

*A new mapping function based on GPS Radio Occultation for the ZTD
estimation*

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Content

- *Historic background*
- *Niell mapping function: How it was computed*
- *MF with Radio Occultation observation*
- *Global M.F. with RO*
- *Results*

The Phase Observed by GPS: $\Phi = \rho + c(dt - dT) + \lambda A - \Delta_{ion} + \Delta_{trop} + \varepsilon$

The path of GPS signal from the satellite to the ground receiver is ruled by Fermat Principle:

$$L = \int n \, ds, \quad \Delta_{trop} = \int (n - 1) \, ds = 10^{-6} \int N^{trop} \, ds$$

$$N^{trop} = k_1 \frac{P_d}{T} + k_2 \frac{e}{T} + k_3 \frac{e}{T^2} \quad \text{Refractivity as from Smith \& Weintraub (1953)}$$

P_d =surface pressure (mbar)

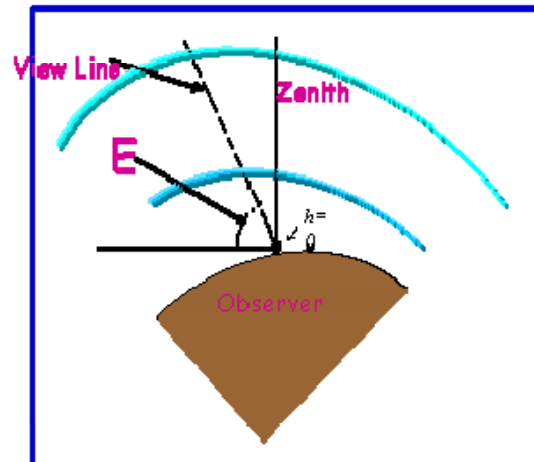
e =wet pressure

T =temperature

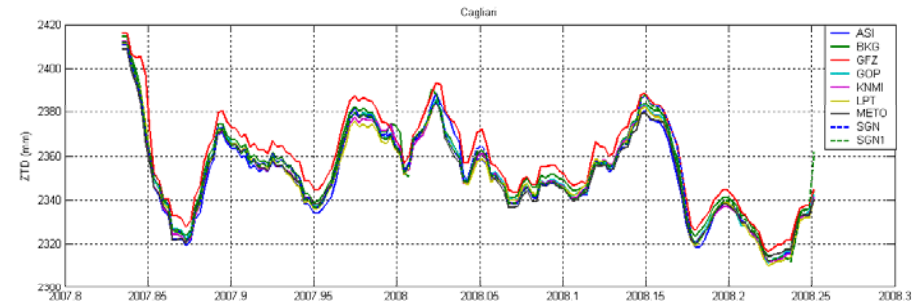
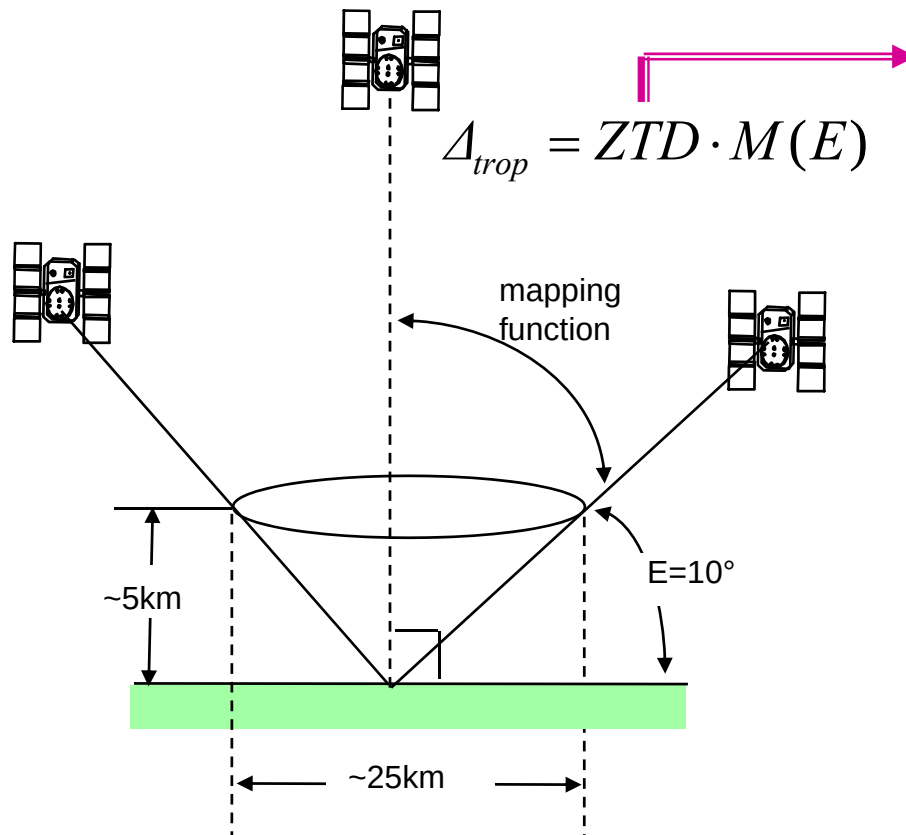
$$\Delta_{trop} = ZTD \cdot M(E) \quad \text{With:}$$

$$M(E)=\text{Mapping Function} \quad ZTD = 10^{-6} \left[\int k_1 \frac{P_d}{T} + k_2 \frac{e}{T} + k_3 \frac{e}{T^2} \, dz \right] = ZHD + ZWD$$

$$\Delta_{trop} = m_1(E)ZHD + m_2(E)ZWD + m_3(E) \cot E [G_N \cos \phi + G_S \sin \phi]$$



Ground-Based GPS Meteorology



Fundamental Measurement

$$L_s = 10^{-6} \int N(s) ds$$

$$N = k_1 \cdot \left(\frac{P_d}{T} \right) + k_2 \cdot \left(\frac{e}{T} \right) + k_3 \cdot \left(\frac{e}{T^2} \right)$$

A mapping function is applied to determine how the signal delay changes with elevation angle.

