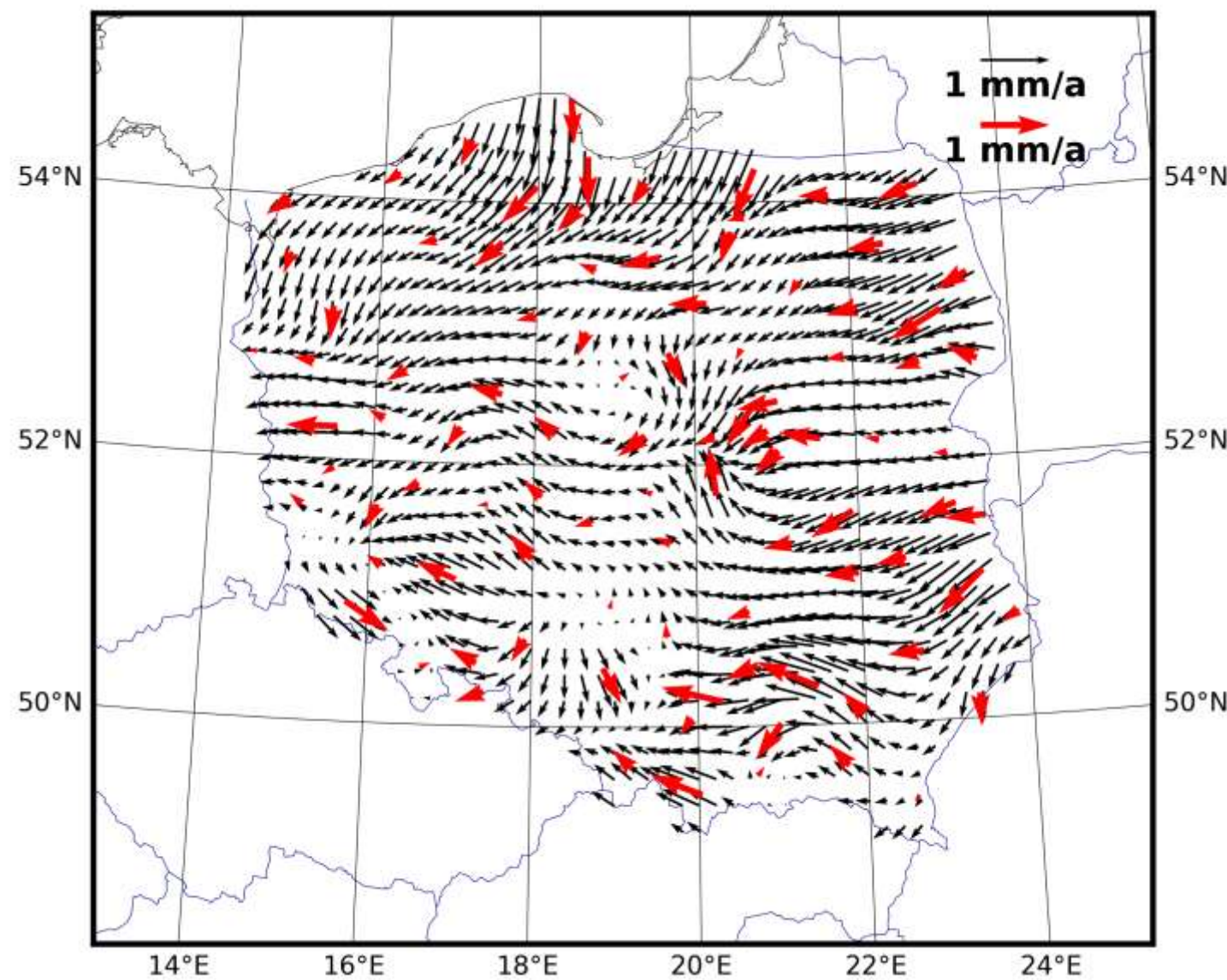
A FEW EXAMPLES - HUNGARY



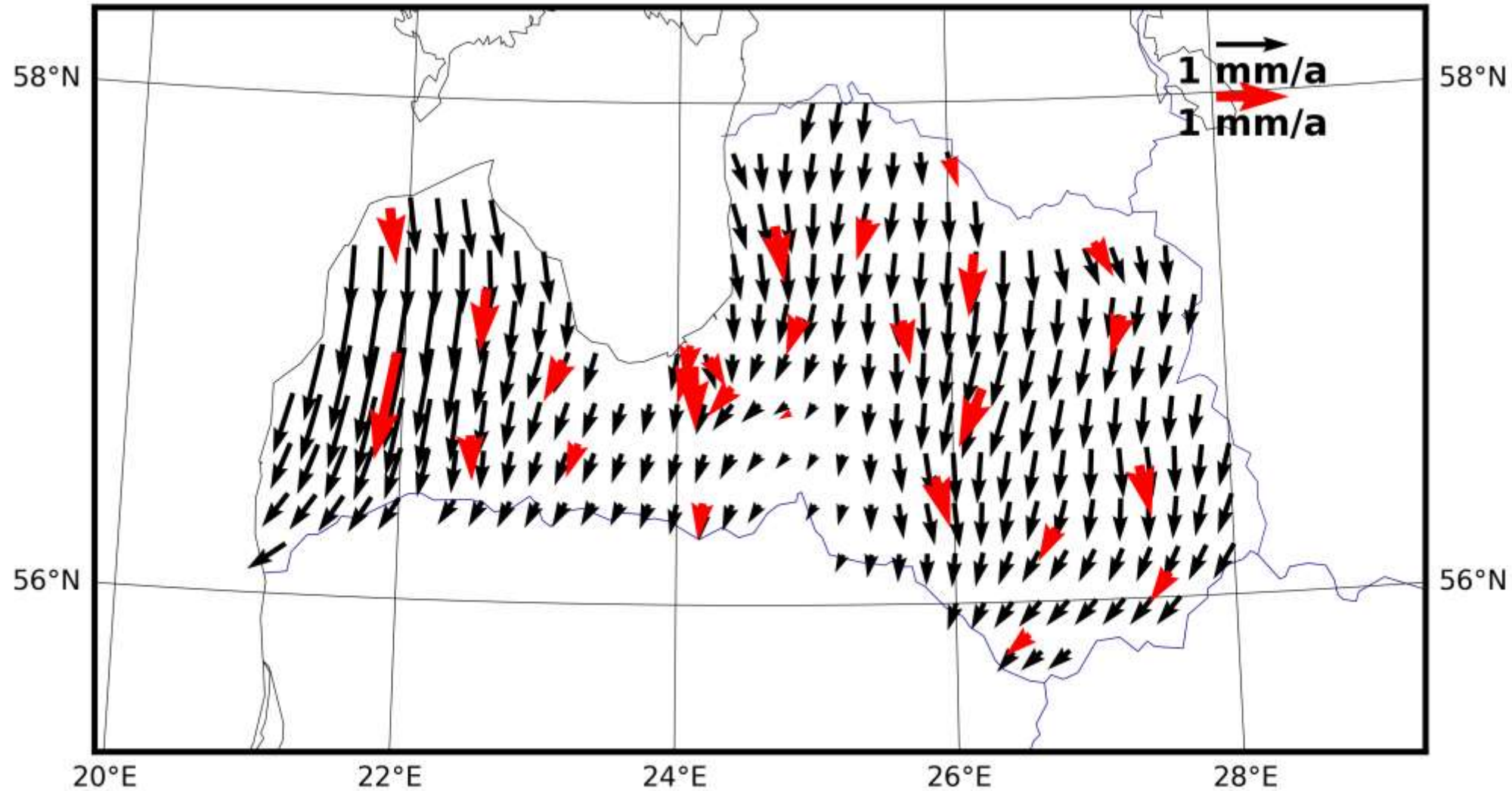
Red – original data

Black – collocated data

A FEW EXAMPLES - POLAND



