

Assessment of standard positioning using individual GNSS

In preparation of EUREF contribution to ICG

Jan Douša, Pavel Václavovic

(jan.dousa@pecny.cz)

Geodetic Observatory Pecný, RIGTC, Czech Republic

EUREF TWG

Vilnius, 3.6. 2014

Available software & routine monitoring

Software: **G-Nut/Anubis V1.2** – developed at GOP/RIGTC recently

G-Nut/Anubis V1.1 – current last released in April 29, 2014 (+fix)

- *Quantitative check (all GNSSs)*
- *Qualitative check (partial support for GNSSs)*
- *Meta data check (in future)*
- *Positioning (all GNSSs) → **V1.1:** GPS+GLO, **V1.2:** GPS+GLO+GAL+BDS*

Multi-GNSS monitoring (GPS+GLO+GAL+BDS+SBS+QZS):

- IGSv3 monitoring:

<http://www.pecny.cz/Joomla25/index.php/gnss/data-center/igs-mgex>

- EURv3 monitoring:

<http://www.pecny.cz/Joomla25/index.php/gnss/data-center/euref-rnx3>

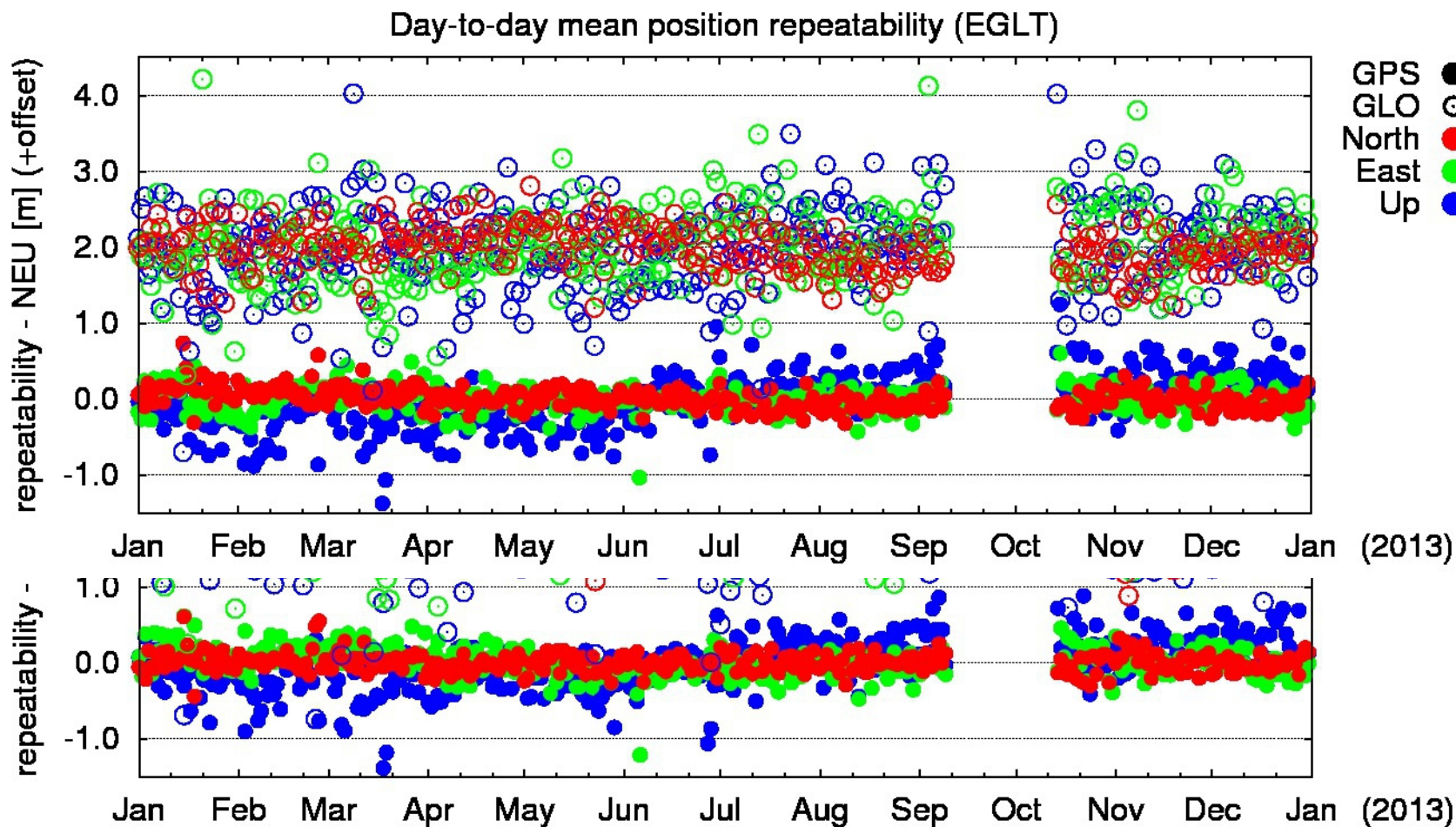
Standard monitoring (GPS+GLO):

