

Research Institute of Geodesy, Topography, and Cartography – Geodetic Observatory Pecny Land Survey Office, Prague



EUREF Related Activities in the Czech Republic 2011 - 2012 National Report

J. Šimek¹, J. Douša¹, V. Filler¹, J. Kostelecký jr.¹, J. Kostelecký¹ M. Lederer², J. Nágl², J. Řezníček²

¹ Research Institute of Geodesy, Topography and Cartography ² Land Survey Office, Prague

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National reference system: S-JTSK/05

- •ETRF2000 implemented in the CZEPOS positioning system on January 1st, 2011
- •New national S-JTSK/05 system based on ETRF2000 available to users since January 1st, 2011, still not mandatory!
- •S-JTSK/05: composed projected coordinate reference system (ISO 19111) ETRS89 coordinates, planar coordinates (conformal oblique conical projection of the Bessel ellipsoid, normal heights Balt after adjustment
- Conversion between S-JTSK/05 and mandatory S-JTSK by means of correction tables computed for 2 x 2 km grid; improvements in border zones in 2011 2012 → rms difference 2 cm
 Conversion of heights by the CR 2005 quasigeoid model (1'x 1.5
- 'grid fitted to 1,024 GPS/levelling heights)

Permanent GNSS Stations and Networks in the Czech Republic

- Fundamental Geodetic Observatory Pecný GOPE, http://www.pecny.cz (IGS, EPN, CZEPOS, VESOG, E-GVAP II)
- CZEPOS: http://czepos.cuzk.cz, Czech Positioning System, **28 PS**, operated by the Land Survey Office + **27 PS** of neighbour countries
- GEONAS: http://geonas.irsm.asc.cz, 19 PS, experimental monitoring network operated by the Institute of Rock Structure and Mechanics, Acad. Sci. CR
- VESOG: http://pecny.asu.cas.cz/vesog/, research and experimental GNSS network operated by the RIGTC GOP and academic institutions, 8 PS
- TopNet: http://www.geodis.cz, 23 PS, includes also 11 GEONAS and 3 VESOG PS, operated by the private company GEODIS Brno
- Trimble VRS NOW Czech: http://www.geotronics.vrsnow, 24 sites + 8 sites of Trimble VRS NOW Deutschland, operated by Geotronics Praha, s.r.o. private company
- several smaller networks, operated by private companies, e.g. *byS@T* and others
- Total: 98 permanent stations, 12 of them EPN

Permanent GNSS networks in the CR (2)



Fundamental Geodetic Observatory Pecný (GOPE) – RIGTC at Ondřejov









GOPE – Fundamental GNSS Station

- Established in 1993, since 1995 has been contributing to IGS (International GNSS Service)
- Topcon Net-G3 receiver, Topcon CR-G3 antenna with a spherical radom TPSH, individual PC calibration
- Tracking the following GNSS: GPS NAVSTAR (L1C, L1P, L2P, L2C), GLONASS (L1C, L2P)
- Post-processing data + real-time data
- Post-processing data downloaded in RINEX 2.10 format in daily files with 30 sec sampling rate, hourly files/ 1 and 30 sec, 15-min files/ 1 sec
- Data are forwarded to the following data centers:
- GOP RIGTC, Czech Republic (hourly and daily 30 sec data)
- BKG, Frankfurt am Main, Germany (hourly and daily 30 sec data)
- OLG, Graz, Austria (hourly and daily 30 sec data)
- CZEPOS, Land Survey Office, Czech Republic (hourly 1 sec data)
- CDDIS, NASA, U.S.A. (15-minute 1 sec data)
- Real-time RTCM 2.3 and RTCM 3 data streams forwarded in NTRIP protocol to VESOG caster and further to BKG and CZEPOS casters