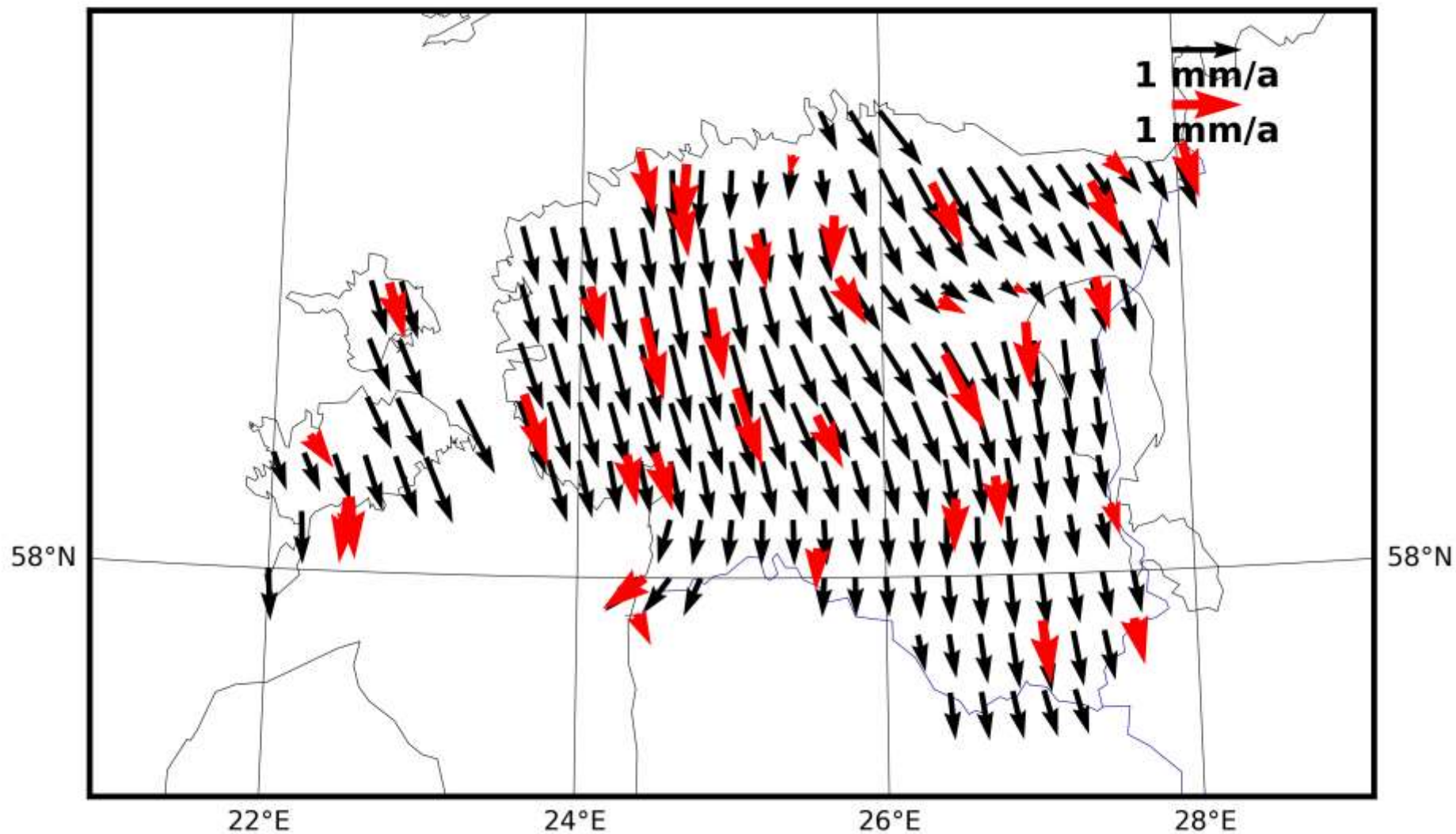
A FEW EXAMPLES - LATVIA



Red – original data

Black – collocated data

A FEW EXAMPLES - ESTONIA



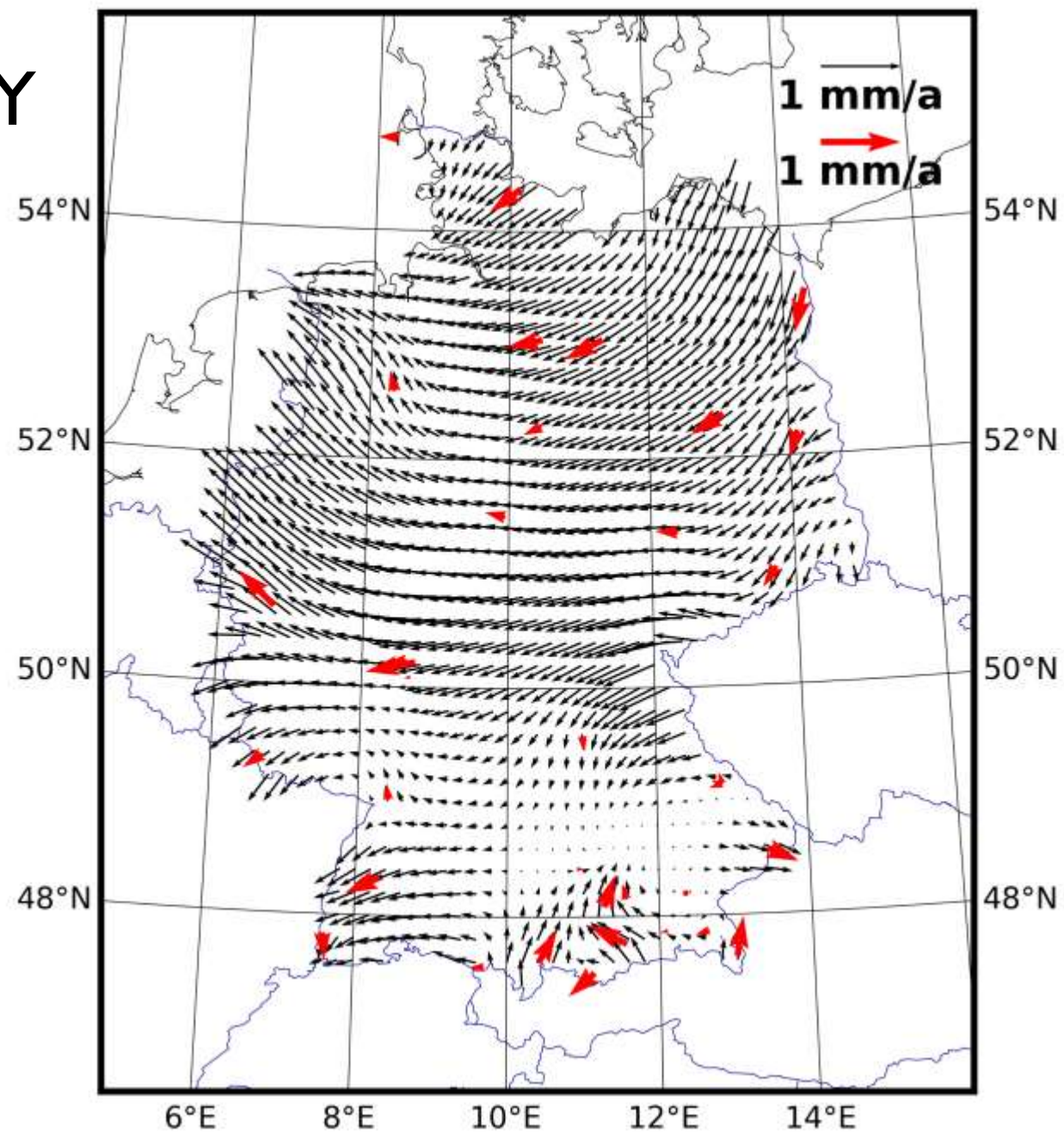
Red – original data