The results are averaged over all the satellites to give the ZTD.

HOPFIELD Era (1969)

$$N^{trop} = N_d^{trop} + N_w^{trop}$$

$$N_d^{trop}(h) = N_{d,0}^{trop} \left[\frac{h_d - h}{h_d} \right]^4$$

$$N_{d,0}^{trop} = 77.64 \frac{P_0}{T_0}$$

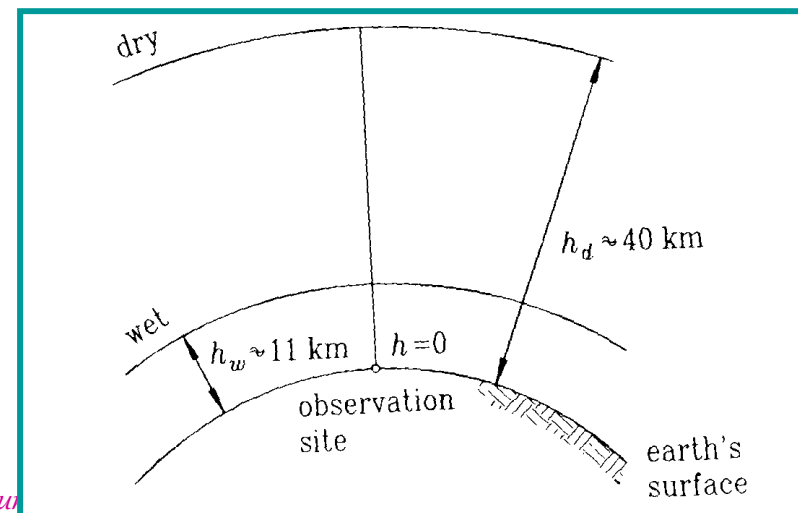
P_0 e T_0 are ground measurement.

$$h_d = 40136 + 148.72(T - 273.16) \quad [m]$$

$$h_w = 11000 \text{ m}$$

$$N_w^{trop}(h) = N_{w,0}^{trop} \left[\frac{h_w - h}{h_w} \right]^4$$

$$N_{w,0}^{trop} = -12.96 \frac{e}{T_0} + 3.718 \cdot 10^5 \frac{e}{T_0^2}$$



Hopfield MF

$$M_d(E) = \frac{1}{\sin(\sqrt{E^2 + 6.25})}$$

$$M_w(E) = \frac{1}{\sin(\sqrt{E^2 + 2.25})}$$

Saastamoinen Era (1973)

$$\Delta_{trop} = \frac{0.002277}{\cos(z)} \left[p + \left(\frac{1255}{T} + 0.05 \right) e - B(h) \cdot \tan^2(z) \right] + \delta R(z, h)$$

z= zenith angle (90-E)

P=Pressure

T=Temperature

e=wet pressure

B=tabled pressure correction

$\delta R(z,h)$ =tabled delay corrections

Mapping Function Marini-Murray like (1972)

$$m(E) = \frac{1}{\sin E + \frac{a}{\sin E + \frac{b}{\sin E + \frac{c}{\sin E + \dots}}}}$$

$$\Delta^{trop} = ZHD \cdot M_d(E) + ZWD \cdot M_w(E)$$

Mapping Function
Marini-Murray like (1972)

Herring (1992)

$$a_d = [1.2320 + 0.0139 \cos \varphi - 0.0209h + 0.00215(T - 283)] \cdot 10^{-3};$$

$$b_d = [3.1612 - 0.1600 \cos \varphi - 0.0331h + 0.00206(T - 283)] \cdot 10^{-3};$$

$$c_d = [71.244 - 4.293 \cos \varphi - 0.149h - 0.0021(T - 283)] \cdot 10^{-3}.$$

$$a_w = [0.583 - 0.011 \cos \varphi - 0.052h + 0.0014(T - 283)] \cdot 10^{-3};$$

$$b_w = [1.402 - 0.102 \cos \varphi - 0.101h + 0.0020(T - 283)] \cdot 10^{-3};$$

$$c_w = [45.85 - 1.91 \cos \varphi - 0.29h + 0.015(T - 283)] \cdot 10^{-3}.$$

Parameters involved:

latitude “ φ ”

Height “ h ”

Surface Temperature T

Niell (1996)

$$m(\varepsilon) = \frac{1 + \frac{a}{b}}{1 + \frac{c}{a}} \cdot \frac{1}{\sin(\varepsilon) + \frac{b}{\sin(\varepsilon) + c}} + \left(\frac{1}{\sin(\varepsilon)} - \frac{1 + \frac{a_h}{b_h}}{1 + \frac{c_h}{a_h}} \cdot \frac{1}{\sin(\varepsilon) + \frac{b_h}{\sin(\varepsilon) + c_h}} \right) \cdot h$$

$$a(\lambda_i, t) = a_{avg}(\lambda_i) - a_{amp}(\lambda_i) \cos\left(2\pi \frac{t - T_0}{365.25}\right)$$

$$m_{wet}(E) = \frac{1 + \frac{a_{wet}}{b_{wet}}}{1 + \frac{c_{wet}}{a_{wet}}} \cdot \frac{1}{\sin(E) + \frac{b_{wet}}{\sin(E) + \frac{a_{wet}}{b_{wet}}}}$$

An equivalent formulation is given for the wet MF

We are using just the same formulation of Niell but
Using Radio Occultation Data !!

