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wissen wohin
savoir où
sapere dove
knowing where



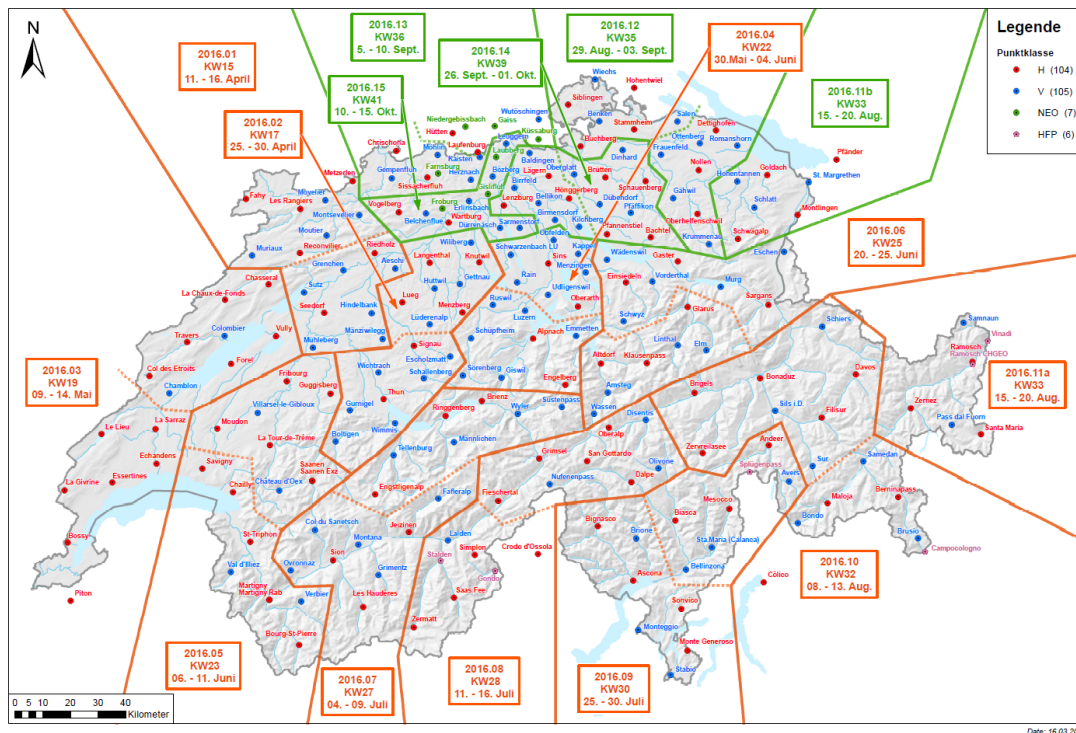
Maintaining the Swiss Terrestrial Reference Frame CHTRF using Multi-GNSS

E. Brockmann, D. Ineichen, S. Lutz, S. Schaer



CHTRF2016: Multi-GNSS field campaign

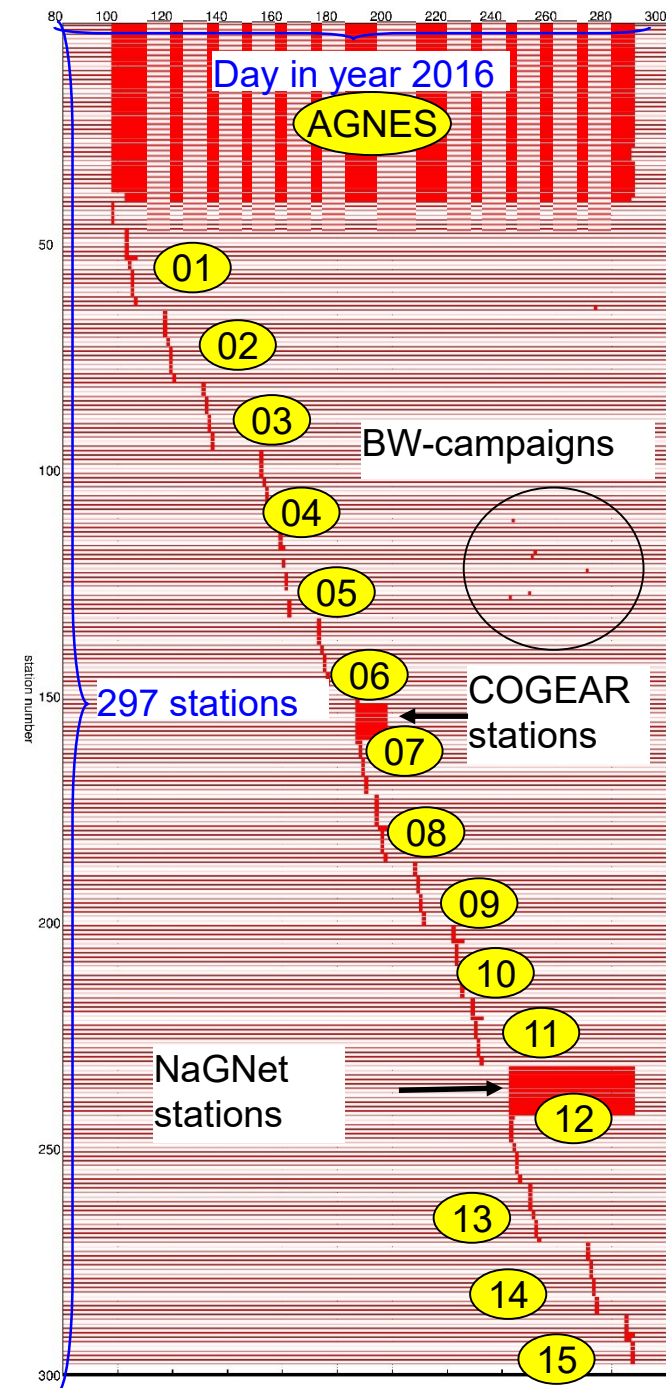
- All ~200 reference points measured in summer 2016 (1988-1995 establ., 1998, 2004, 2010 remeasured every 6 years)
- **Multi-GNSS knowledge** extension (permanent analysis later because campaigns are **less time-critical**)