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A FEW EXAMPLES - GERMANY

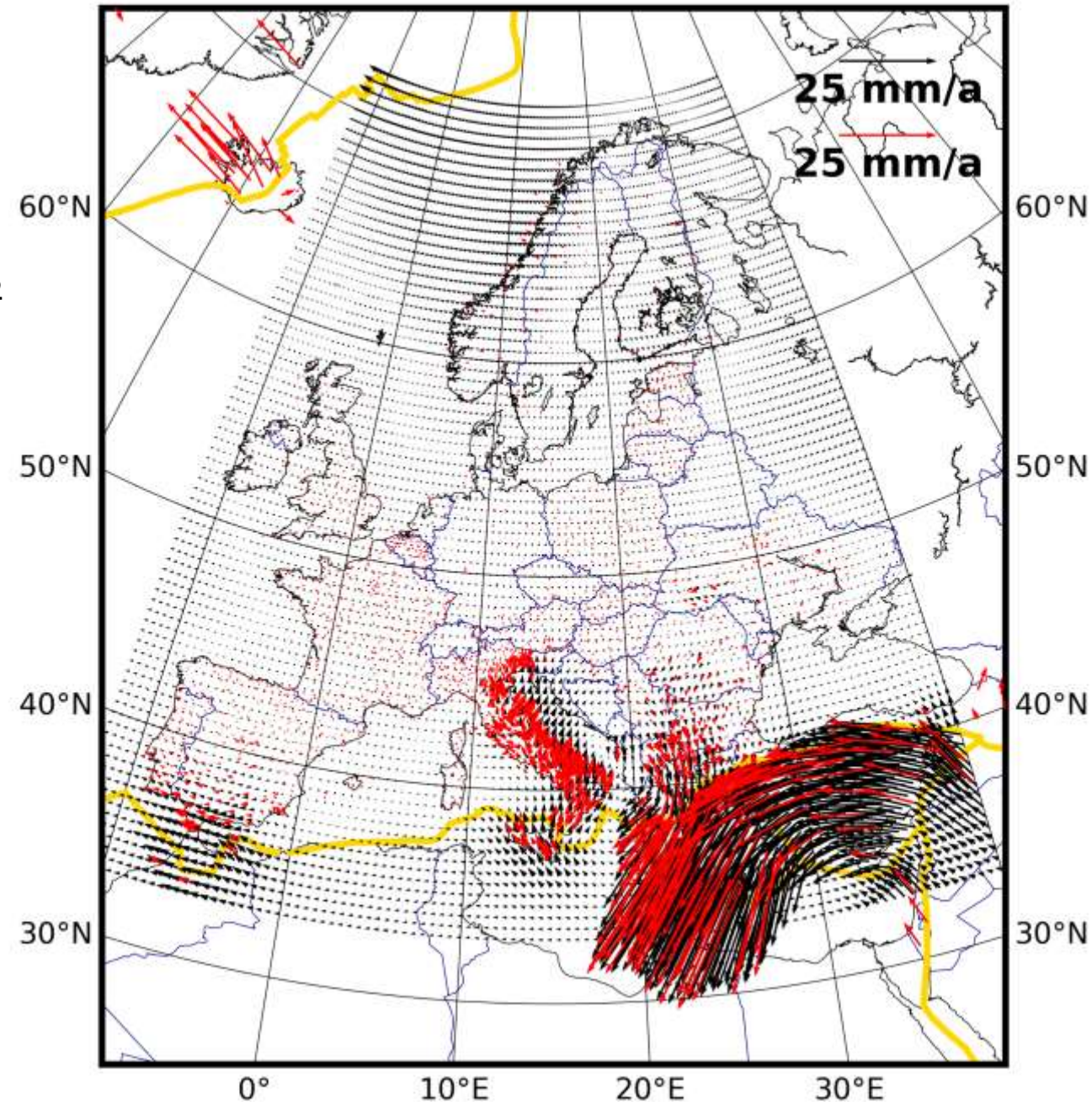
Red – original data

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