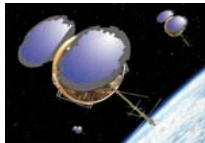
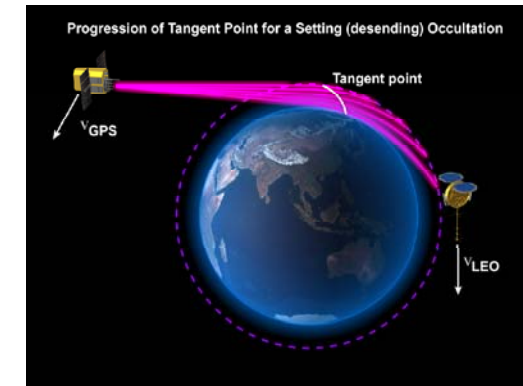
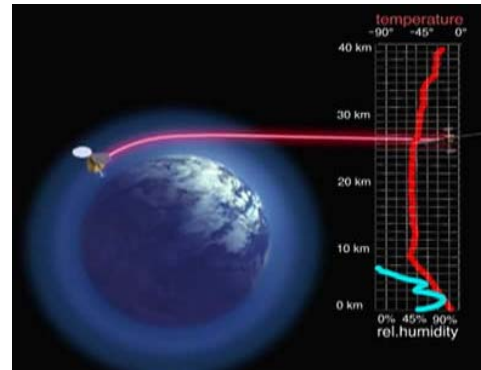
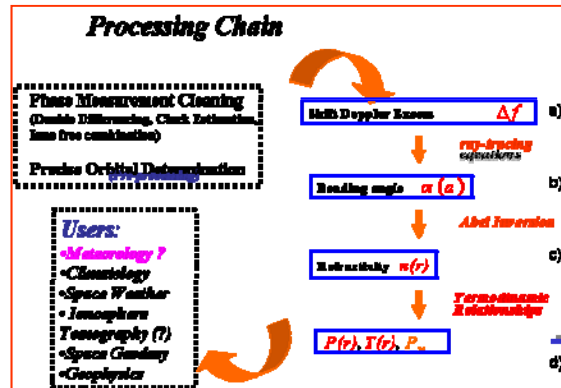
Parameters involved:

latitude " φ "

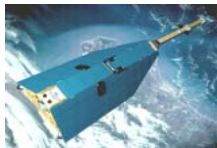
Height " h "

DoY " t "

**For the computation of the coefficients
RAOB data were used**



COSMIC 6 satellites in orbit since 14 April 2006 (~2000 occ/day).
Still active



CHAMP launched on July 2000 (~200 occ/day). Still active

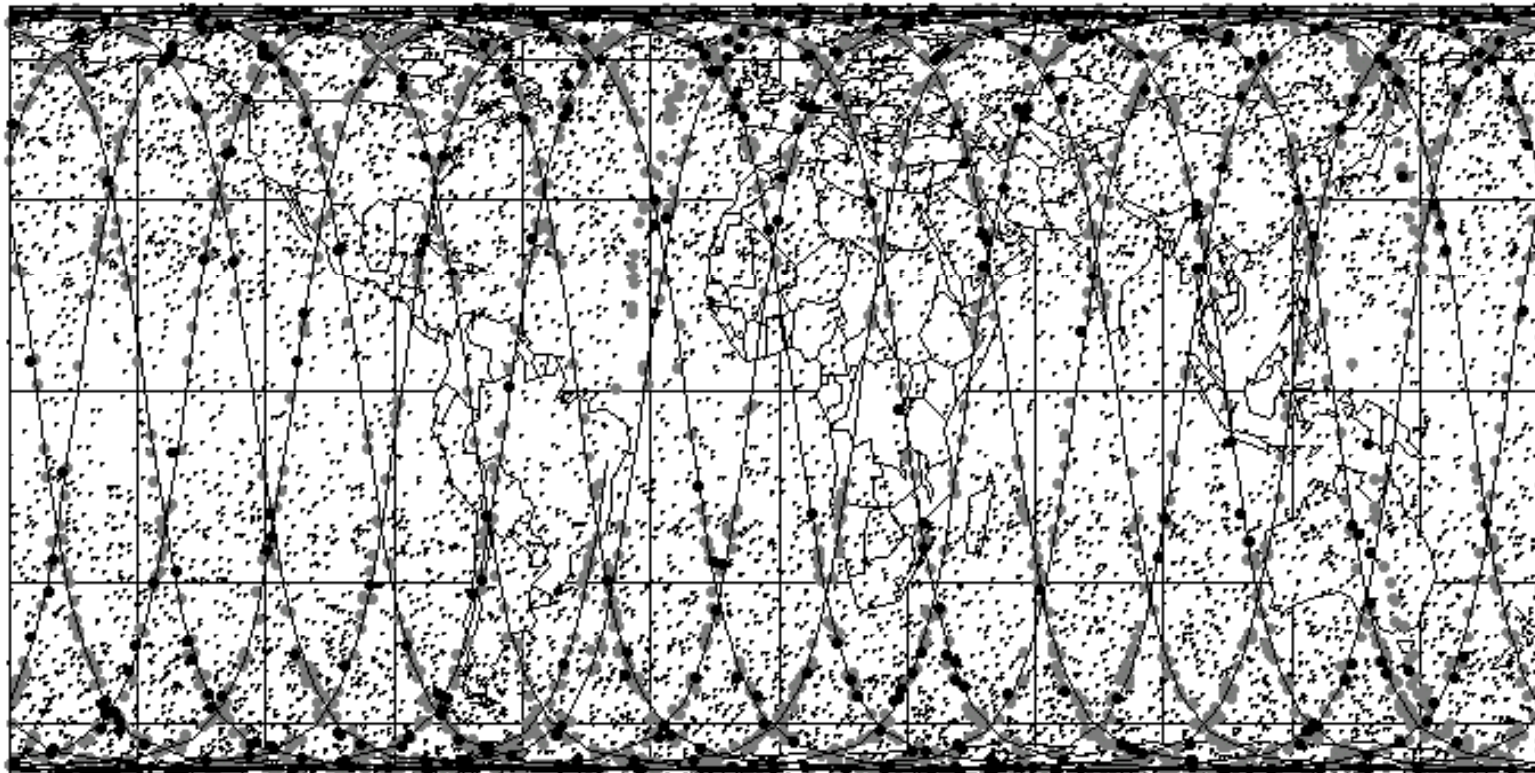


SAC-C launched on November 2000 (one year only of data)

