



# CENTIMETRE LEVEL OF ACCURACY OF QUASIGEOID MODEL IN POLAND

### Jan Krynski

Institute of Geodesy and Cartography, Poland krynski@igik.edu.pl

### Adam Lyszkowicz

University of Warmia and Mazury in Olsztyn, Poland adaml@moskit.uwm.edu.pl



Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006

uropean Reference Frame – EUREF 20 Riga, Latvia, 14-17 June 2006













Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006

Riga, Latvia, 14-17 June 2006





## Introduction



Geoid/quasigeoid models in Poland

- 1949 first gravimetric geoid model for the region of Central Europe, including Poland (accuracy ~3 m)
- 1962 first astro-geodetic geoid for Poland (accuracy 60 cm)
- 1970 first astro-gravimetric geoid for Poland (accuracy 30 cm)
- 1993 first gravimetric quasigeoid model for Poland, using the LS collocation combined with the integral method (accuracy 10 cm)
- 1997 gravimetric quasigeoid model for Poland, using the FFT technique (accuracy 5 cm)

need for centimetre quasigeoid in Poland

2002-2005 - extensive research on precise geoid/quasigeoid model in Poland with the use of all available geodetic,

gravimetric, astronomic, satellite and geological data





## Data used (1)







 1999-2002 levelling campaign: 382 levelling lines (total length 17 516 km, average length ~46 km) 16 150 sections (average length 1.1 km), 135 loops, 245 nodal points
 rms of lev. ±0.278 mm/km<sup>1/2</sup>, rand. error ±0.264 mm/km<sup>1/2</sup>, syst. error ±0.080 mm/km, σ of unit weight to ±0.088 mm/km



Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006

Riga, Latvia, 14-17 June 2006





## Data used (2)



### digital terrain models

DTM	Resolution ["]	Vertical acc. [m]	Horizontal acc. [m]
DTED2	1 × 1 1 × 2	2-7	15
SRTM3	3 × 3	16	20
SRTM30	30 × 30		



### tide gauge data

25 tide gauges from Danish, Finnish, German, Polish and Swedish coast line (monthly and annual means from at least 50 years)



### lithosphere density data

- points of evaluated lithosphere density above the sea level (1363; 1/230 km<sup>2</sup>)
- map of lithosphere density above the sea level (range 1.71- 2.76 gcm<sup>-3</sup>) mean = 2.17 gcm<sup>-3</sup>; σ = 0.15 gcm<sup>-3</sup>







Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006 Riga, Latvia, 14-17 June 2006





## **Geopotential models**



Model	Degree	Туре
EGM96	360	combined
EIGEN-CH03S	140	satellite only
GGM01S	120	satellite only
GGM02S (140)	160	satellite only
GGM02C	200	combined
GGM02S/EGM96	360	combined

### GM vs POLREF [m]

Model	Mean	Std dev.	Min	Max
EGM96	-0.53	0.19	-1.03	0.08
EIGEN-CH03S	-0.33	0.76	-2.22	1.06
GGM01S	-0.36	0.46	-1.70	1.05
GGM02S (140)	-0.34	0.47	-1.53	1.23
GGM02C	-0.35	0.26	-1.09	0.49
GGM02S/EGM96	-0.37	0.13	-0.79	0.05



### GM vs ∆g [mgal]

Model	Mean	Std dev.	Min	Max
EGM96	-0.18	9.39	-112.01	137.34
EIGEN-CH03S	0.00	17.30	-111.42	182.54
GGM01S	0.26	15.37	-109.94	166.07
GGM02S (140)	-0.14	14.81	111.89	157.57
GGM02C	-0.20	12.44	-115.57	153.86
GGM02S/EGM96	-0.30	9.31	-115.56	135.44





Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006 Riga, Latvia, 14-17 June 2006







atitude [degrees]

Map of calculated "2005" ter. corr. at 1 078 046 gravity stations [mGal]



The optimum maximum integration radius [km] for different distortions of terrain elevation

correction [mGal]         15 (flat)         50 (hilly)         300 (model)           0.1         14.90         205         118         118	tive to a gravity station [m]	h of terrain e	Distortion Ah of terra	Accuracy of the terrain
0.1         14.90         205           0.2         0.22         118	illy) 300 (mountainous)	at)	15 (flat)	correction [mGal]
0.2 0.22 118	5 280	0	14.90	0.1
	3 265	2	0.22	0.2
0.3 0.06 33	3 249	5	0.06	0.3

## **Differences** between the "1992" and "2005" terrain corrections [mGal]



# Number<br/>of stationsMinMaxMeanStd dev.288 507-8.13510.260-0.0500.616



longitude [degrees]

Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006 Riga, Latvia, 14-17 June 2006

**T** 



## Mean gravity anomalies



- **1.** Point free-air anomalies  $\Delta g_{P'}^F$  on the geoid
- 2. Point Faye anomalies  $\Delta g_{P'}^{Faye}$  on the geoid
- **3.** Point Bouguer anomalies  $\Delta g_{P'}^{B}$