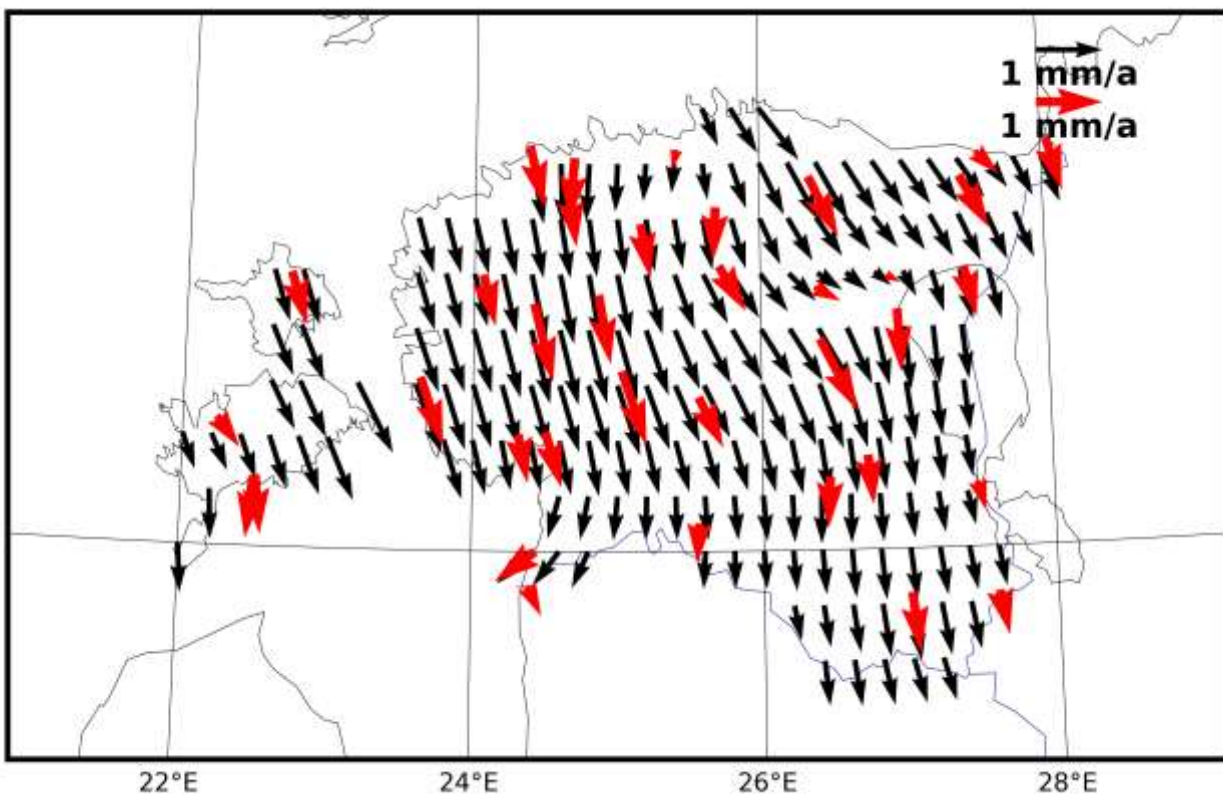
OUTLOOK

- Problem of non-stationarity exists in collocation method
 - development of a new approach: HV-LSC-ex²
 - moving variance
 - resulting model is smoother

