

[illegible]

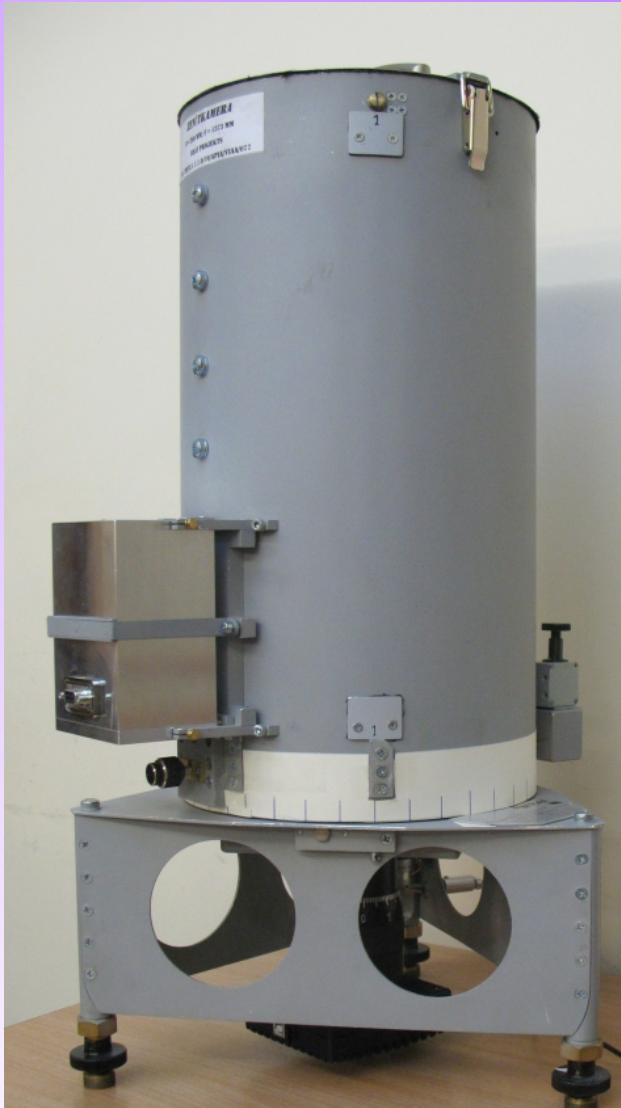
Presented by Jānis Kaminskis



Development of a digital zenith telescope optical system and telescope prototype and analysis of experimental vertical deflection measurements for applications in Latvian geodetic network has been performed at the **Institute of Geodesy and Geoinformation (GGI)**, University of Latvia.

An **original optical system** for a digital zenith telescope was computed and a **patent application** has been submitted.

The astro-geodetic method is known since mid-20th century, however with little recognition, since the acquisition and processing of high quality data was time and labor consuming process. During the recent decades due to the emergence of site geocentric coordinate acquisition using GNSS, charge-coupled device (CCD) imaging technologies, high resolution electronic tiltmeter technologies and extensive, high accuracy reference star catalogues, this method has become increasingly popular. The research has yielded that astro-geodetic methods provide a faster result with a smaller number of measurements than in the case of gravimetric methods. In order to apply and expand the astro-geodetic method in Latvia and improve precision of local geoid model, vertical deflection measurements will be performed in Latvia.



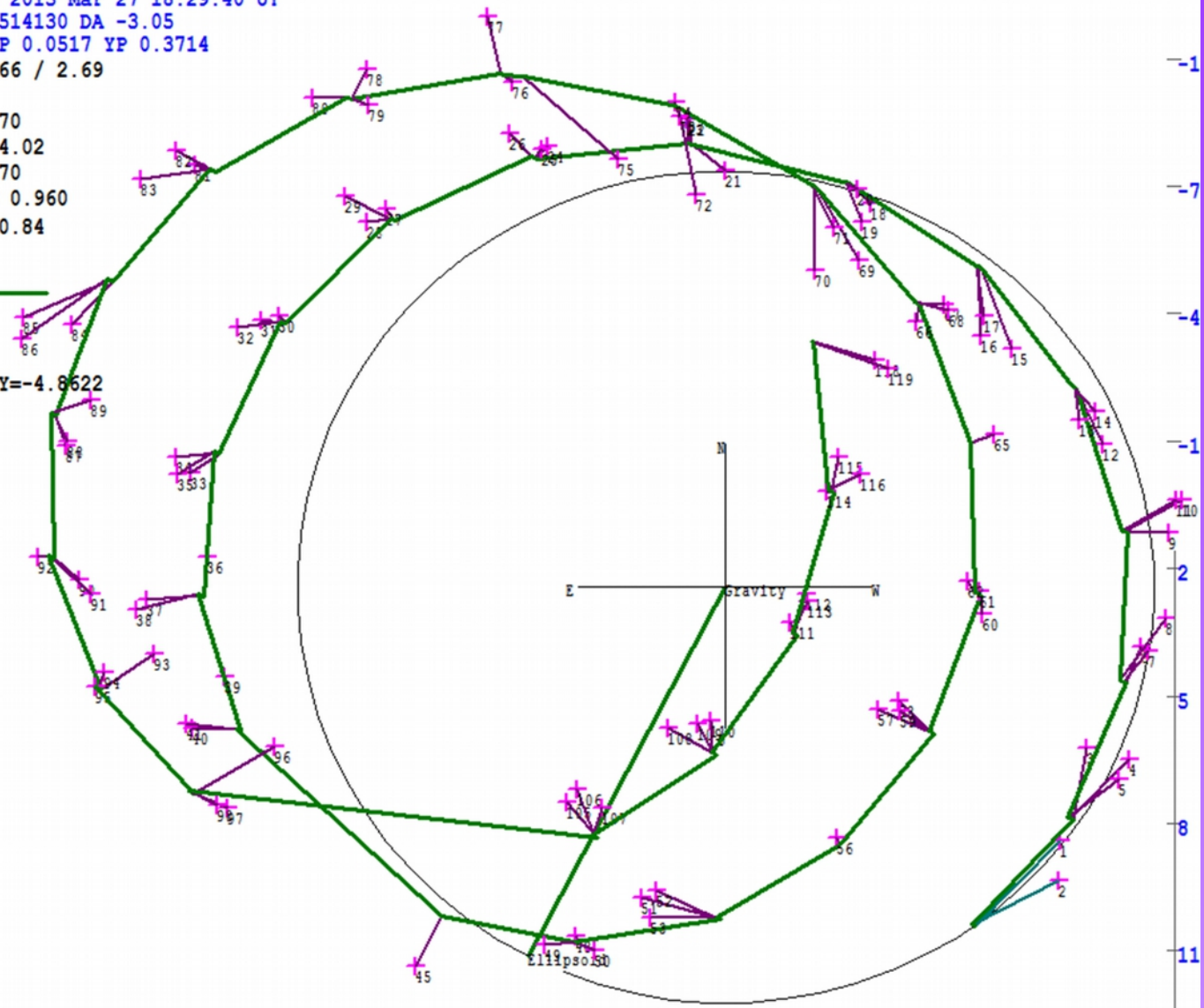
Astrometric and gravimetric subsystems:

- 20 cm catadioptric telescope, $F=1373$ mm
- Field of view 0.35×0.27 dg, 1360×1024 pixels ($\sim 1''$)
- Reference star catalogue: subset of NOMAD (*Naval Observatory Merged Astrometric Dataset*) up to 15m
- Reference stars per frame: 4 .. 23, average 12
- Star magnitude: 6m .. 13m with 0.1-0.3 sec. exposure
- Source of apparent places: NOVAS (*Naval Observatory Vector Astrometry Software*)
- RMS of star image position: $0.3''$.. $1.5''$, average $0.5''$
- Zenith position accuracy for frame: $0.1''$.. $0.2''$
- Precision tiltmeter HRTM with 50 prad ($\sim 1e-5''$) resolution in $\pm 2'$ range

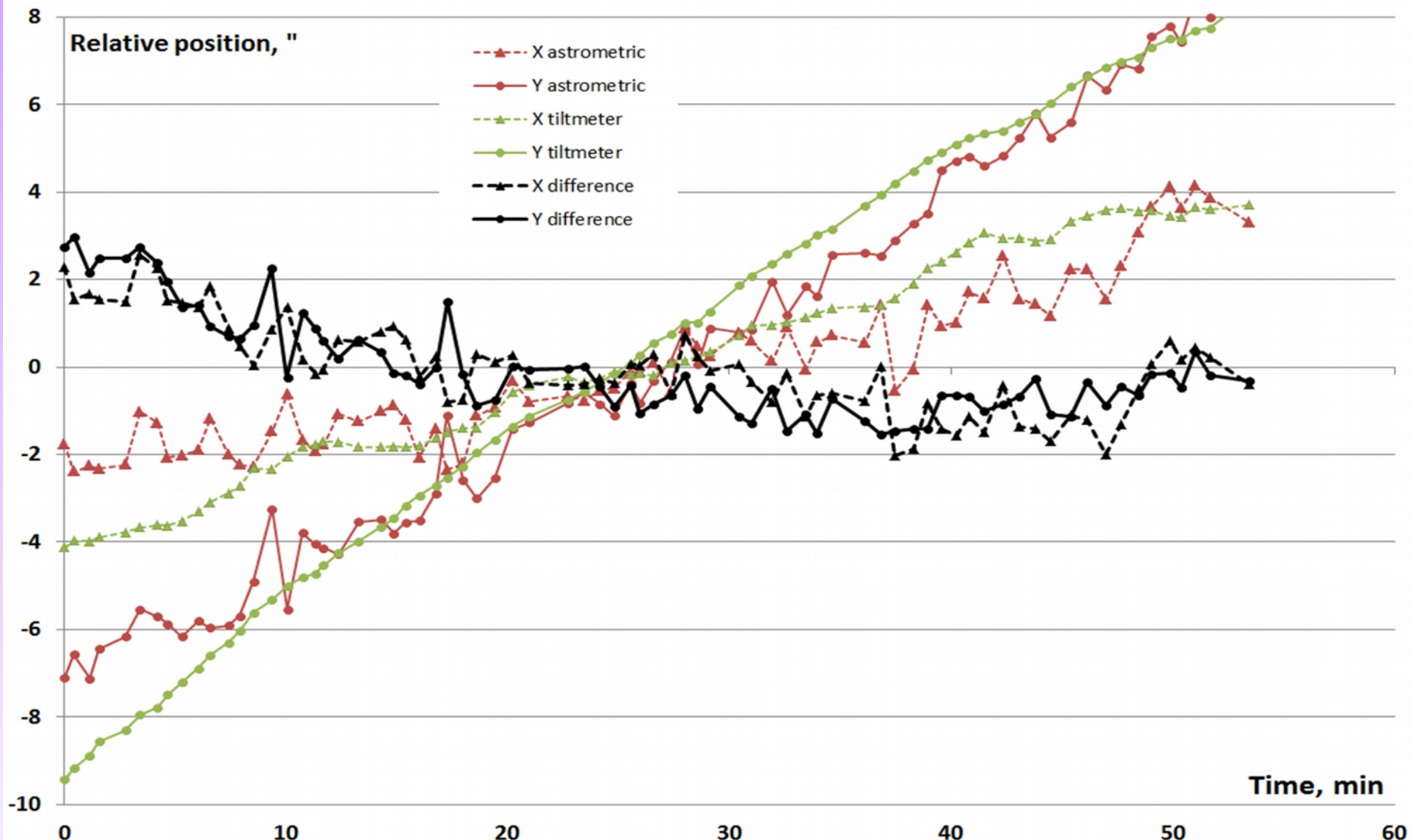
Development of a zenith telescope was commenced in 2011 in the Institute of Geodesy and Geoinformatics <GGI> at the University of Latvia

site 1003 Ikšķile 2013 Mar 27 18:29:40 UT
 F=56.834070 L=24.514130 DA -3.05
 UT1-UTC 0.16500 XP 0.0517 YP 0.3714
 N=101 / 103, S=2.66 / 2.69
 X0=2.67 Y0=2.44
 dZx=-4.49 dZy=8.70
 X0c=460.54 Y0c=464.02
 Rc=9.71 Ac=209.70
 Lscale: X 0.960 Y 0.960
 rms W-E 0.78 S-N 0.84
 rms 1.15 N=101