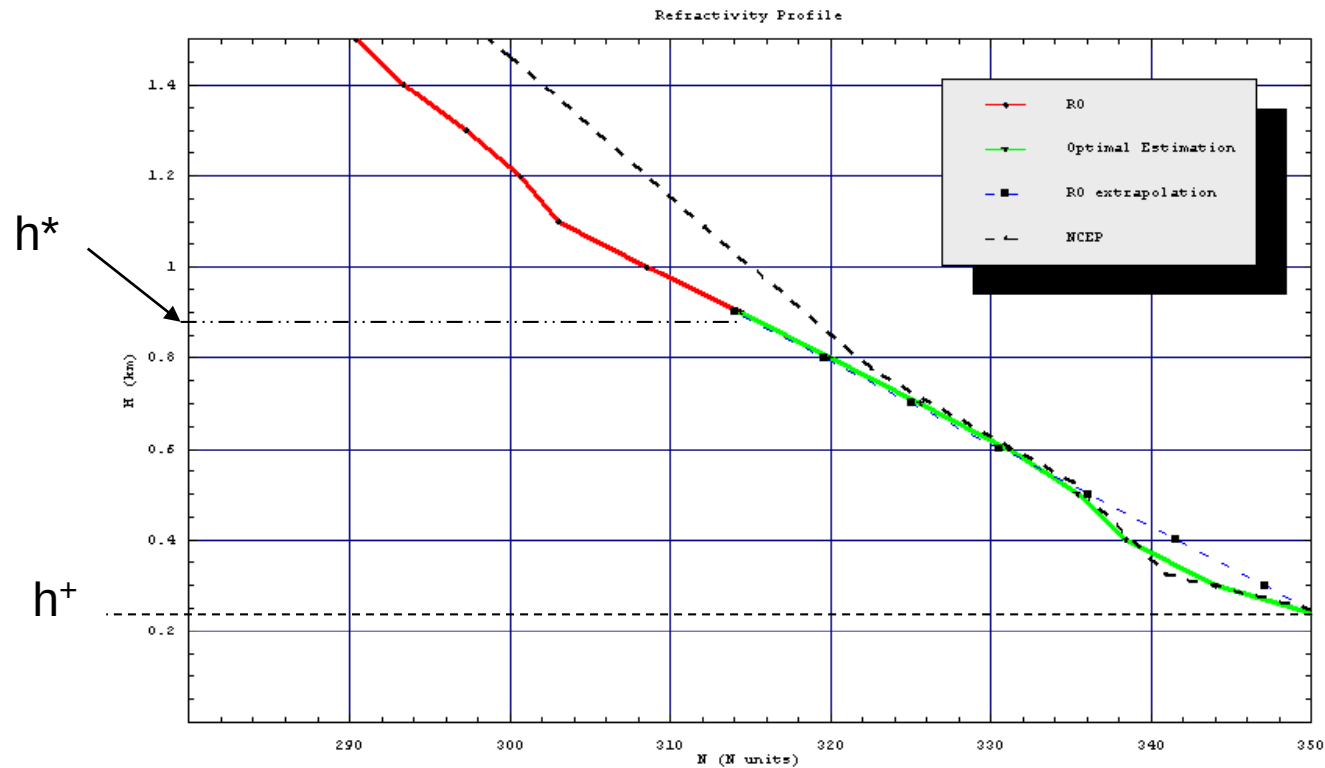
150.000 RO events selected !!

Spreaded and organized according the day of the year acquired. The selected events must provide profiles down at an height $h < 1$ km over the ground at least

COSMIC
CHAMP
SAC-C
METOP
GRACE
OCEANSAT₂



RO vs NCEP merging



$$N(h) = k(h) \cdot N(h)_{ER} + (1 - k(h)) \cdot N(h)_{NCEP}$$

$K(h^*)=1$ lowest layer of RO data

$K(h^+)=0$ lowest layer of NCEP data

Estimation of Total Delay (TD)

The tropospheric delay TD is given by the difference between the optical path of the signal (L) and the geometrical distance satellite-receiver (L_0):

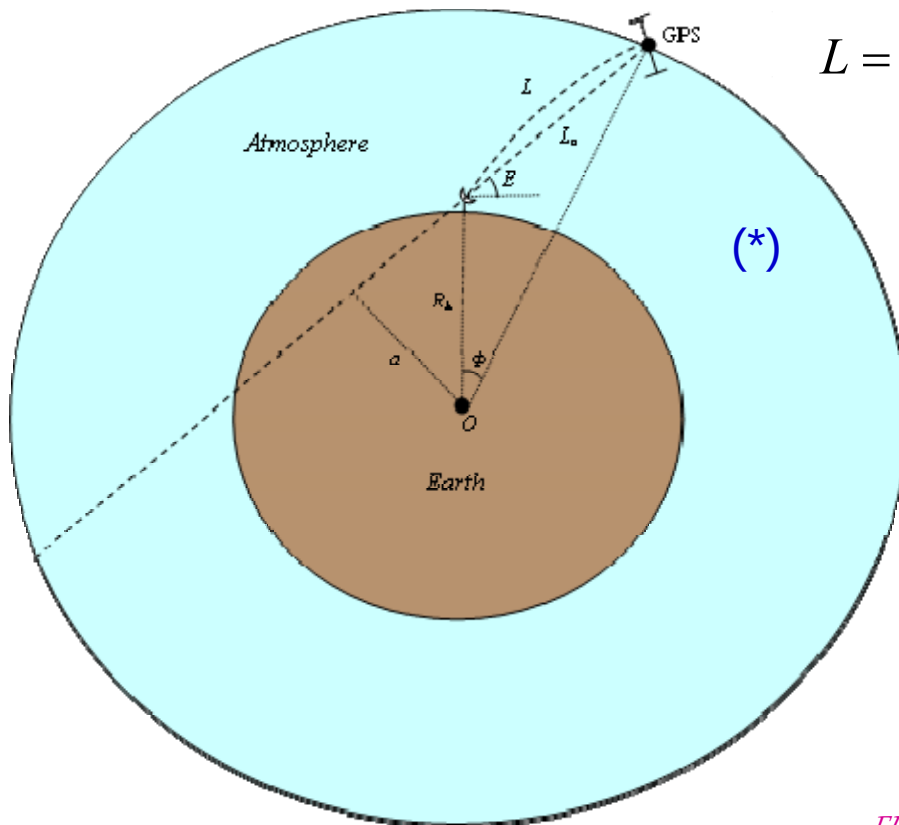
$$L = \int_{R_E + h_{topo}}^{R_E + h_{atm}} \frac{n^2(r) \cdot r}{\sqrt{n^2(r) \cdot r^2 - a^2}} dr \quad a = R_E \cdot \cos(E)$$