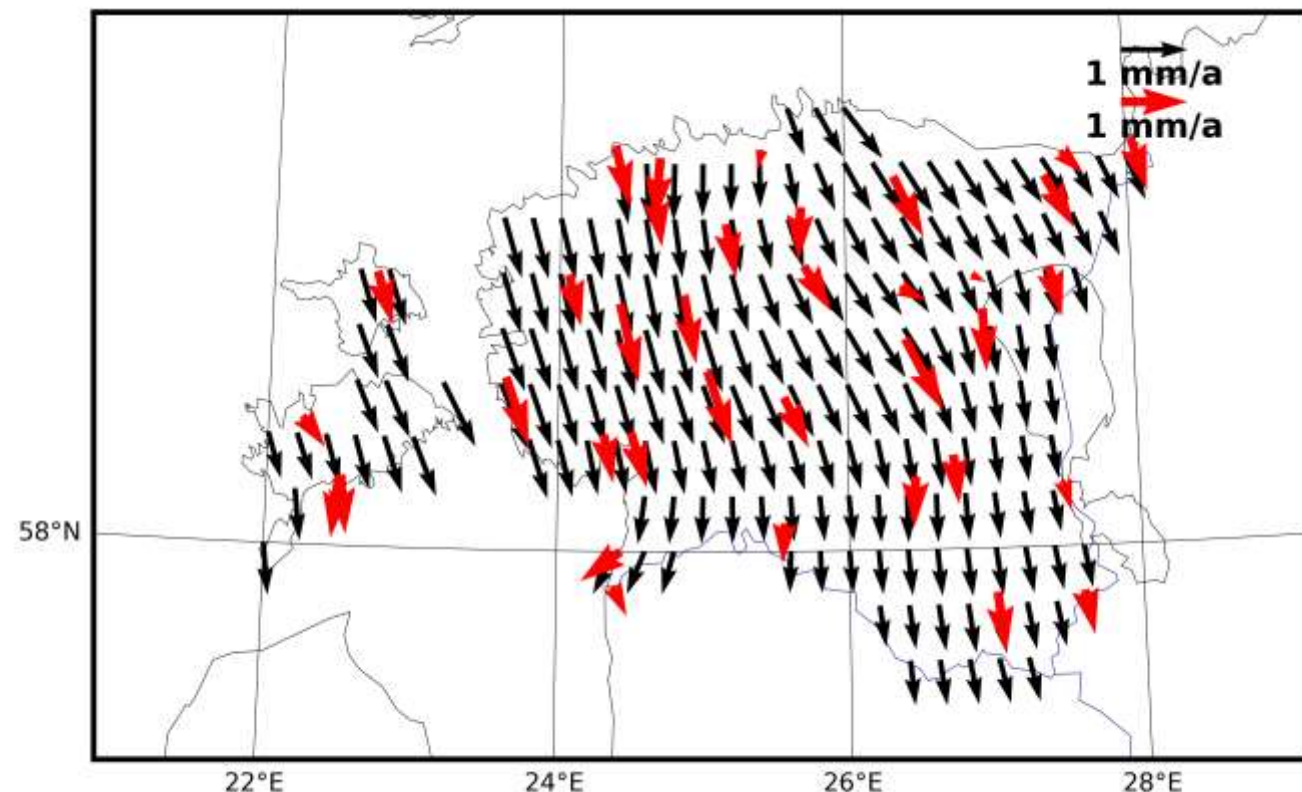


A FEW EXAMPLES - ESTONIA

Without moving variance (HV-LSC-ex)



With moving variance (HV-LSC-ex²)