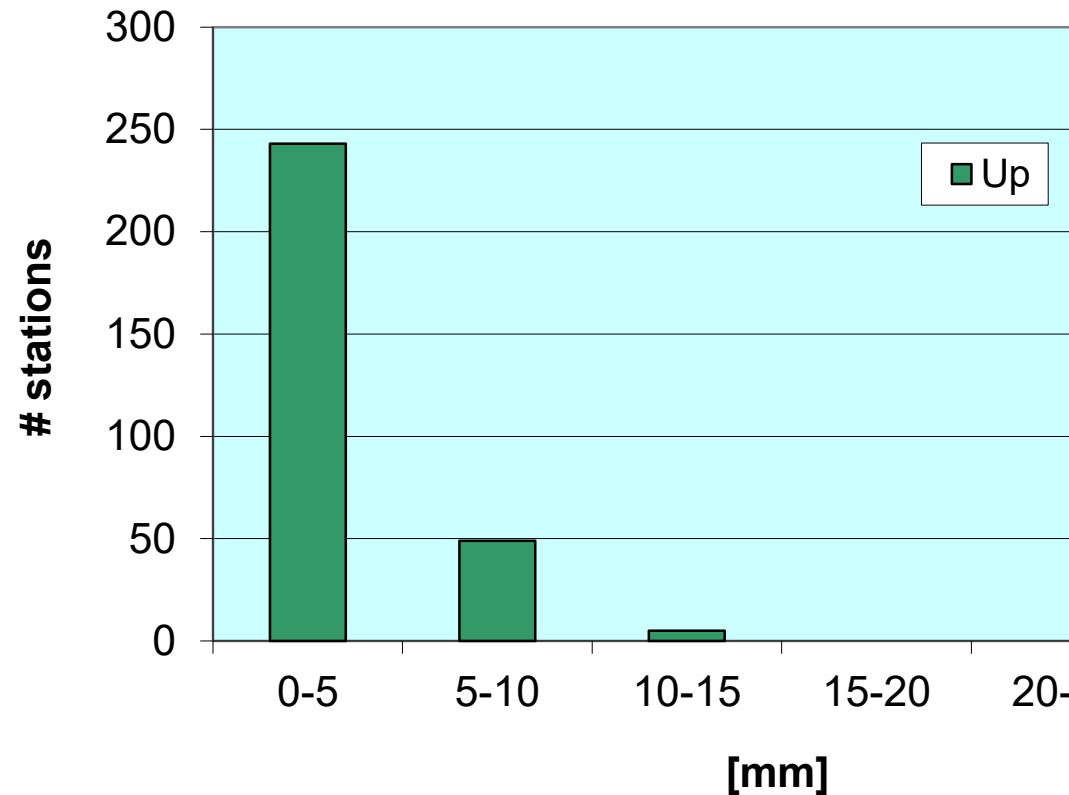
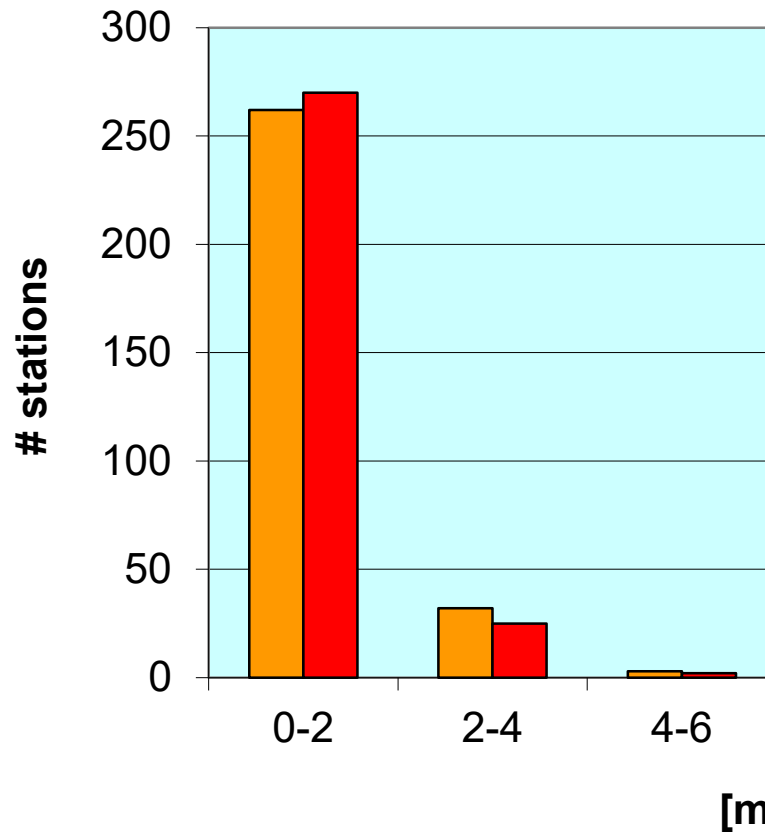
Campaign 2016

- 10 observers
- 15 weeks (Mo – Sa)
- 297 points (incl. AGNES)
- ~ 44.6 h observations / point
- 5 campaigns from Baden-Württemberg integrated (6 h measurements, separated in time)
- Analysis using BSW5.3 (development version)
- Analysis delay 1-2 months – CODE Multi-GNSS orbits not operational in 2016