$$L_0 = \int_{R_E + h_{topo}}^{R_E + h_{atm}} \frac{dr}{\sin(E)} = \frac{h_{atm} - h_{topo}}{\sin(E)}$$

where:

$$TD = \Delta L = L - L_0$$

- the refractive index $n(r)$ is provided by RO data or by models (NCEP, ECMWF) ;
- the impact parameter a is related to the satellite and receiver position.



Estimation of the MF parameters

$$m(E) = \frac{L - L_0}{ZTD}$$

$$L = \int_{R_E+h}^{R_E+h_{atm}} \frac{n^2(r) \cdot r}{\sqrt{n^2(r) \cdot r^2 - a^2}} dr$$

$$L_0 = \int_{R_E+h}^{R_E+h_{atm}} \frac{dr}{\sin(E)} = \frac{h_{atm} - h}{\sin(E)}$$

$$ZTD = 10^{-6} \int_{R_E+h}^{R_E+h_{atm}} N(r) dr$$

$$\text{Min} \left\| M(E, \lambda_i, h_j, t_k, \mathbf{P}(\lambda_i, t_k)) - \frac{L(E, \lambda_i, h_j, t_k) - L_0(E, \lambda_i, h_j, t_k)}{ZTD(E, \lambda_i, h_j, t_k)} \right\|$$

Where

$$\mathbf{P}(\lambda_i, t_k) = (a(\lambda_i, t_k), b(\lambda_i, t_k), c(\lambda_i, t_k), a_h(\lambda_i, t_k), b_h(\lambda_i, t_k), c_h(\lambda_i, t_k))$$

i stands for the i^{th} longitude
j “ “ “ j^{th} height
k “ “ “ k^{th} epoch

Estimation of the MF Parameters (2)

Latitude Gridding Longitude Gridding	15° (12 groups) 30° (12 groups)
Number of epochs of the year	8 (45 days)
Layers selected to estimate a_h , b_h , c_h	Up to 2000 meters with steps of 400 meters starting from sea level. About 150 different Elevation Angle have been selected for fitting.

Our parameters are not exactly the same as appear in Niell MF. So we apply the following relationship to have uniform parametrization (important for the processing):

$$a_{avg}(\lambda_i) = \overline{a(\lambda_i, t)}_{Time}$$

$$a(\lambda_i, t) = a_{avg}(\lambda_i) - a_{amp}(\lambda_i) \cos\left(2\pi \frac{t - T_0}{365.25}\right)$$

$$a_h = \overline{a_h(\lambda_i, h_j, t_k)}_{\lambda, H, T}$$

$$\left(\frac{1}{\sin(s)} - \frac{1 + \frac{a_h}{b_h}}{\sin(s) + \frac{a_h}{1 + c_h}} \right) \cdot h$$

While $a_{amp}(\lambda)$ and T_0 are estimated fitting the residuals: $[a(\lambda_i, t_k) - a_{avg}(\lambda_i)]$ with:

Fit the computed coefficients in terms of an harmonic expansion truncated at 8°:

$$a(\varphi, \lambda, t) = \sum_{n=0}^{n=8} \sum_{m=0}^n P_{nm} \sin(\varphi) \cdot (C(t)_{nm} \cos(\lambda) + S(t)_{nm} \sin(\lambda))$$