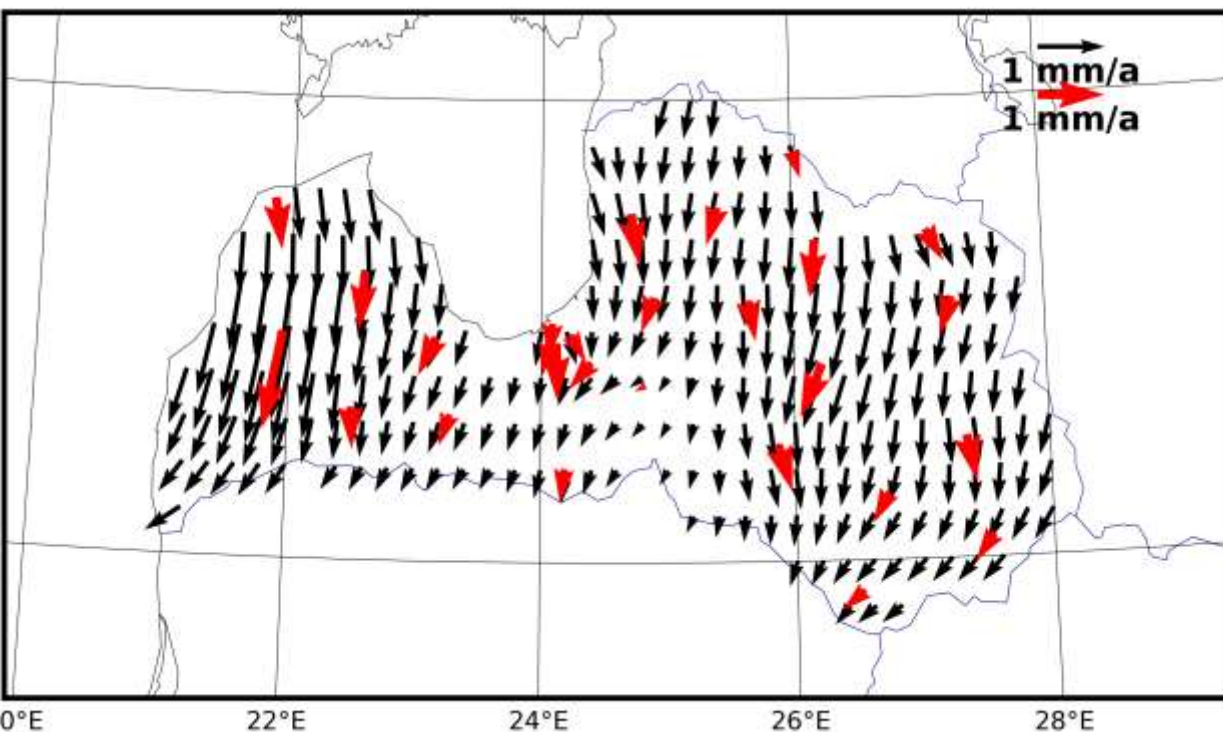


Red – original data

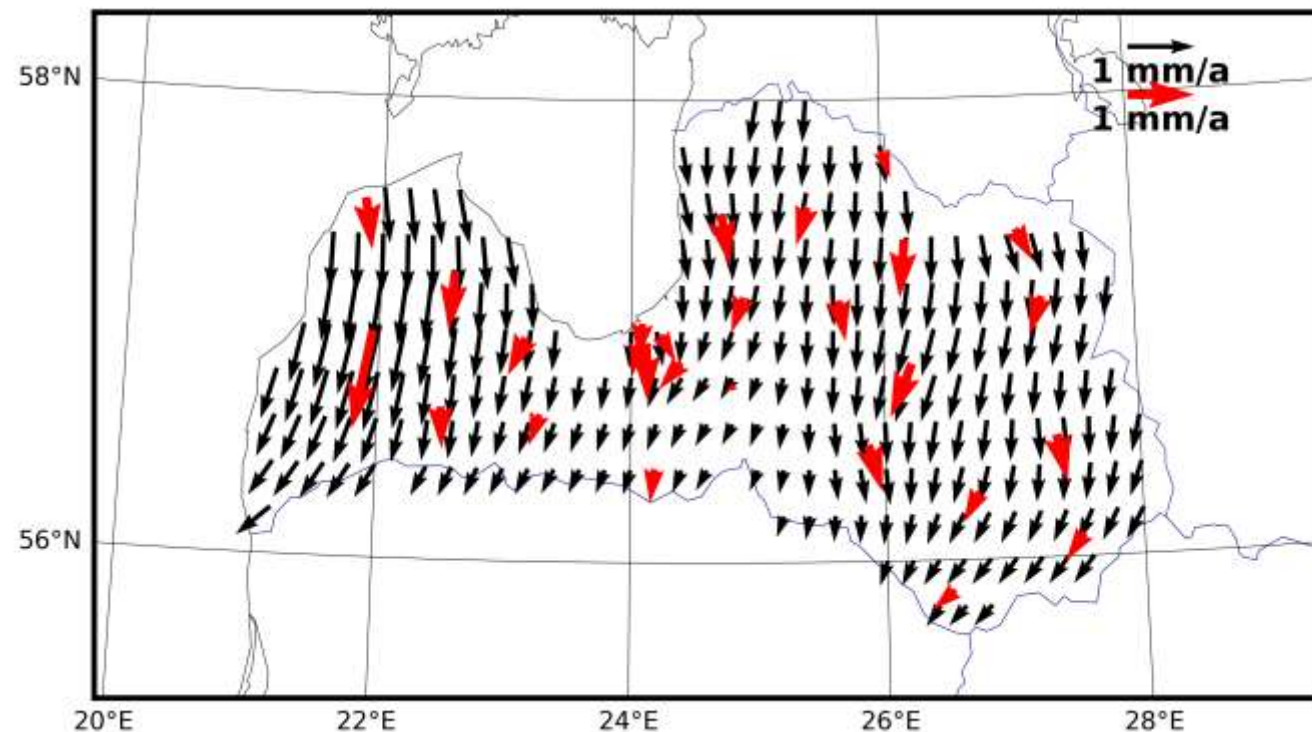
Black – collocated data

A FEW EXAMPLES - LATVIA

Without moving variance (HV-LSC-ex)



With moving variance (HV-LSC-ex²)