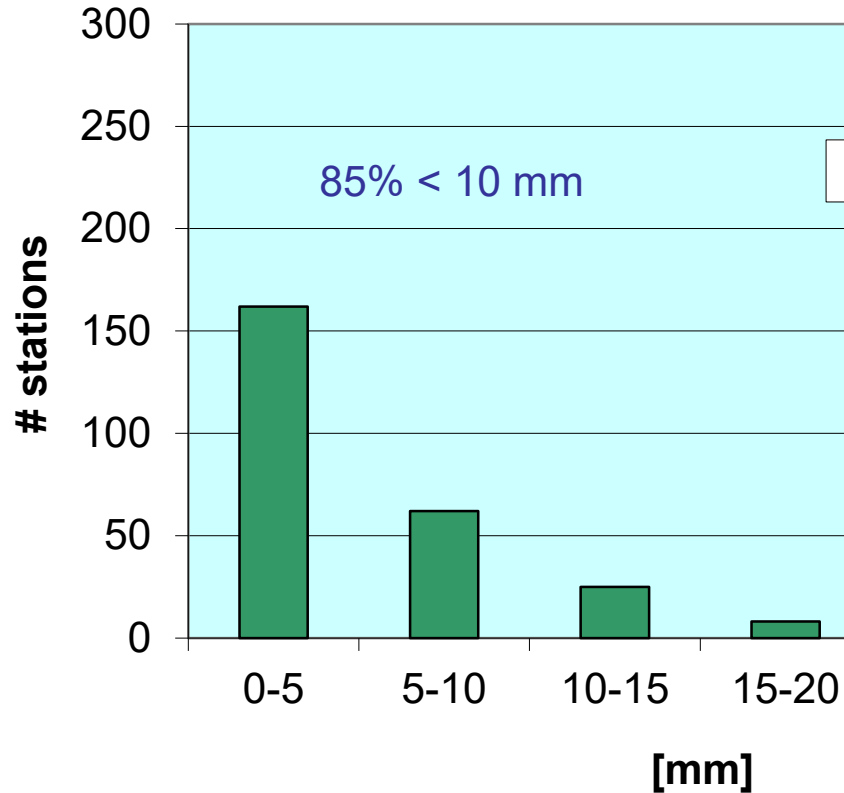
Repeatability horizontally / vertically



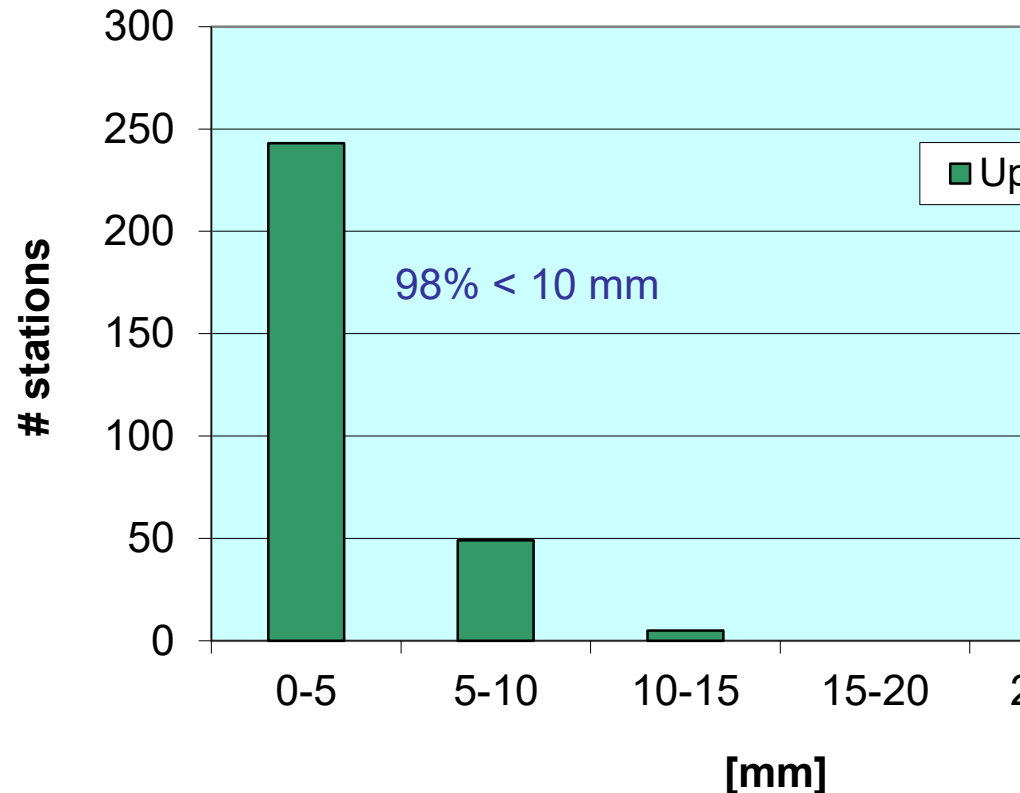


Height repeatability: comparison CHTRF2010 – 2016

2010: GPS



2016: GPS GLO GAL BDS



Improvement due to
GPS -> Multi-GNSS?



ISTPs: „Inter system translation parameter“

- one MIX coordinate (+TRP): N,E,U,T

4



or

- per satellite system one coordinate (+TRP):