5" —————
 dT=40min
 Drift X=-10.3982 Y=-4.8622



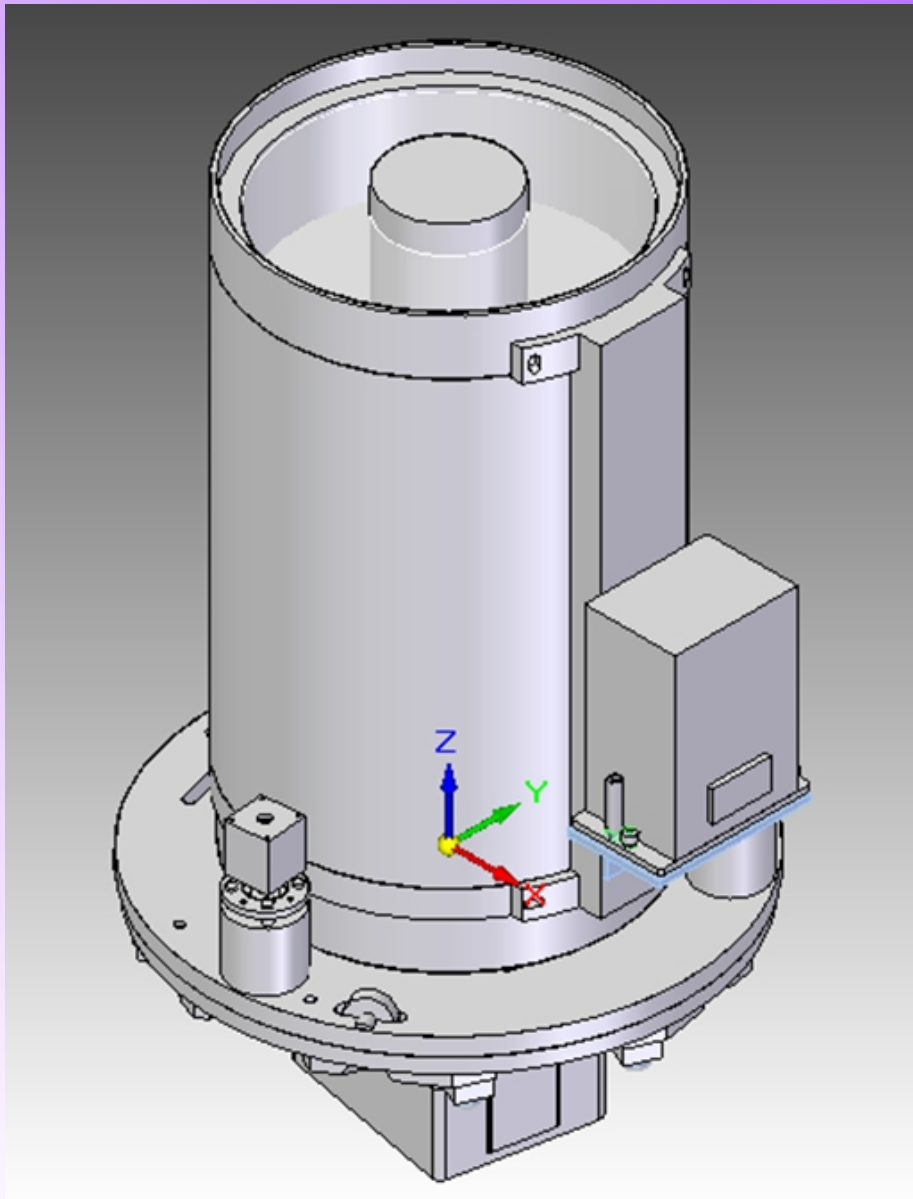
Difference between directions to reference ellipsoid normal and tiltmeter axis in rotating coordinate system. In ideal circumstances it should make circle with radius of plumb line deflection value (shown by thin black line). In reality, thermal deformations changes tiltmeter axis direction relative to optical system, resulting in spiraling trajectory. If dependence of deformations on time is close to linear, evaluation of compensating drift model is possible.



Drift of plumb line and ellipsoidal zenith positions and difference of them in instrument coordinate system. Drift of plumb line and ellipsoidal zenith positions and difference of them when instrument is in stationary position. Some bending of instrument assembly has occurred besides tilting of support surface, resulting in decidedly non-linear drift of tiltmeter and imager relative orientation. Observation sessions must be short (a few minutes) to avoid most of effects of this bending or include them in linear drift model.