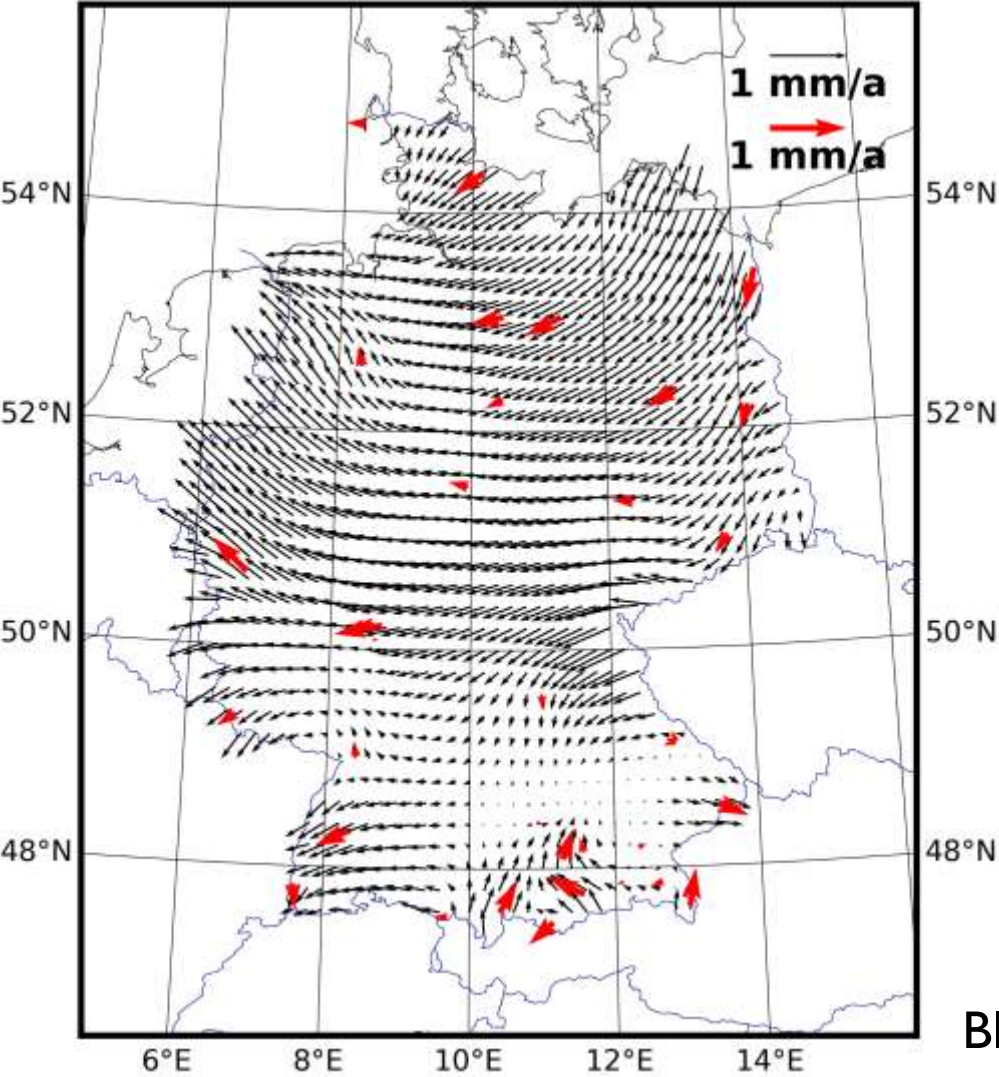


Red – original data

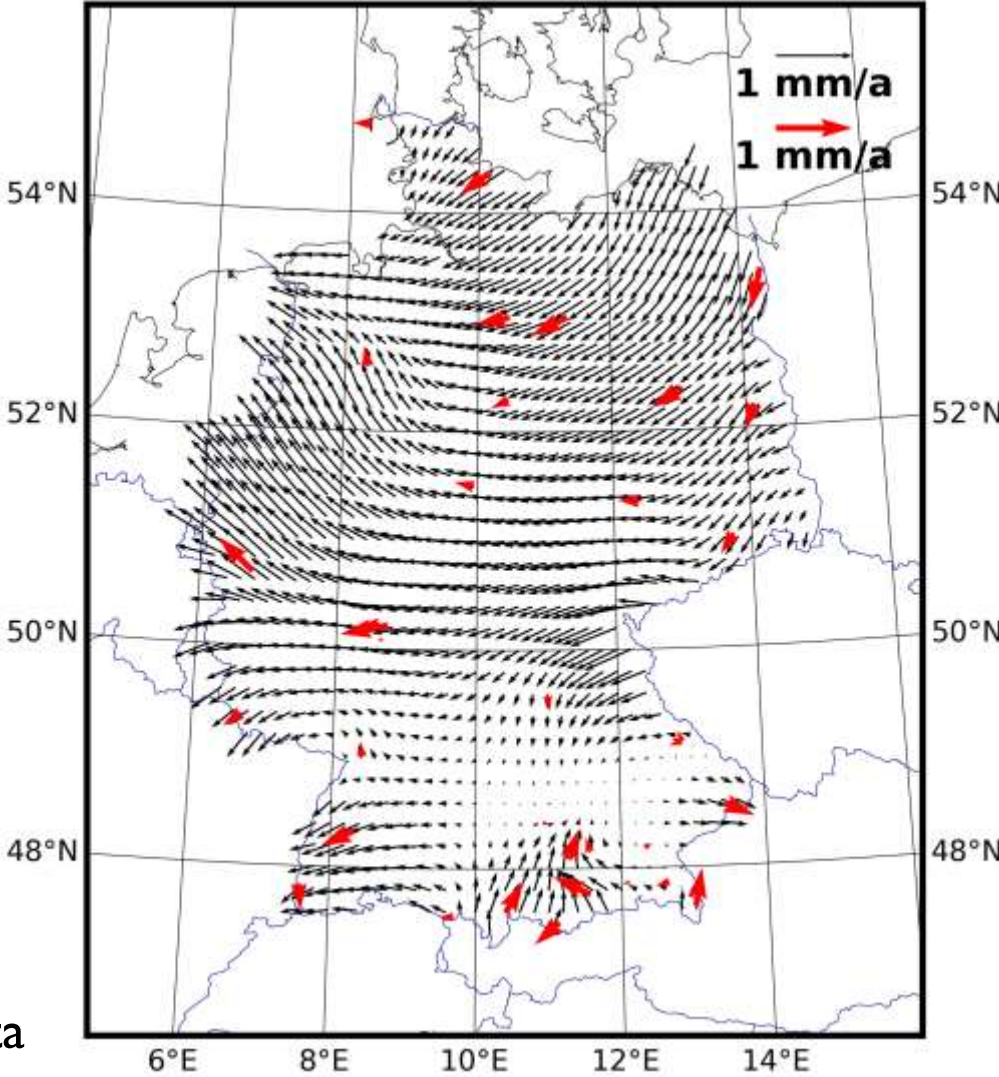
Black – collocated data

A FEW EXAMPLES - GERMANY

Without moving variance (HV-LSC-ex)



With moving variance (HV-LSC-ex²)