- $\Delta g_{P'}^{F} = g_{P} + \delta g_{P}^{F} \gamma_{P_{0}}$ with  $\delta g_{P}^{F} = 0.3086 \times h_{P}$   $\Delta g_{P'}^{Faye} = \Delta g_{P'}^{F} + c_{P}$   $\Delta g_{P'}^{B} = \Delta g_{P'}^{Faye} 2\pi\rho h_{P}$
- 4. Interpolation of point Bouguer anomalies ( $\Delta g_i^{int}$ ) and terrain elevations ( $h_i^{int}$ ) on the grid of higher resolution then the resultant grid of mean Faye anomalies
- 5. Calculation of mean Bouguer anomalies  $\overline{\Delta g}^{B}$  in 1' × 1' blocks
- 6. Calculation of mean heights  $\overline{h}$  in 1' × 1' blocks
- 7. Calculation of mean Faye anomalies  $\overline{\Delta g}^{Faye}$  in 1' × 1' blocks

**Concept of calculating mean gravity anomalies** 







Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006 Riga, Latvia, 14-17 June 2006





## **Control traverse**



GPS/levelling traverse – stations at the benchmarks of 1<sup>st</sup> and 2<sup>nd</sup> order precise levelling network



### The fit of the heights of the control traverse to the GUGiK 2001 quasigeoid





Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006

Riga, Latvia, 14-17 June 2006





## **Quasigeoid models developed**





### Gravimetric quasigeoid - different models (gravity data, GM, terr. corr)

	Statistics	quasi04a	quasi04b	quasi04c	quasi04d	quasi05a	quasi05b	quasi05c	quasi06a
fitting to the	Mean	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
POLREF sites [cm]	Std dev.	3.2	4.1	3.9	3.6	3.6	3.6	3.7	3.8
	Min	-8.4	-12.0	-10.2	-10.5	-9.2	-9.2	-10.1	-10.3
	Max	10.1	10.8	11.4	10.9	9.0	9.0	9.7	10.1



### GPS/levelling quasigeoid - EUREF-POL, POLREF, EUVN, WSSG (kriging, min. curv.)

nure numerical	Statistics	Mean	Std dev.	Min	Max	with gravity	Statistics	Mean	Std dev.	Min	Max
	$\zeta_{\text{model}} = \zeta_{\text{EUVN}}$	-3.4	4.8	-21.3	10.3		$\zeta_{\text{model}} = \zeta_{\text{EUVN}}$	-3.1	2.9	-12.4	2.1
[cm]	ζmodel - ζwssg	-3.1	5.4	-16.7	21.6	support [cm]	ζ <sub>model</sub> - ζwssg	-3.2	5.5	-25.9	43.8

#### Integrated quasigeoid - GPS/levelling + gravity + terrain model

fitting to the POLREF, EUVN and WSSG sites [cm]

Statistics	Mean	Std dev.	Min	Max
$\zeta_{model} = \zeta_{POLREF}$	0.5	0.7	-1.3	3.0
$\zeta_{model} = \zeta_{EUVN}$	-0.5	0.6	-2.3	1.2
ζmodel - ζwssg	-1.5	4.0	-24.3	38.9

### Best fitted quasigeoid - gravimetric quasigeoid fitted to GPS/levelling

The fit of "best fitted" quasigeoid model to the POLREF sites [cm] (mean difference: 1.0 cm)



Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006

Riga, Latvia, 14-17 June 2006







## **Quality of quasigeoid models**



### Fit of quasigeoid models to GPS/levelling control traverse [cm]





best-fitted

integrated

Symposium of the IAG Subcommission for Europe European Reference Frame – EUREF 2006

2.0

1.8

-7.4

-4.7

-2.7

-0.7

Riga, Latvia, 14-17 June 2006



0.004"

-0.004"

2.0

5.4







 All available data has been gathered, extensively qualitatively and quantitatively analysed, verified, and unified

- The data has been archived and appropriate databases were developed
- Precise terrain corrections were calculated for all gravity data
- Control GPS/levelling traverse established is a powerful tool for quality control of precise quasigeoid models in Poland
- Quality of heights of the POLREF sites is not sufficient for quality control of precise quasigeoid models in Poland











• New as well as and were deve	astro-geodetic geoid model gravimetric quasigeoid models best fitted quasigeoid model integrated quasigeoid model based on gravity, GPS/levelling and topographic data
• Accuracy	of the developed quasigeoid models has been evaluated
	astro-geodetic 21 cm
	gravimetric 2.2 cm
	best-fitted 2.0 cm
	integrated 1.8 cm
<ul> <li>Develope gained reprint of the precise of the precise</li></ul>	d methods and computing strategies as well as experience flect high potentiality for further research on developing uasigeoid models in Poland