N,E,U,T | N,E,U,T | N,E,U,T | N,E,U,T

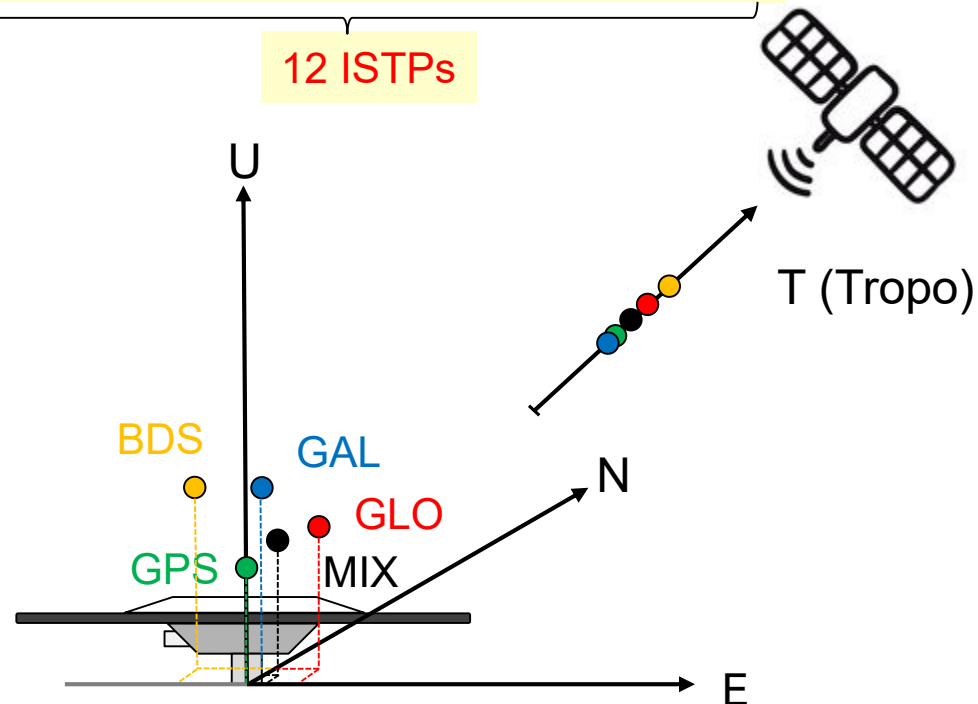
4x4



Reference

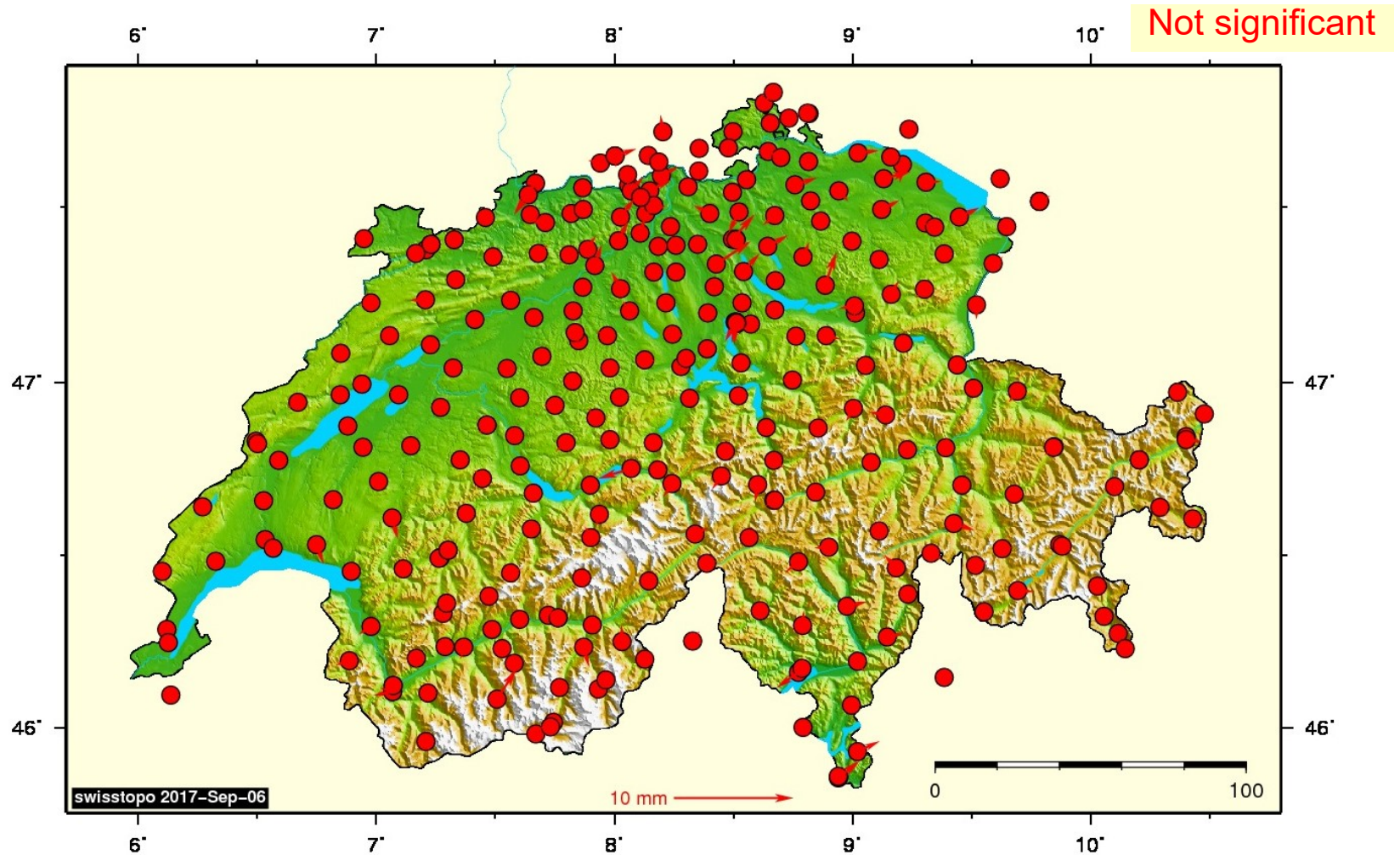
dN,dE,dU,dT | dN,dE,dU,dT | dN,dE,dU,dT

12 ISTPs



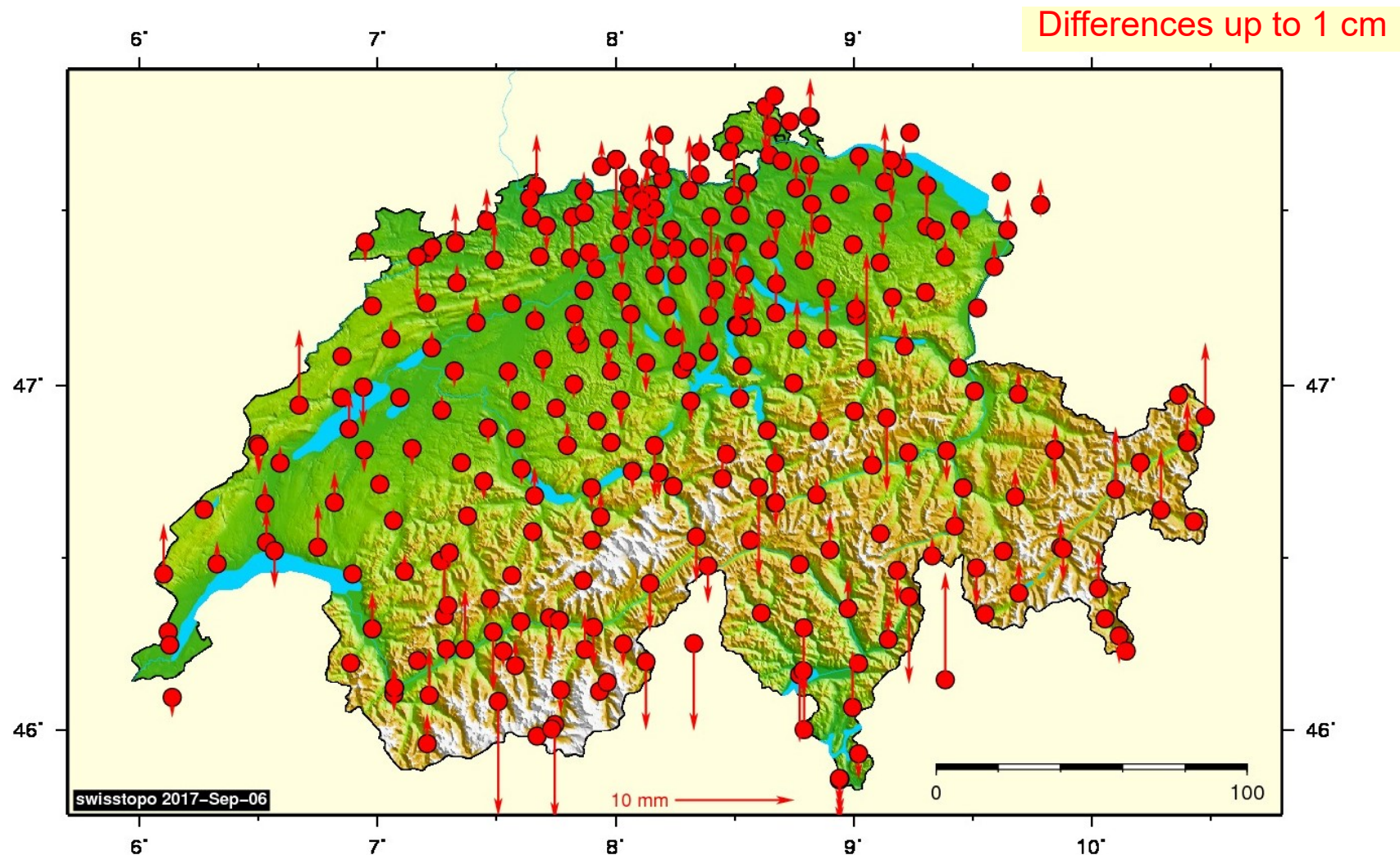