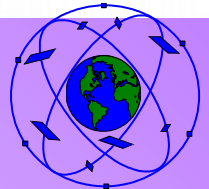
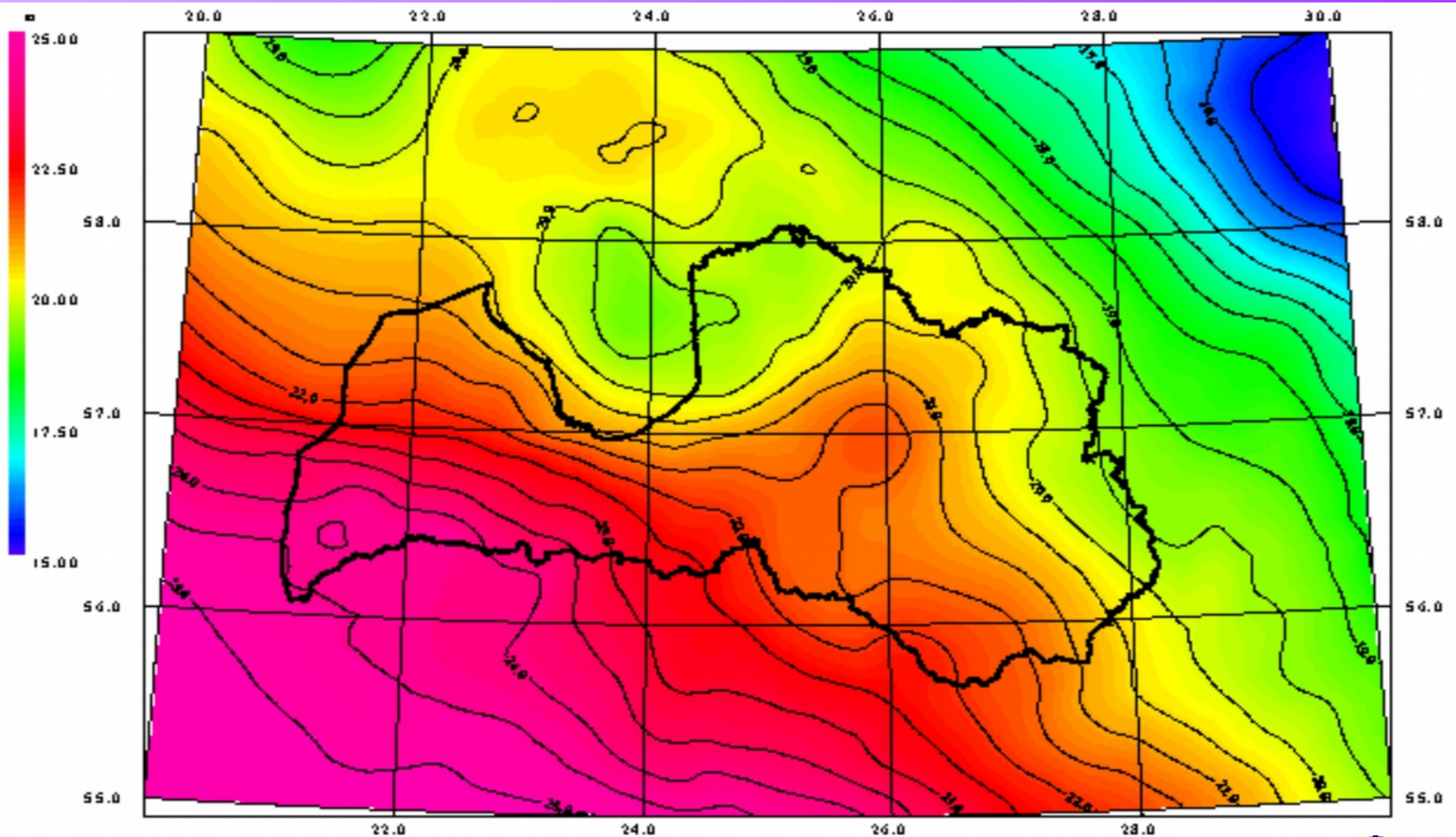
Digital zenith camera

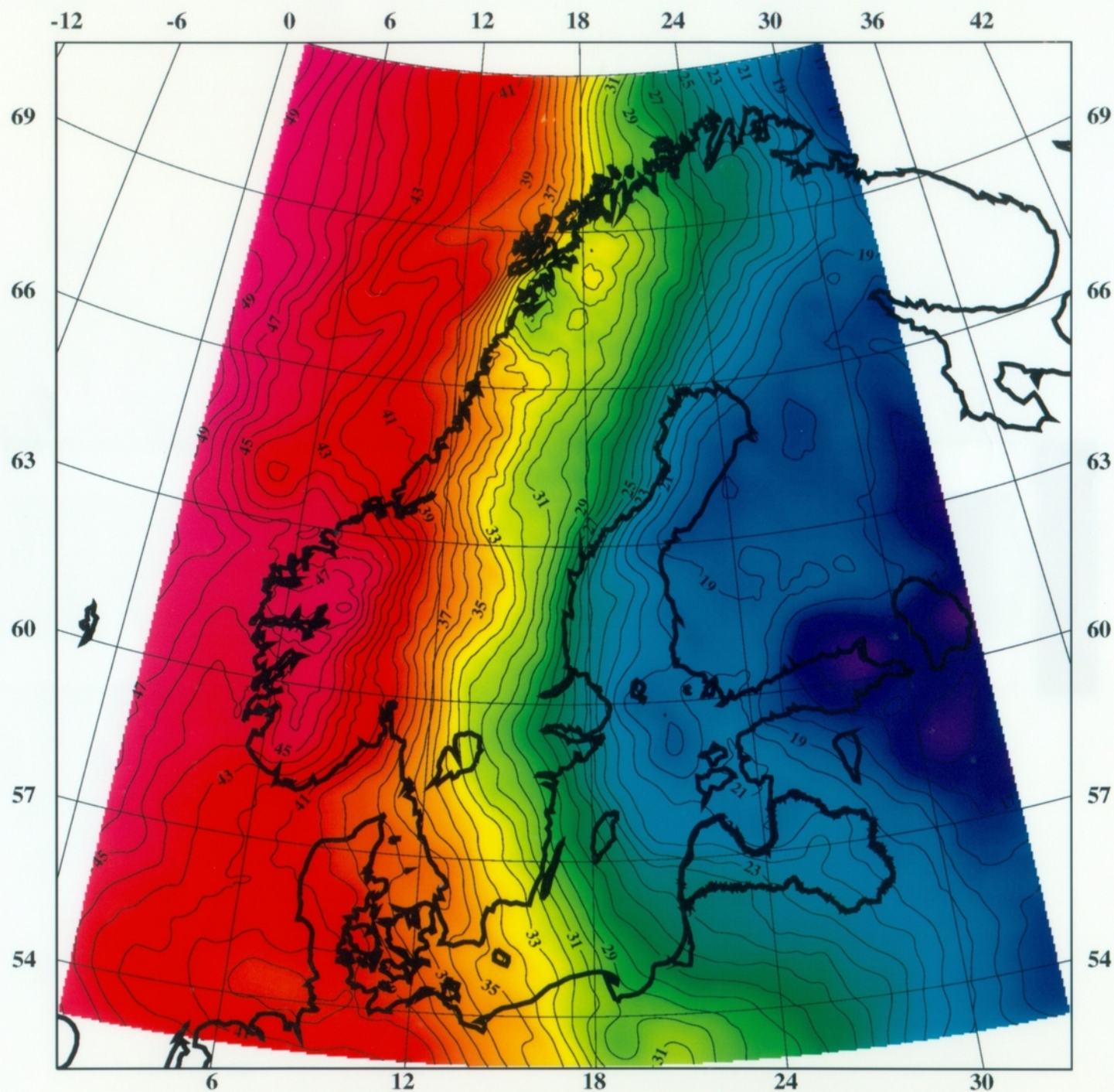
Continuing digital zenith camera project, a prototype camera has been built and an extensive test research carried out, looking for solutions and design elements which might present problems and should be improved [1]. In general, camera properties were found close to expected. The most problematic aspect of prototype camera was mechanical stability of camera assembly. Effects of thermal deformations during observation sessions were found to be a serious disturbing factor. Also, necessity to improve extent of automation was obvious. As a result, an improved camera design was made. It uses different approach to observation process – motorized leveling will be performed in each camera position before measurements, ensuring, that tiltmeter readings are always small and minimizing problems rising from tiltmeter scale and orientation uncertainty.