$$b(\varphi, \lambda, t) = \dots\dots$$

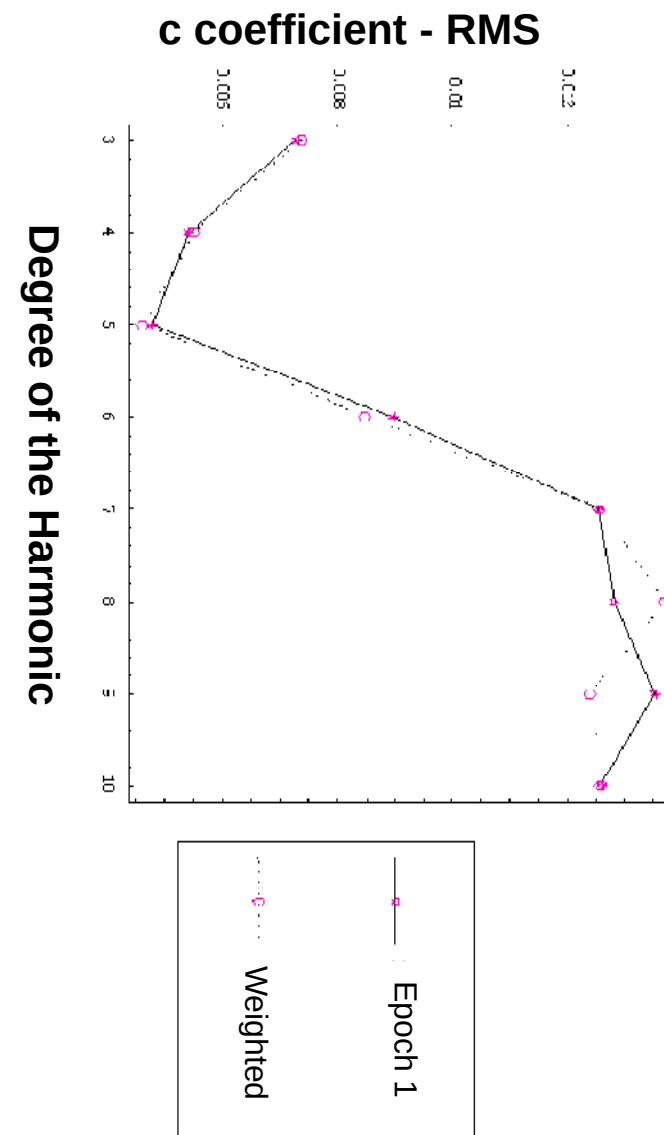
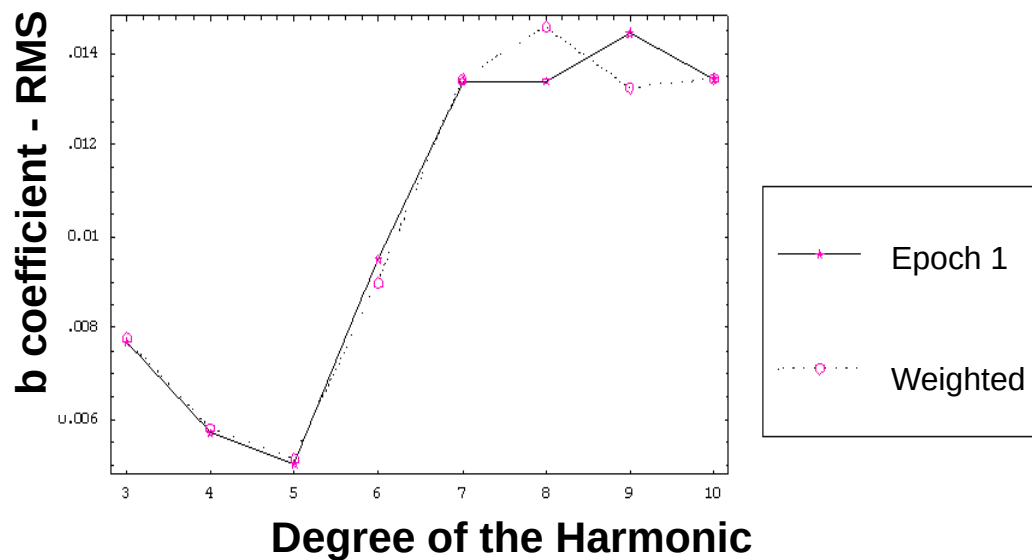
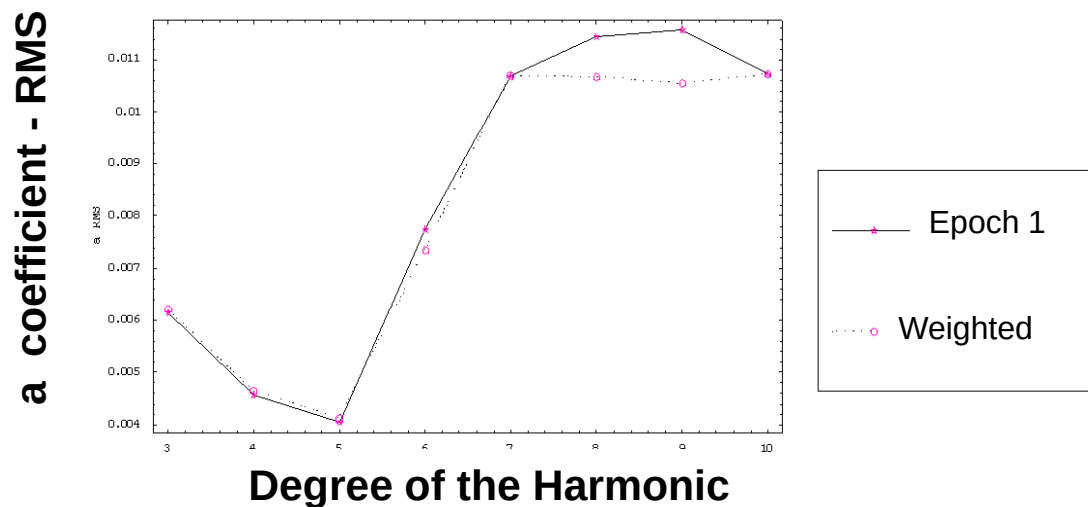
$$c(\varphi, \lambda, t) = \dots\dots$$