CHTRF16 hor. difference: MIX-GPS





CHTRF16 vertical difference: MIX-GPS

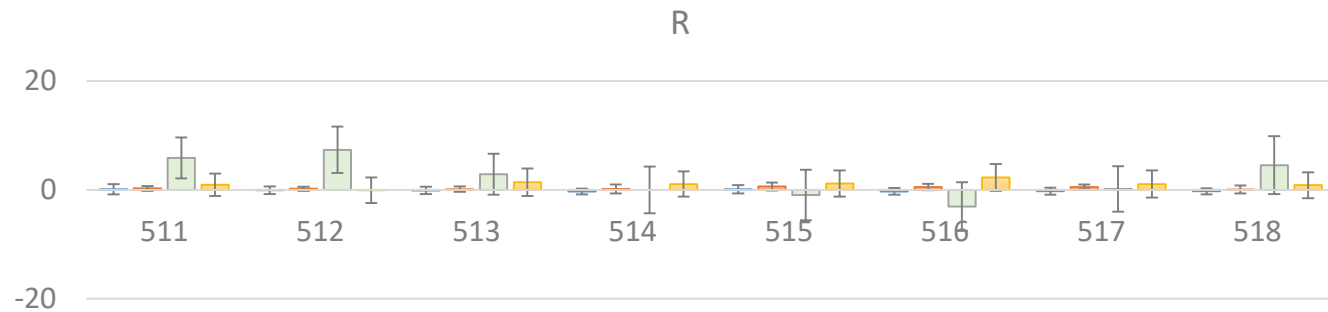




ISTPs field equipment

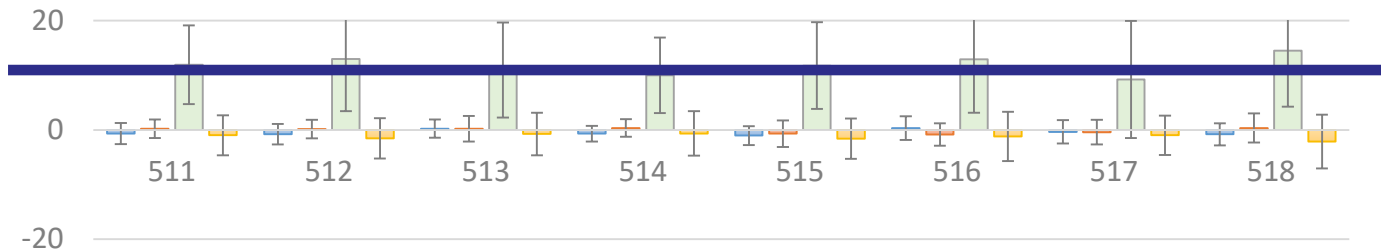
ca. 30 observations / antenna

GPS (Ref)