New camera design

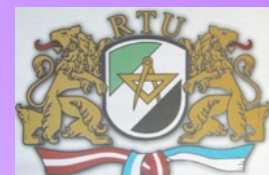
Latvia geoid (LV'98) from gravimetry and ERS-1 data





NKG
from
15m
till
50m
c.i.1m

Possible combination with other geodetic techniques: GNSS & VLBI



IRBENE

Typical view of
antenna,
Place in a quite
place without
radio noise

RT-32 max angular
speed around the
altitude and the
azimuth axis (2 direct-
current, 60kw
motors): **2°/sec**

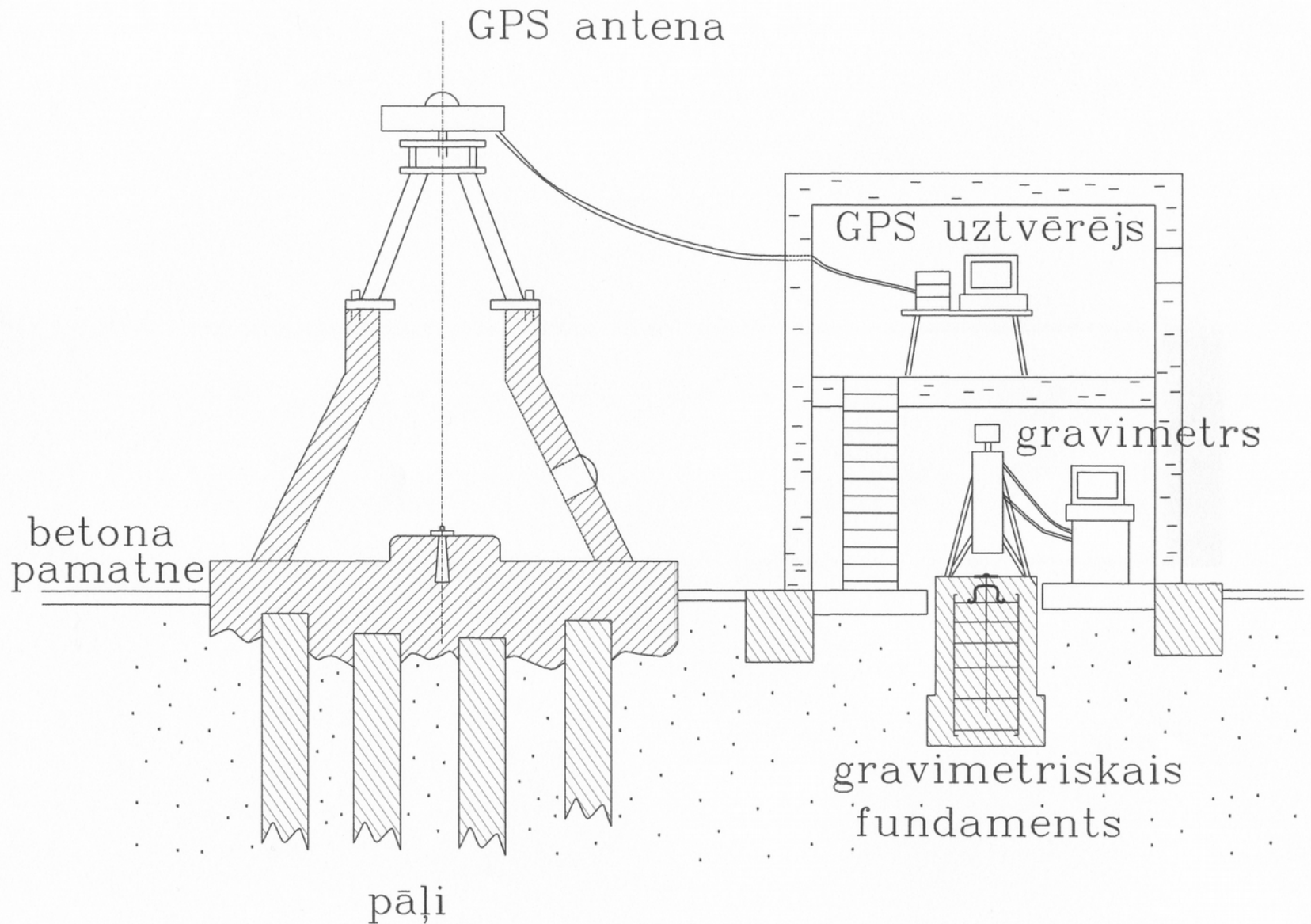
Possible use in geo-VLBI



IRBENE



IRBENE



IRBENE



**Absolute
gravity
station**

Computations with GRAVSOFT

```
C:\Users\Janisk\Desktop\GEOID_~1\GEOID_O.EXE

*****
*
*   GEOID - GRAUSOFT geoid interpolation and transformation   *
*
*   vers. MAR95 (c) RF, Kort- og Matrikelstyrelsen, Denmark *
*
*****

Enter task: 1 = interpolate geoid heights
            2 = ellipsoidal to orthometric heights using geoid
            3 = orthometric heights to ellipsoidal - - -