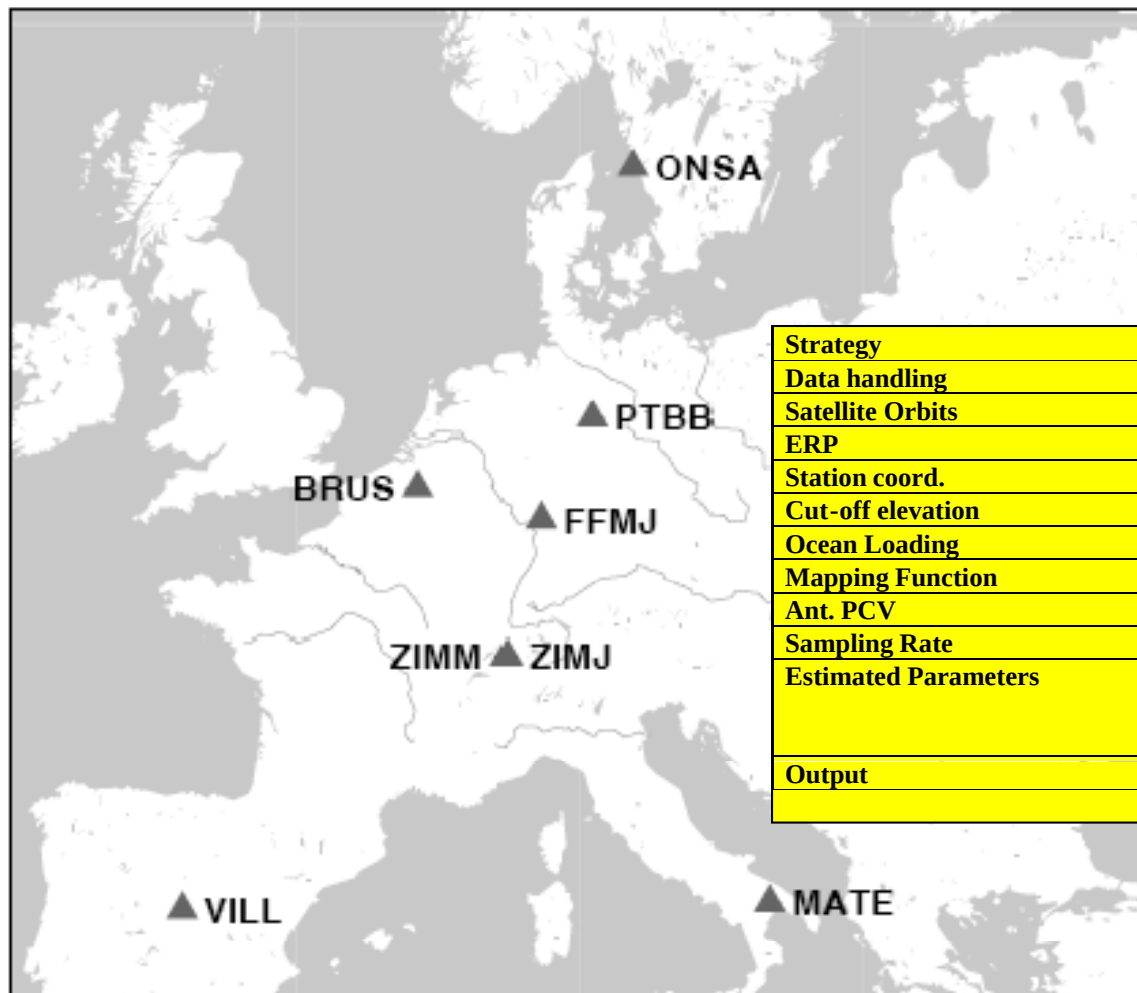
This is the same approach applied by Boehm et al. 2006 using Numerical Weather Models for the construction of a GMF:

Boehm, J.; Niell, A.; Tregoning, P.; Schuh, H. 2006, "Global Mapping Function (GMF): A new empirical mapping function based on numerical weather model data," Geophysical Research Letters, 33: L07304, doi:10.1029/2005GL025546.

Best Solution: 5th Degree

The Optimal Degree of the Harmonics

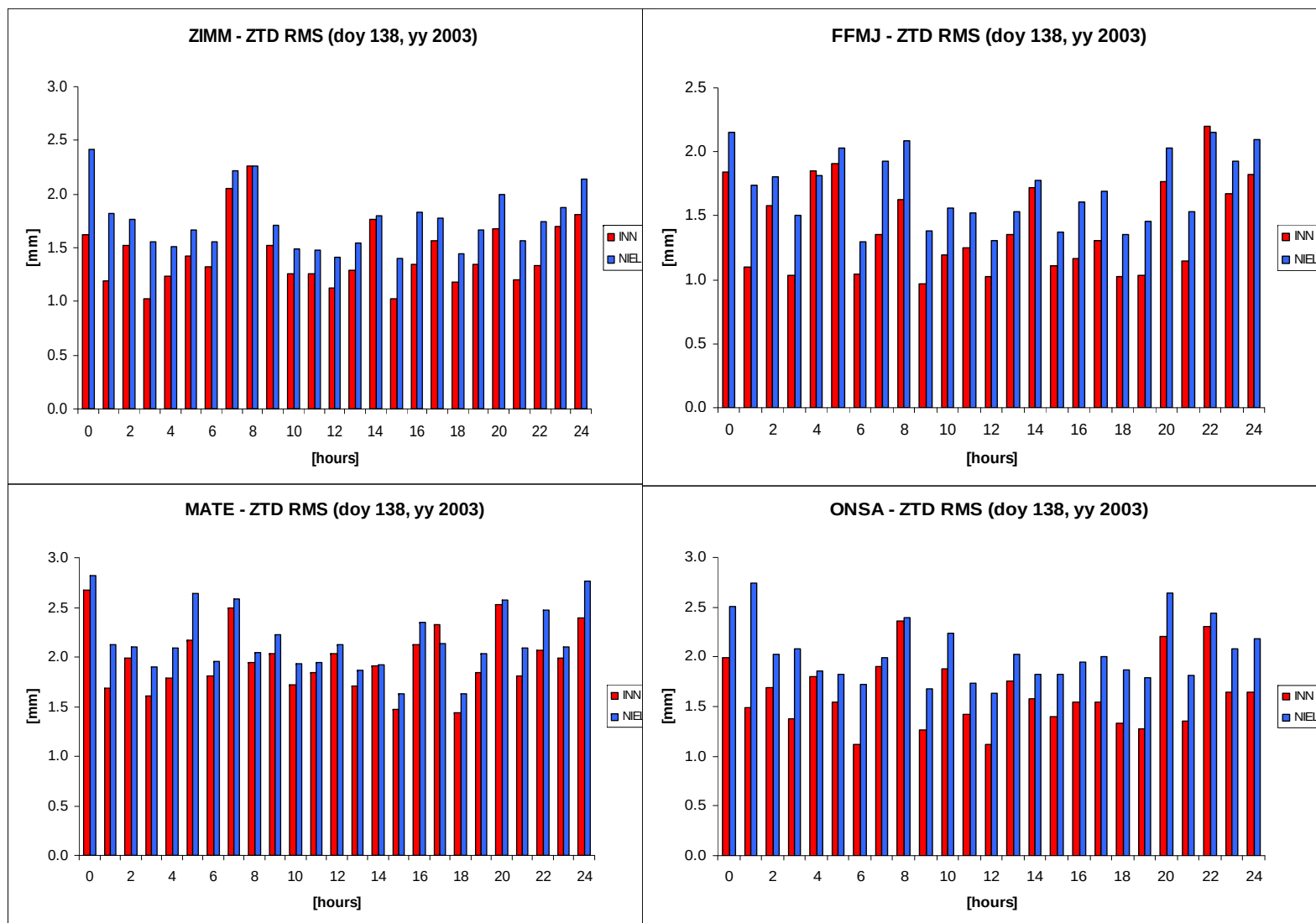




Processing Strategy (BERNESE SW used)