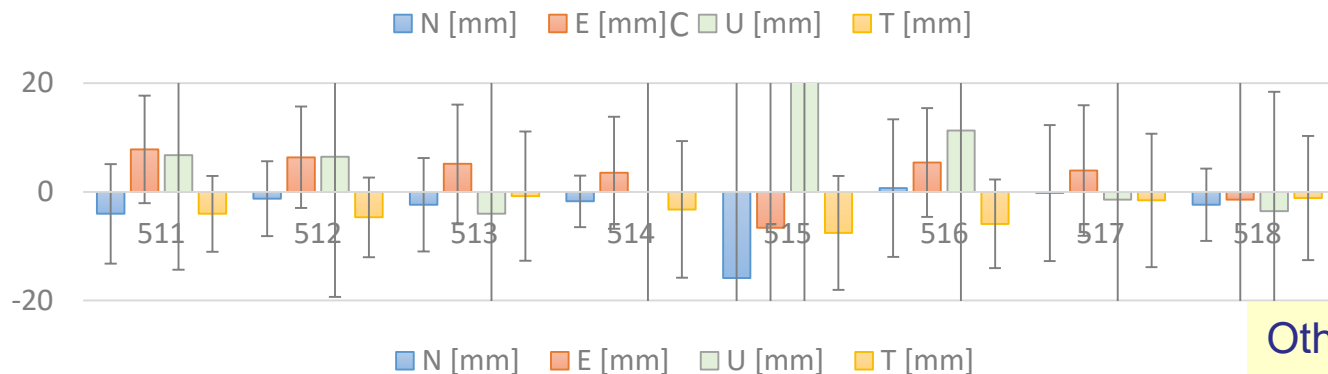


GLO

Up GAL:
 12 ± 2 mm
significant



GAL

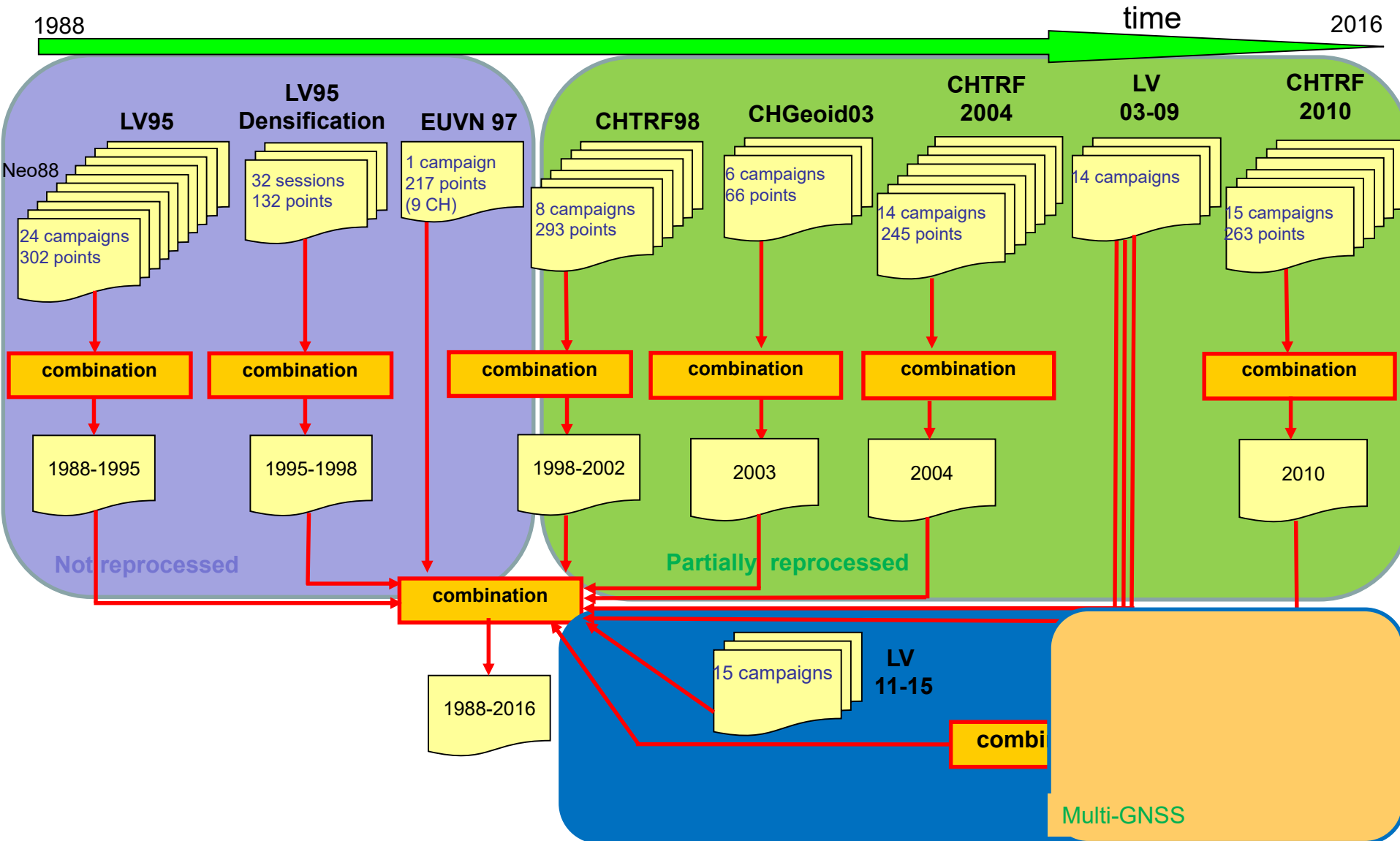


BDS

Other ISTPs
not significant



CHTRF: combination scheme





Combination types

Solution type	remark
REP_CAMP REP_CAMP_C REP_CAMP_C Velocities	All campaigns starting 1998 (reprocessed; major campaigns sub-combined)
ALL_DAY ALL_DAY_C ALL_DAY_C Velocities	All campaigns starting 1988 (1988 – 1997 sub-combination w/o reprocessing) and all other based on session solutions

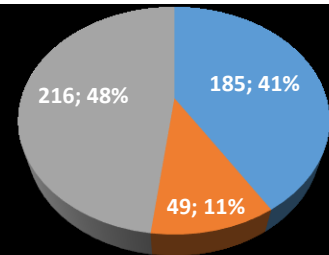


Repeatabilities

Length of time
series

REP_CAMP

comment	#CRD / #VEL ([%])	sN [mm]	sE [mm]	sU [mm]	# Session Files
CRD	450 / 0 (0%)	2.1	1.8	6.7	1718
CRD+VEL	450 / 223 (50%)	1.4	1.1	6.7	1718
improvement [%]		31.7	36.7	0.4	



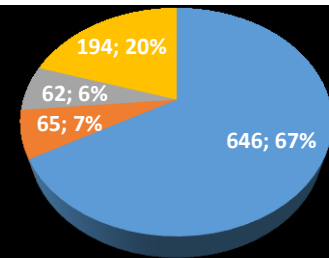
■ 0-4 ■ 4-8 ■ 8-16 ■ 16-26

Only horizontal velocities

(too many antenna changes and too weak heights)

ALL_DAY

comment	#CRD / #VEL ([%])	sN [mm]	sE [mm]	sU [mm]	# Session Files
CRD	967 / 0 (0%)	2.2	1.6	5.4	16538
CRD+VEL	967 / 310 (33%)	1.7	1.4	5.3	16538
improvement [%]		23.1	14.1	0.7	

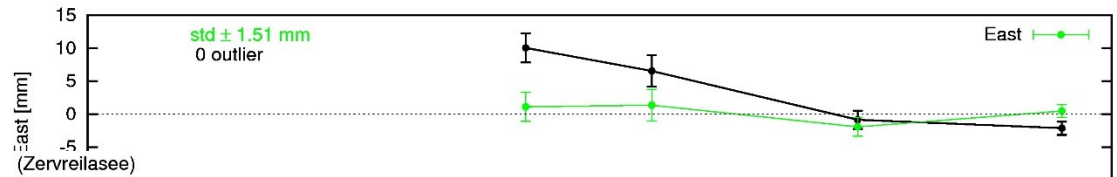
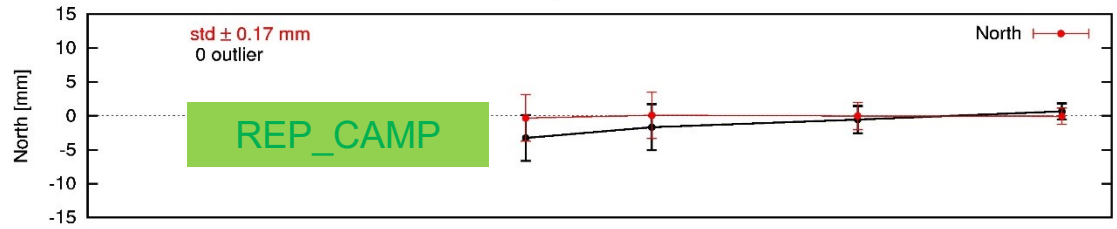