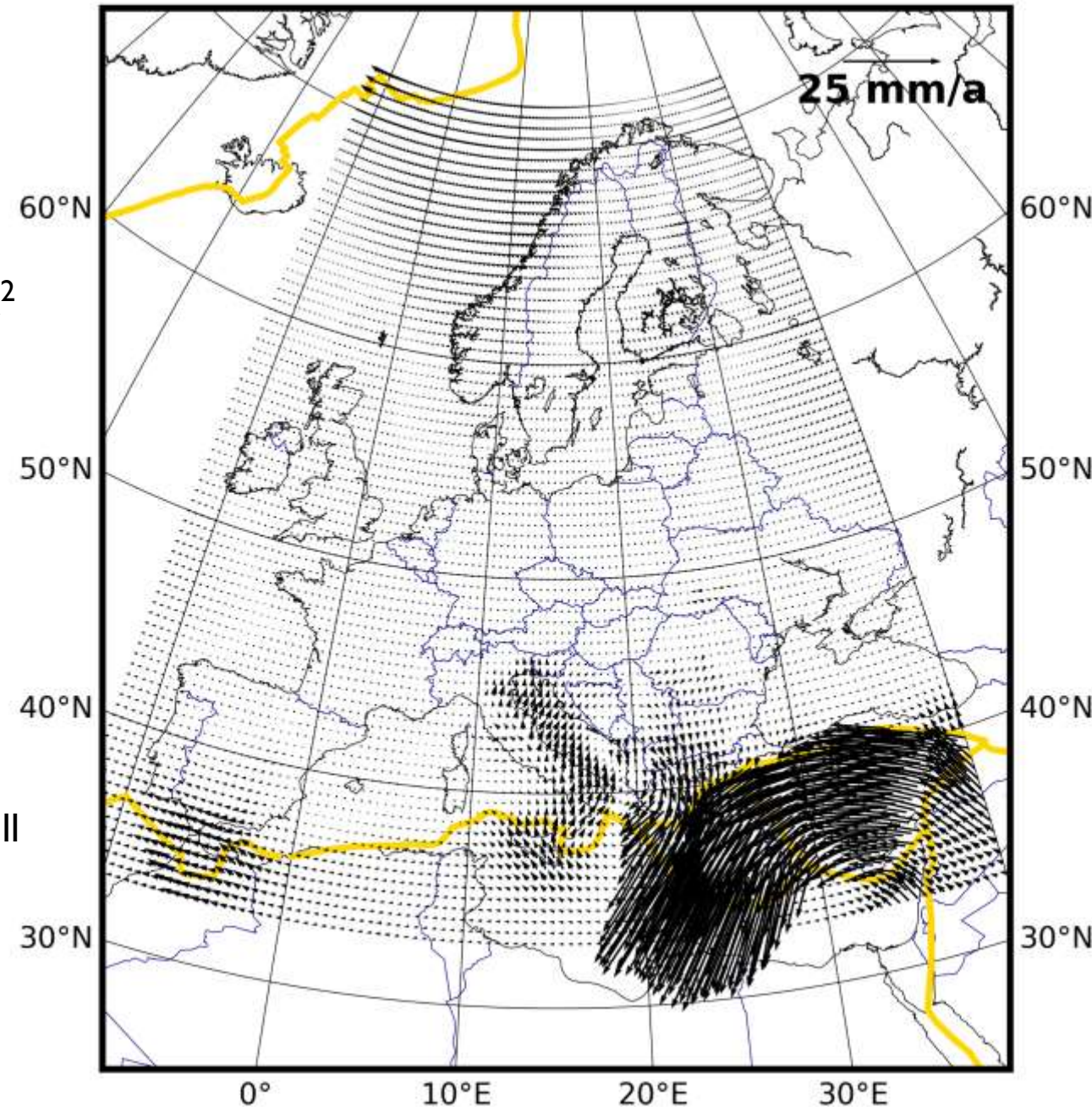


Red – original data

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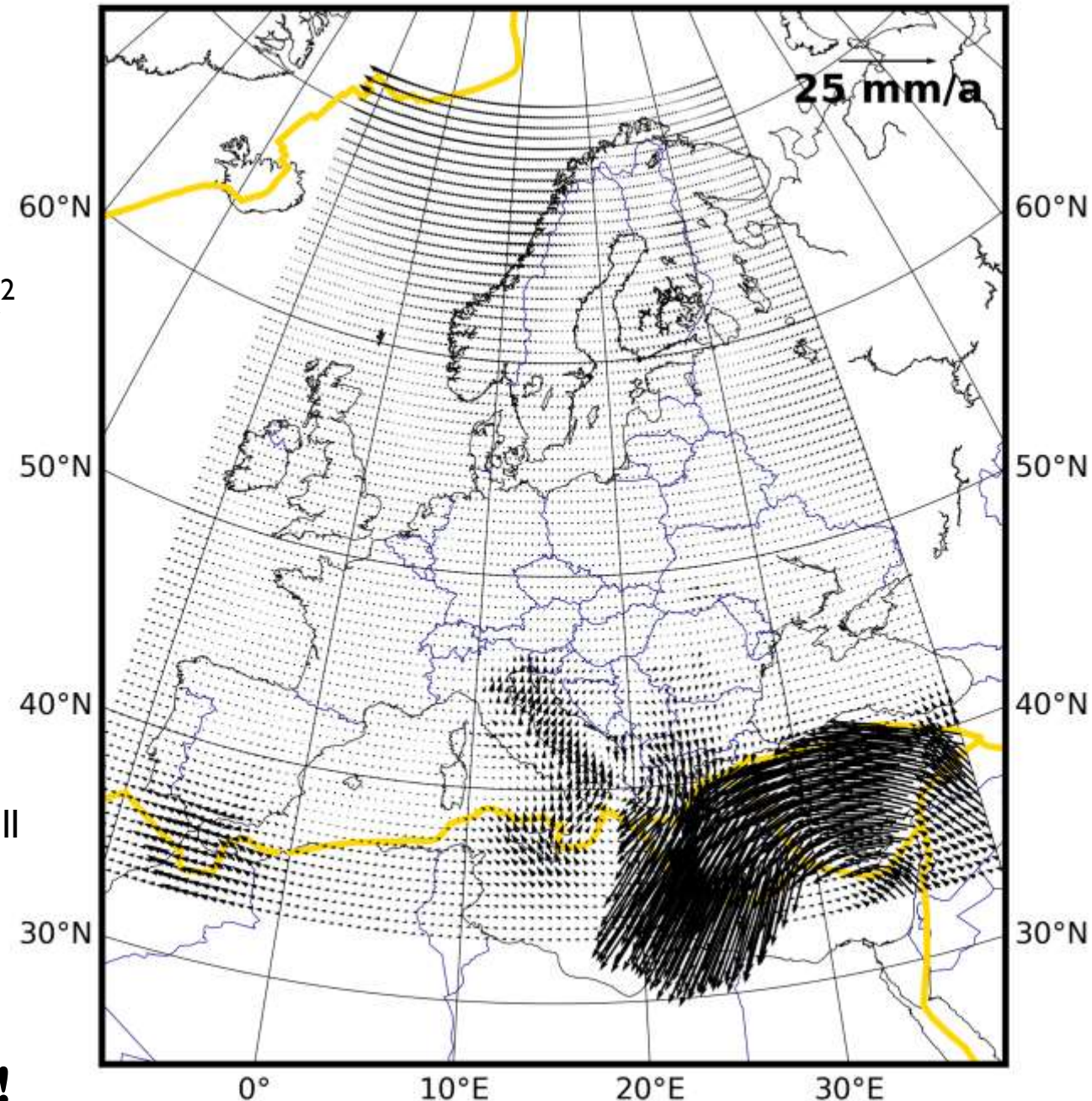
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- Next steps:
 - Verifying the applied correlation length via a test of several values and leave-one-out-cross-validations
 - External validation of the model via a Jackknife resampling
 - Method article is currently in preparation and will be submitted soon
 - EuVeM2021 (with and without moving-variance approach) will be released as ASCII and grid file soon



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THANK YOU FOR YOUR ATTENTION!