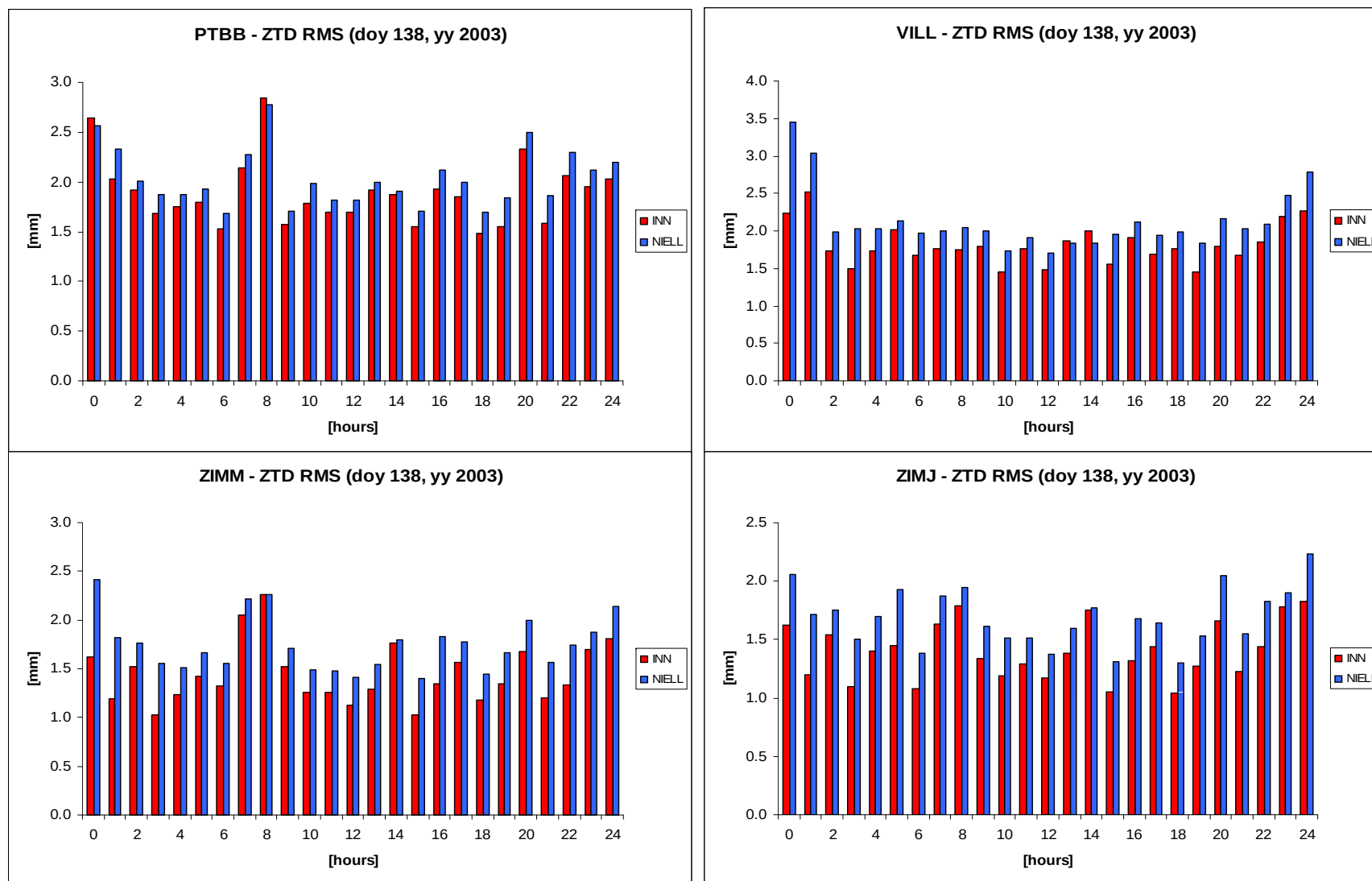
Strategy	Network Adjustment
Data handling	1 week of Data of 8 Perm. GPS Stations
Satellite Orbits	IGS Precise
ERP	IERS-IGS
Station coord.	aligned to IGS00
Cut-off elevation	5°
Ocean Loading	Applied (H.G.Scherneck)
Mapping Function	Neill (1996), INN (2008)
Ant. PCV	Relative
Sampling Rate	30"
Estimated Parameters	Coordinates, Satellite & station clocks w.r.t a reference one, Phase ambiguities (float), ZTD time resolution: every hour
Output	Coordinates, ZTD

ZTD Results



Results₂

Improvements up to ~20%



Conclusions

- *A huge amount of data are coming from RO Observations: (COSMIC, SAC-C, CHAMP, METOP, GRACE and Next OCEANSAT 2 mission)*
- *We have replaced RAOB with RO data to construct the Niell MF*
- *The new parameters organized in Niell MF fashion have been applied to a small network achieving encouraging improvements on ZTD estimation but not in the coordinates (?)*
- *A better choose of the network to test the new MF (?)*
- *A wide and extensive validation activity must be performed comparing our MF not only with NMF but also with GMF Vienna Mapping Function achieved by using Numerical Weather Models as well as against other kind of MF*