■ 0-4 ■ 4-8 ■ 8-16 ■ 16-26



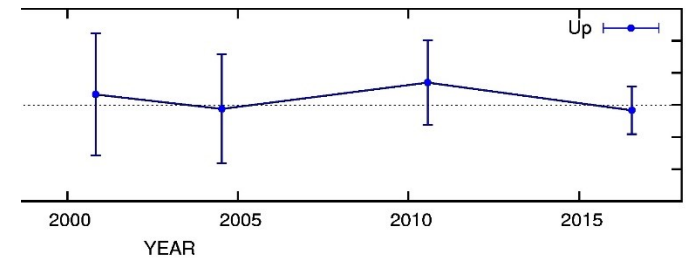
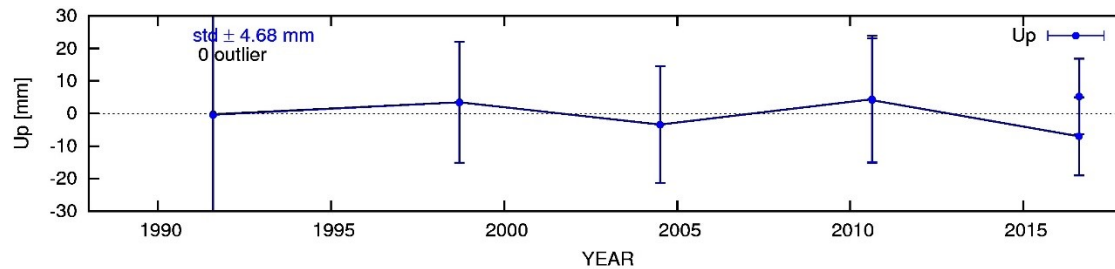
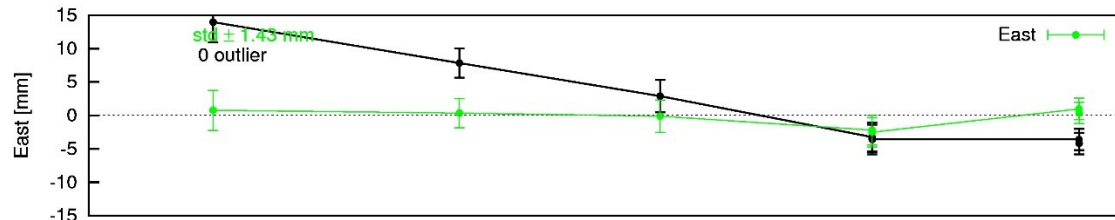
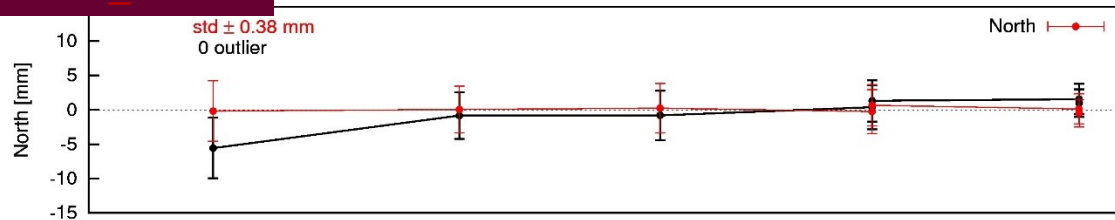
Example Zervreilasee

Coordinate repeatability of 1234.100 (Zervreilasee)