Permanent GNSS station GOPE



Topcon CR-G3 antenna with TPSH radom

Topcon Net-G3 receiver

GOPE Participation in the M-GEX IGS project

- station GOP6 excentric site of the main GOPE station in the Multi-GNSS Experiment
- Leica GRX1200+GNSS receiver + Leica AR25.R4 antenna with a spherical radom LEIT and individual PC calibrations
- Satellite tracking: GPS NAVSTAR (L1C, L1P, L2P, L2C, L5), GLONASS (L1C, L2P), Galileo (E1, E5a, E5b, AltBoc), SBAS (L1)
- Post-processing data in RINEX 2.10 (directly generated by the receiver) and RINEX 3.01 (conversion from 2.11 using own software in the operation centre):
- hourly and daily files/ 30 sec data
- 15 min files of 1 sec data
- Post-processing data forwarded to:
- CDDIS, NASA, USA (only RINEX 3.01)
- BKG, Frankfurt am Main, Germany (only RINEX 3.01)
- IGN, Paris, France(RINEX 2.10 and 3.01)
- GOP, RIGTC, Czech Republic (only RINEX 2.10)
- Real-time data streams
- binary data Leica LB2
- RTCM 2.3 a RTCM 3
- NTRIP protocol forwarded to NTRIPcaster VESOG/GOP, RIGTC, Czech Republic, binary data LB2 forwarded to the M-GEX caster of the BKG, Frankfurt/Main, Germany

GOP6 M-GEX Site - antenna





GOPE Participation in the JAXA MGM Project

- MGM (Multi-GNSS Monitoring network) Project organized by the Japan Aerospace Agency JAXA – GOPE participates as a hosting station operating a receiver provided on loan by JAXA
- Javad DELTA-G3T receiver is connected through a signal splitter to the Leica AR25.R4 antenna with a spherical radom LEIT installed at the GOP6 site
- Satellite tracking:
- GPS NAVSTAR (L1C, L1P, L2P, L2C, L5)
- GLONASS (L1C, L1P, L2P, L2C)
- Galileo (E1, E5)
- SBAS (L1, L5) including the first QZSS satellite
- Real-time data forwarded to the NTRIP caster of the MGM project in Japan as Javad binary data
- Providing post-processing data generated by the Javad receiver for the M-GEX project under negotiations

GOPE - receivers



Leica GRX1200+GNSS receiver at GOP6 Javad DELTA-G3T receiver at GOP7/GOP6M

CZEPOS – operated by Land Survey Office since 2004/2005



CZEPOS Services



- Real-time services: RTK, RTK-FKP, RTK- PRS, RTK3, VRS3 = 80 Kč (3,26 €) / 1 hour, DGPS = 20 Kč (0,82 €) / 1 hour
- Post-processing: data interval 1 - 4 sec = 80 Kč (3.26 €), 5 - 9 sec = 16 Kč (0.65 €), 10 - 19 sec = 8 Kč (0.33 €), ≥ 20 sec = 4 Kč (0.16 €)

CZEPOS – upgrade schedule



CZEPOS – availability of services



CZEPOS – number of users



Analysis and Research

- Monitoring of permanent sites in the CR
- EPN Data Center GOP
- EPN Analysis Center GOP
- IGS rapid orbits
- GNSS Ground-based meteorology
- Geodynamics EPN velocities, CEGRN
- IDS Analysis Center GOP

Monitoring of the Czech permanent GNSS sites – Analysis Center GOP

- Check of stability and quality
- Rapid solution used as a basis
- EPN processing standards and guidelines
- 8:00 UTC the daily solution compared with coordinates + statistical test
- Limits: 7mm, 7 mm and 15 mm for N,E,U components

Monitoring results for the site CFRM (good) based on ultra-rapid solution



Monitoring results for the site CJIH based on ultra-rapid solution



GNSS data operation/dissemination

GOP operational centre

- GPS, GLONASS, Galileo, QZSS
- hourly, daily, real-time
- 30-sec, high-rate (1Hz)
- EUREF, IGS, VESOG, CZEPOS, ...

GOP Data Centre (EUREF, ..)

 Files – GNSS data (daily, hourly and historical), various supporting products





GPS+GLONASS precise orbit determination

GOP contribution to the International GNSS Service (IGS) – since 2004

software: Bernese GPS sw. V5.0 (GOP modified)

input: hourly GPS data + navigation messages

<u>OUTPUT</u>: ultra-rapid orbits (GPS+GLONASS)

product: 2-day arcs fitting, 1-day arc prediction

<u>USage:</u> (near) real-time applications

processing features:

- LSQ adjustment
- 6-hour update cycle
- double-differenced observations
- efficient strategy with no redundancy
- network split into continental clusters
- self-initializing processing system
- all satellites included, multi-GNSS
- automated manoeuvres detection
- originally developed at GOP



GPS ultra-rapid (GOP) x final orbits (IGS)



GOP orbits/ERP products (milestones) (contribution to the International GNSS Service (IGS) - since 2004

	orbits	clocks	Y,X pole	X,Y pole rates	length of the day
fitted prod.	<5 cm	-	0.1 mas	0.2 mas/day	0.03 ns
predicted prod.	10 cm		0.3 mas	0.3 mas/day	0.07 ns



