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swisstopo

## GNSS and Tachymetry for Monitoring the stability of Permanent Reference Station

## **Example Zimmerwald**

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## Campaign details

- Dates:14. 25. June 2013
- Temperatures: 5-30 °C



25-06

27-06

sunny

21-06

23-06

19-06

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15-06

17-06

30

25

20

10

5

0

13-06

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### D **Automatic measurements using (parts** of) Leica GeoMoS



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## Terrestrial: absolute versus relative



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## Terrestrial results ZIMM+ZIM2: Height

Top

### Differential: Top – Reference point-



dHeight= f (Temp) -> extension coefficient of steel 11.8e<sup>-6</sup>K<sup>-1</sup>: dT 10 °C -> dh 1.2 mm

## Differential to bottom point Terrestrial results ZIM2: Horizontally



#### Differential to bottom point

--ZIM2

TIM2.P2

←ZIM2.P1

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## Terrestrial results ZIMM+ZIM2: Horizontally, June 17



### Terrestrial results ZIMM+ZIM2: max. horizontal movements 2 hot days



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#### U **GNSS** Analysis

- ZIMM, ZIM2, ZIMJ nested in 3 AGNES stations
- ZIM3=Galileo receiver at ZIM2 antenna
- L1 short baselines
- 2 weeks (June 11-25; DOY 162 176)
- No troposphere estimation for short baselines





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(identical

# Zero baseline: Hot day June 19 Kinematic coordinates: ZIM2-ZIM3

Kinematic repeatability (S) for ZIM2 14001M008 - ZIM3 14001M008 ( 0.0 km)



## Real baseline GNSS: Hot day June 19 Kinematic coordinates: ZIM2-ZIMJ

Kinematic repeatability (S) for ZIMJ 14001M006 - ZIM2 14001M008 ( 0.0 km)



# Real baseline GPS: Hot day June 19 Kinematic coordinates: ZIMM-ZIMJ

Kinematic repeatability (S) for ZIMJ 14001M006 - ZIMM 14001M004 ( 0.0 km)



## Repeatability kinematic coordinates

- Example day June 19 (hot day)
- Horizontal repeatability 2 mm enough?
  - GNSS: less noise some signals visible (temperature movements?)
  - GPS: more noise difficult to see signals







## Comparison GNSS with terrestrial ground truth: ZIMM/ZIM2 June 19



## PPP solutions

 Absolute station monitoring – no reference station – no baselines! – results in ITRF2008!

PPP solutions:

- CODE: GNSS with 30 second clocks, every 5 min. CRD
- swisstopo: GPS with 30 second clocks, every 30 sec. CRD

## All solutions: ZIM2 June 19

ZIM2 North 19.06.2013



ZIM2 East 19.06.2013



## All solutions: ZIM2 June 19

Common mode residuals for PPP !

GNSS slightly less epoch-to-epoch noise

ZIM2 North 19.06.2013



ZIM2 East 19.06.2013



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## Conclusions

- 9-Meter mast movements of peak-to-peak
  - 8 mm horizontally during hot, sunny days
  - 2 mm vertically (temperature depended dT)
  - Terrestrial estimation precision of ~0.2 mm!
- Daily mean horizontal positions + night observations are not biased -> local tie measurements under cloudy condition
- GNSS not able to reliably measure these horizontal movements
  - GNSS kinematic baselines L1
    - Std of 2 mm horizontally, but not precise enough
    - GNSS kin. results less noise compared to GPS-only
  - PPP kinematic solutions GNSS+GPS
    - Std of 10 mm horizontally
    - Attractive for larger movements (>5 cm) without reference stations

Thank you for your attention!

E.