            4 = geoid heights in different datum ...
            5 = deflections of the vertical ...
-> 5

--- deflections of the vertical wanted, unit: arcsec ---
Enter binary geoid file name: CR=\geoide\geoid94a.bin
-> geoid94a.BIN

Geoid grid limits and spacing in degrees:
    55.00000    59.00000    20.00000    30.00000    0.02500    0.05000
Do you wish to input data points from a file? (Y/N or CR=N)
-> N

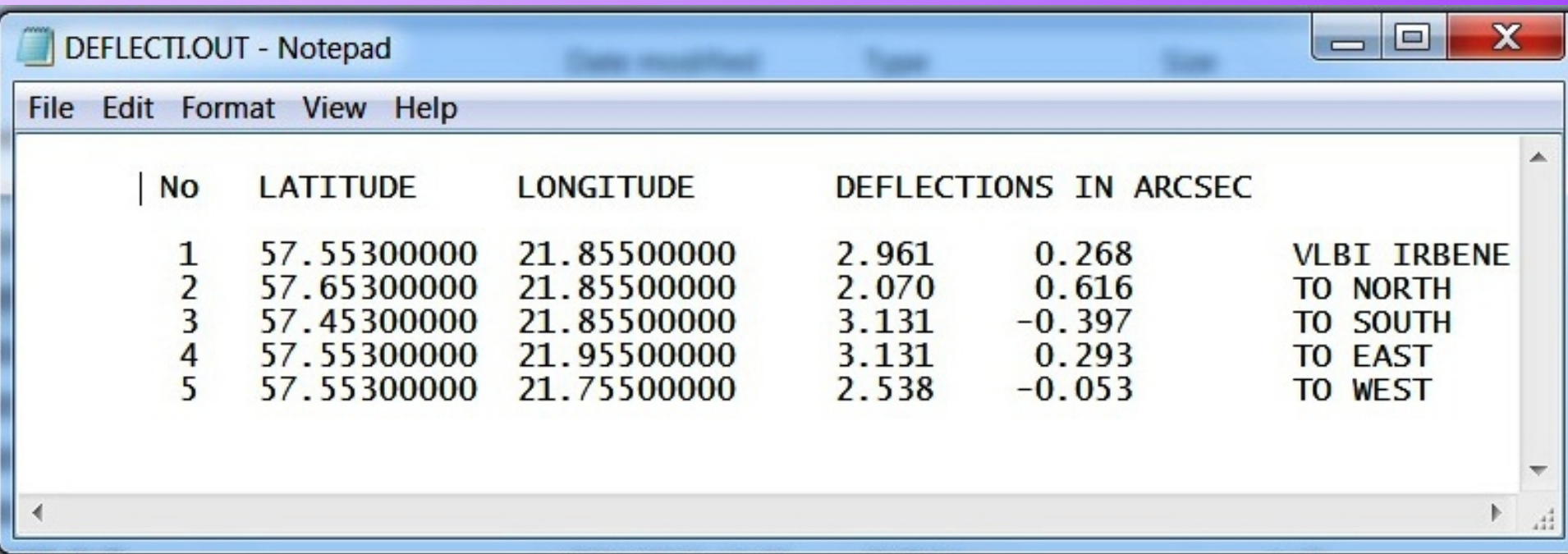
Enter file name for output: (CR=geoid.out)
-> deflection_vertical.out

Type of input: 1 = lat, lon (degrees)
                2 = lat, lon (deg,min,sec)
                3 = X, Y, Z (meter)
                4 = N, E (UTM, meter)
-> 1

- output coordinates are geographic degrees -
Enter: rfi, rla (x=exit)
-> 57.553  21.855

        1   57.55300000  21.85500000    2.961    0.268
Enter: rfi, rla (x=exit)
-> _
```