Terrestrial reference frame realizations

GOP contribution to the EUREF Permanent Network (EPN) – since 1997

- GOP routinely contributes to EUREF RF maintenance and European ITRFxx realization
- GOP supported EPN reprocessing project (since 1996-2008) repro1
- GOP daily & weekly full EUREF network reprocessing (~250 sites) using IGS05 and IGS08 repro1+
- GOP combined full network for the assessment of
 - EUREF ITRF2008 densification,
 - ITRF2008 of EUREF coordinates, velocities and their discontinuities
 - IGS05 x IGS08 PCV model and reference frame (RF)



GOP sub-network re-processing (1996-2008)



stations

GOP reprocessing - raw coordinate time-series

plots of daily-based independent solutions expressed in a single reference frame!



Multi-year combination results

estimation of stations' velocities and coordinates discontinuities





Velocities with respect to Eurasian plate

Based on complete EUREF Permanent network GOP repro1+ solution





Statistics of NRT ZTD product availability [2001-2012]



GOP activities within GPS-meteorology

- COST-716 Action (1998-2003): "Exploitation of Ground-Based GPS for Operational Numerical Weather Prediction and Climate Applications"
 - 15 Institutions, 7 ACs, > 200 GPS sites
 - **TOUGH (2003-2006):** "Targeting Optimal Use of GPS Humidity Measurements in Meteorology"
 - 15 Institutions, 12 ACs, > 400 GPS sites

E-GVAP I (2006 - 2009), E-GVAP II (2010-2012)

"The EUMETNET GPS Water Vapor Programme"

13 Institutions, 12 ACs, > 1600 GPS sites

COST Action (pre-proposal) – March 31, 2012

- "Advanced Global Navigation Satellite Systems tropospheric products for monitoring severe weather events and climate (GNSS4SWEC)"
- interested 37 institutions from 25 countries

Near real-time ZTD solutions by GOP Processing requirements

□ hourly GNSS data and precise IGS ultra/rapid orbits

GOP processing features

- processed every hour in HH:20
- □ 4 hourly data batches and normal equations (NEQ)
- ZTD based on last 12 hours from NEQ combination
- Coordinates based on 28 days from NEQ combination
- processing efficiently distributed in the clusters

GOP ZTD characteristics

- ZTD product (HH:00 HH:59) linear trend model (piece-wise linear function)
- ZTD product filtering:
 - min 4 hours in NRT ZTD solution
 - min 2 days in NRT CRD solution

GOP ZTD solutions (E-GVAP)

- Regional/national (GPS)
- Regional/national (GNSS)
- Global (GPS)





GOP global hourly ZTD 2010-2012



Hourly ZTD comparisons - GOP global solution [2010-2011]





SDEV and BIAS more variable than regional ZTDs, however, still within 3-8 mm and 0-2 mm, respectively



Figures show comparison to UK Met Office global NWM – strong latitude dependence

NRT ZTDs from GPS, GLONASS and multi-GNSS solutions



Using IGS05 APCV model a bias of 0-2 mm observed between stand-alone GPS and GLONASS ZTD solution.

By adopting IGS08 almost disappeared.



ECGN, gravity, geodynamics

- 180 km of levelling lines in the geodynamic network (long-term rms/1 km error 0.60 mm)
- Gravimetric measurements at 2 stations of the geodynamic network, vertical gradients at 3 sites, local gravity network GOP,
- superconducting (OSG-050) and absolute gravimetry (FG5 No. 215) at GOP, environmental effects on gravity
- ICAG at Walferdange, Nov 2011
- Absolute gravity measurements: Slovakia (3 sites), Hungary (6), Czech Republic (3 sites), GGP station Strasbourg (France)
- Repeated absolute gravity measurements at GNSS permanent stations GOPE (12), POL1 (2), KUNZ (2) and ZDIB (3)

Levelling in Fundamental Geodynamical Network in 2011 – Land Survey Office



Tidal Gravimetry at GO Pecný and Environmental Effects

- gravity time series by GWR OSG-050, Askania Gs15 No. 228 and by LCR 137
- calibration by FG5 No. 215 absolute gravimeter
- very broadband 3-D seismometer
- climatological station
- meteorological parameters
- soil moisture
- ground water level









Thank you for your attention !

for more detailed information please visit http://czepos.cuzk.cz http://www.cuzk.cz http://pecny.asu.cas.cz