ALL_DAY

Coordinate repeatability of 1234.100



velocities estimated

No velocities estimated

12/12/17 18:26



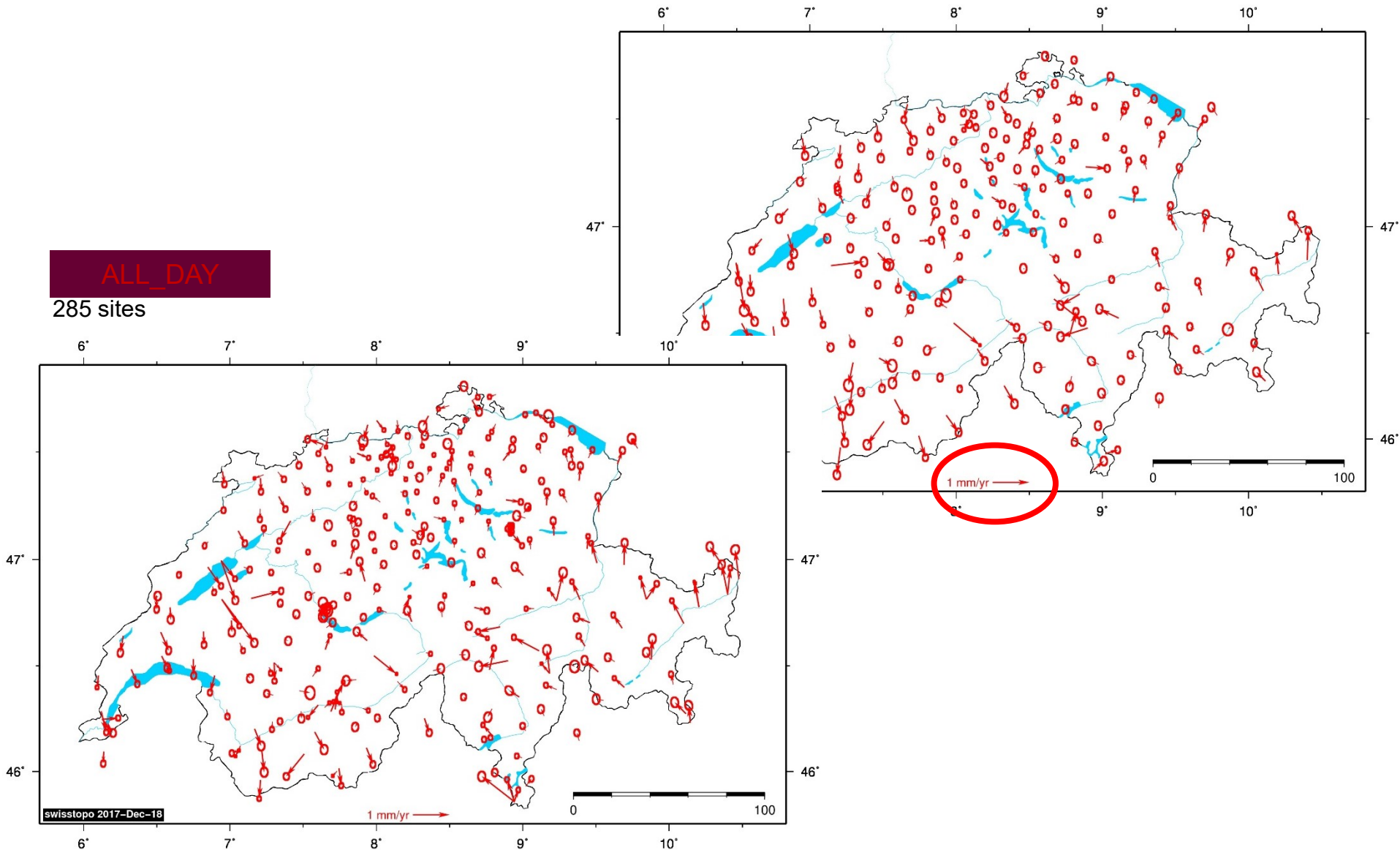
Velocity Fields

REP_CAMP

205 sites

ALL_DAY

285 sites



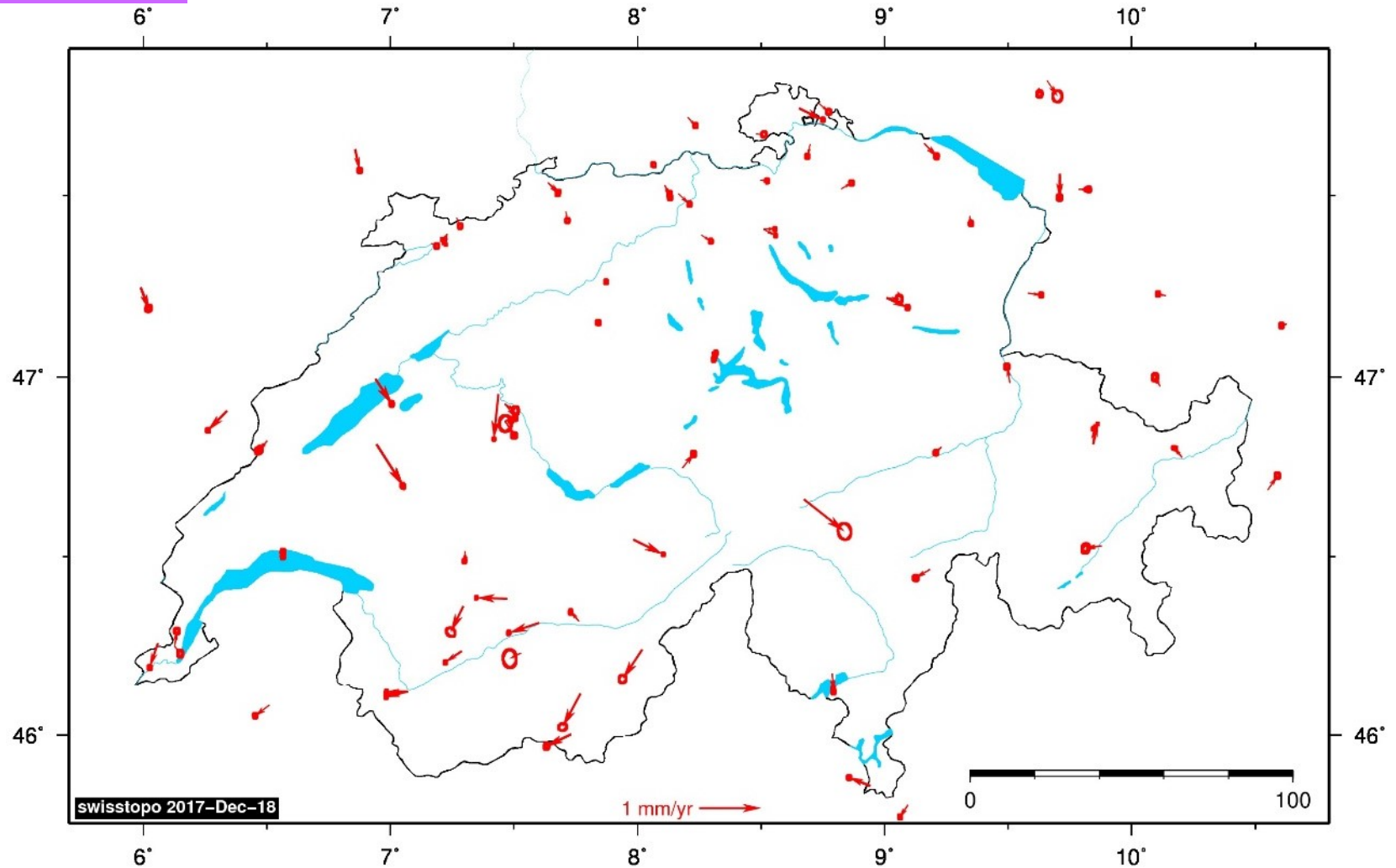
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Velocity field: Permanent Network

AGNES





Statistics of velocity fields

Solution type	# velocities (after QC)	Standard deviation [mm/year] from zero field		Mean formal rms [mm/year] *15	
		North	East	North	East
CHTRF2004	176	0.35	0.33	-	-
CHTRF2010	233	0.27	0.23	0.122	0.168
REP_CAMP	205	0.30	0.20	0.083	0.114
ALL_DAY	285	0.31	0.20	0.067	0.089
AGNES	57	0.20	0.22	0.040	0.051
2016: Diff. REP_CAMP- ALL_DAY	202	0.11	0.10	-	-



Summary

- ✓ • Multi-GNSS (GPS+GLO+GAL+BDS) measurements used for reference frame maintenance (permanent network and campaign data)
- ✓ • Quality control CHTRF2016 fine (repeat. better for height)
- ✓ • Long-term combination successful, but a preliminary velocity field, yet
 - based on partial reprocessing campaigns back till 1998
 - Similar field as derived 2010 (small horizontal velocities: 0.2-0.3 mm/yr standard deviation w.r.t zero field)
 - Velocity field already used within EUREF WG “EU Dense Velocities” → presentation S. Lutz