Results from GRAFSOFT at IRBENE and around

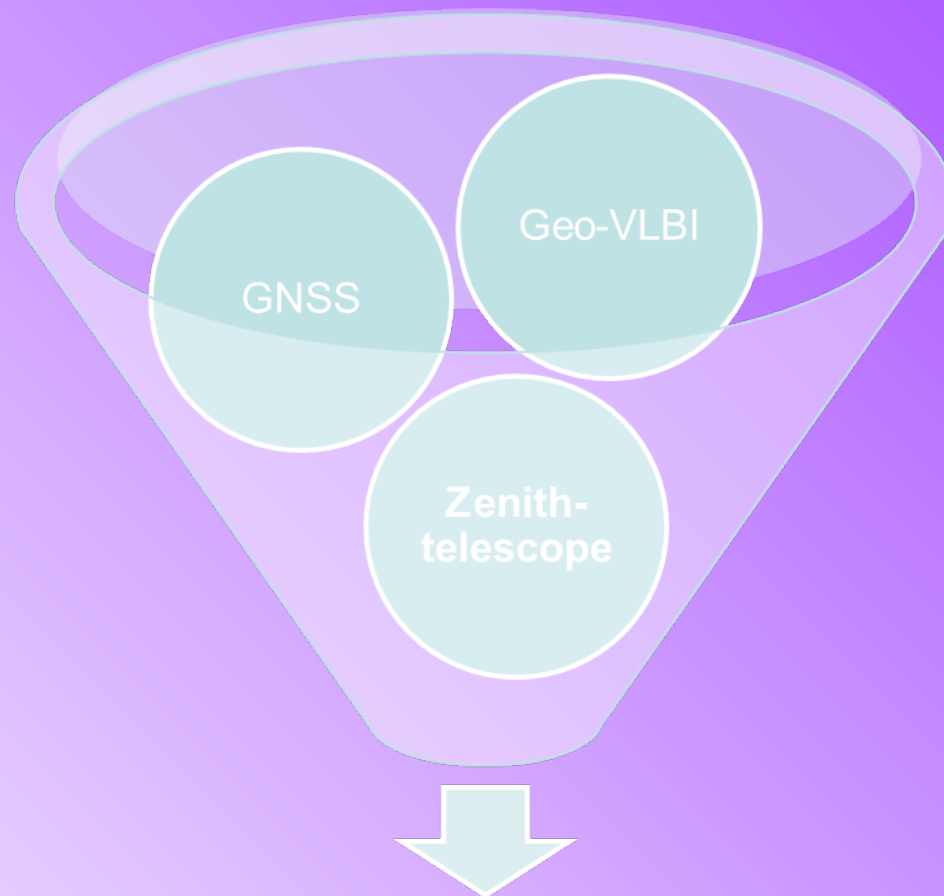


A screenshot of a Notepad window titled "DEFLECTI.OUT - Notepad". The window displays a table with five columns: "No", "LATITUDE", "LONGITUDE", "DEFLECTIONS IN ARCSEC", and "VLBI IRBENE". The table contains five rows of data. The first row shows station 1 with latitude 57.55300000, longitude 21.85500000, and deflections of 2.961 and 0.268. The subsequent rows show stations 2, 3, 4, and 5 with similar data. The deflection values are in arcseconds. The text "VLBI IRBENE" is aligned to the right of the deflection values.

No	LATITUDE	LONGITUDE	DEFLECTIONS IN ARCSEC		VLBI IRBENE
1	57.55300000	21.85500000	2.961	0.268	VLBI IRBENE
2	57.65300000	21.85500000	2.070	0.616	TO NORTH
3	57.45300000	21.85500000	3.131	-0.397	TO SOUTH
4	57.55300000	21.95500000	3.131	0.293	TO EAST
5	57.55300000	21.75500000	2.538	-0.053	TO WEST

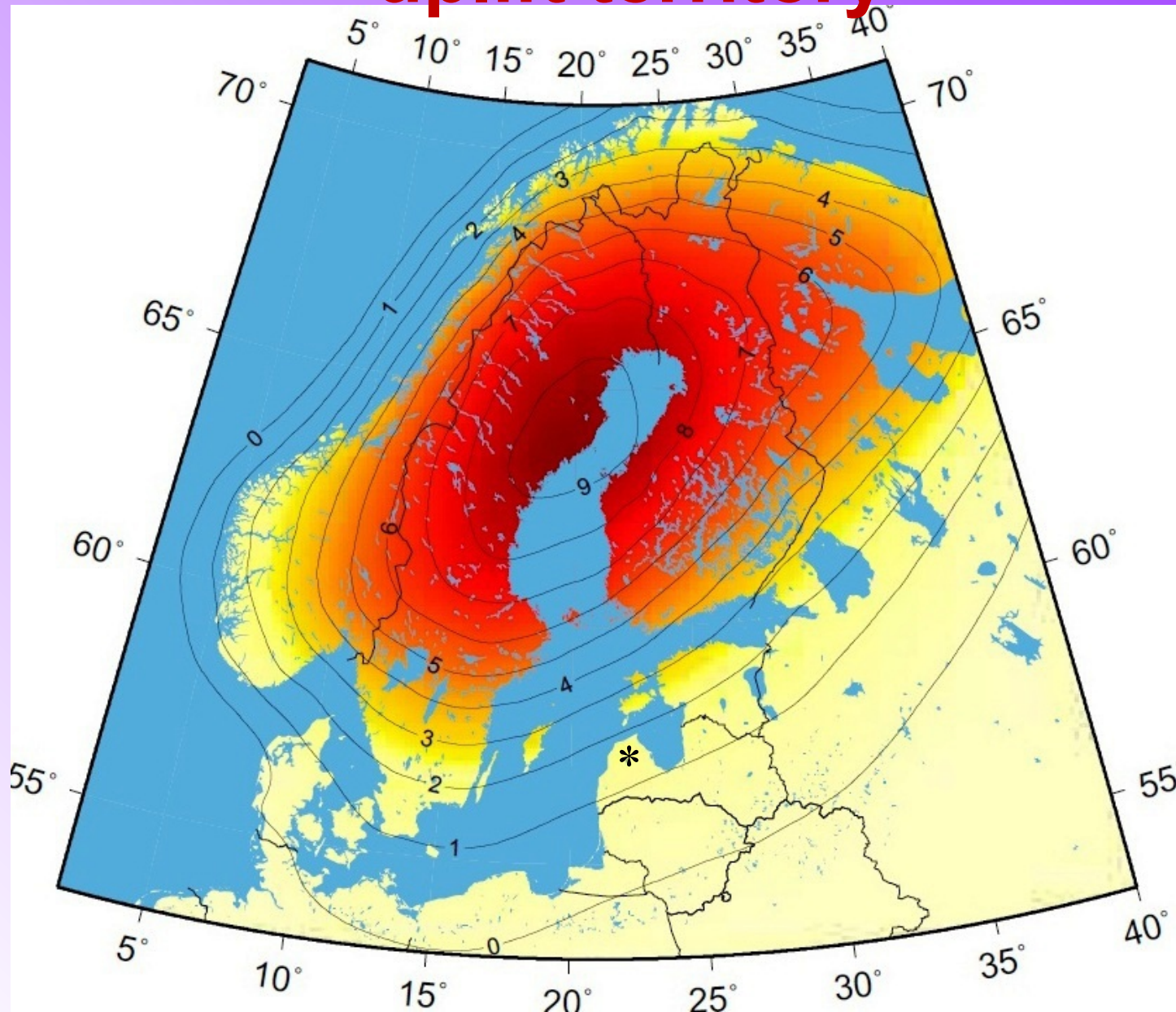
Typically Deflections of Vertical <DoV> in the Baltic region
fluctuate from **- 2** to **+ 5** arc seconds;
locally more

Combinations for development or future / together different techniques



Improvements in accuracy

IRBENE located in Fenno-Scandinavian uplift territory





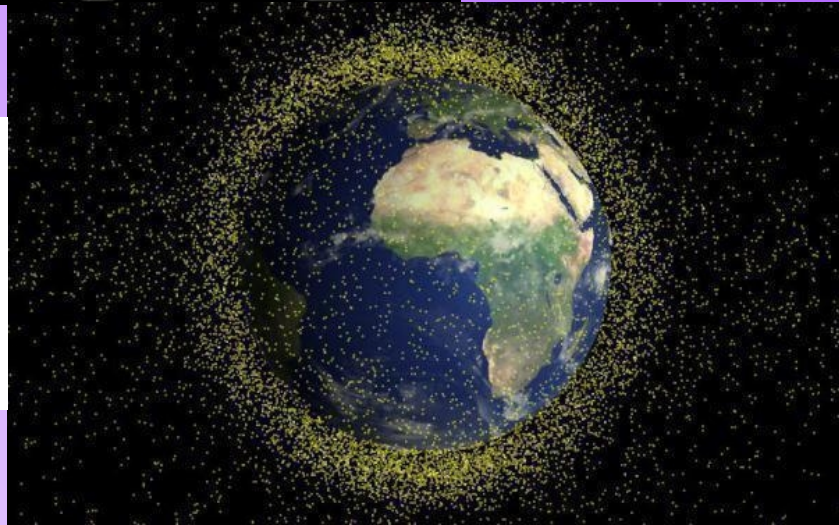
FOTONIKA-LV

GGG

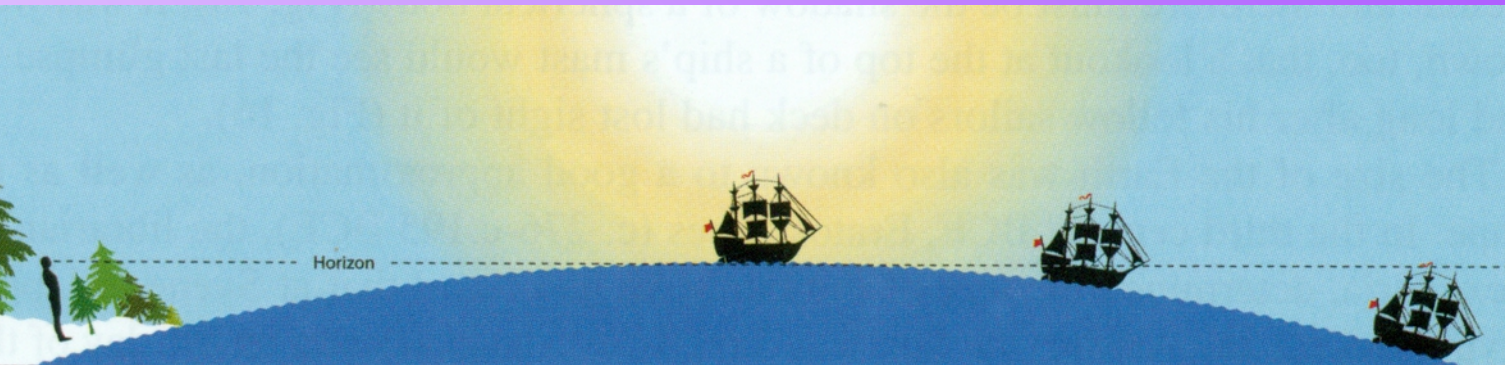
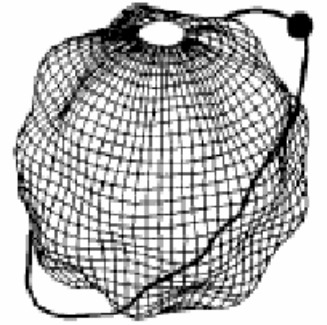


ASI

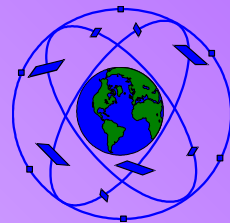
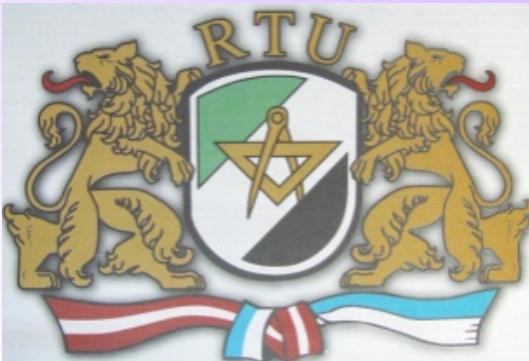
LATVIJAS UNIVERSITĀTES ZINĀTNISKO INSTITŪTU ASOCIĀCIJA



Questions?



Thank You for attention!



<http://www.lu.lv/ggi/eng/>