- EUREF historical archive : (still temporary)

http://www.pecny.cz/WWW_IMG/MULTI-GNSS/EUREF/index.php

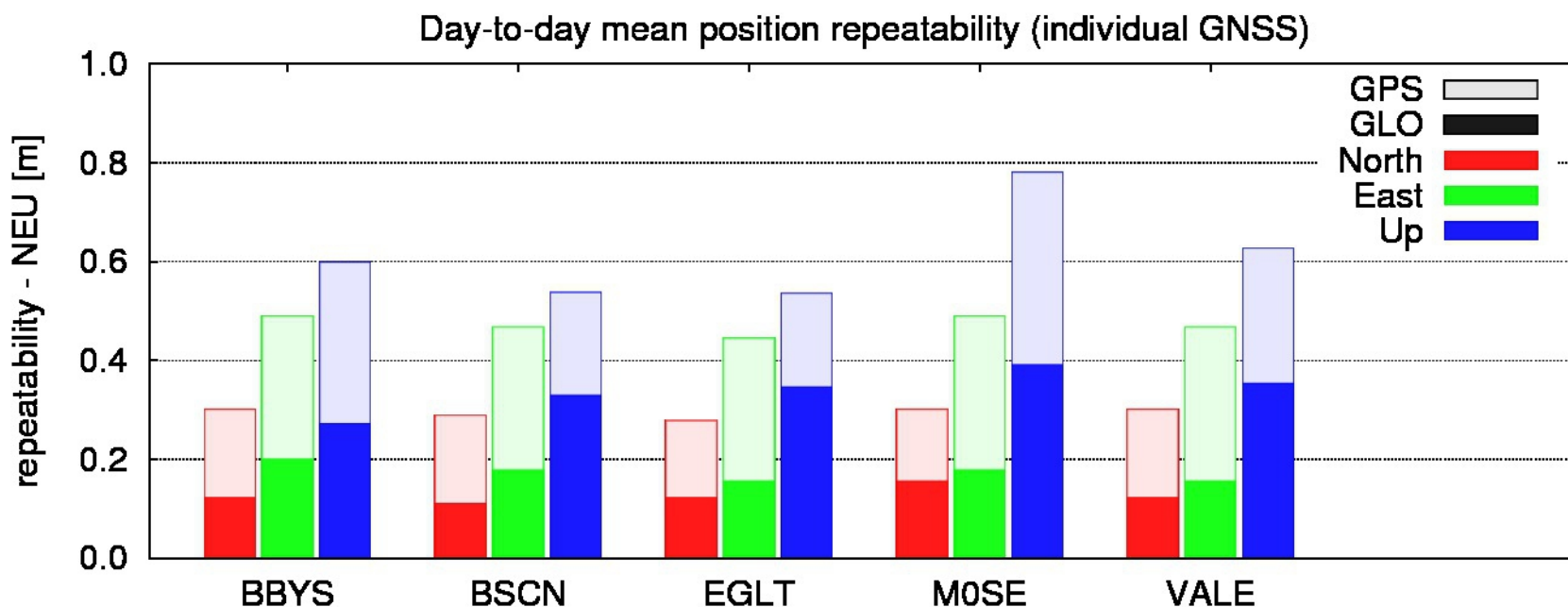
Day-to-day average single GNSS positions

Individual positioning depends on various aspects: quality of navigation messages and observations, processing models, adjusting, averaging, ...



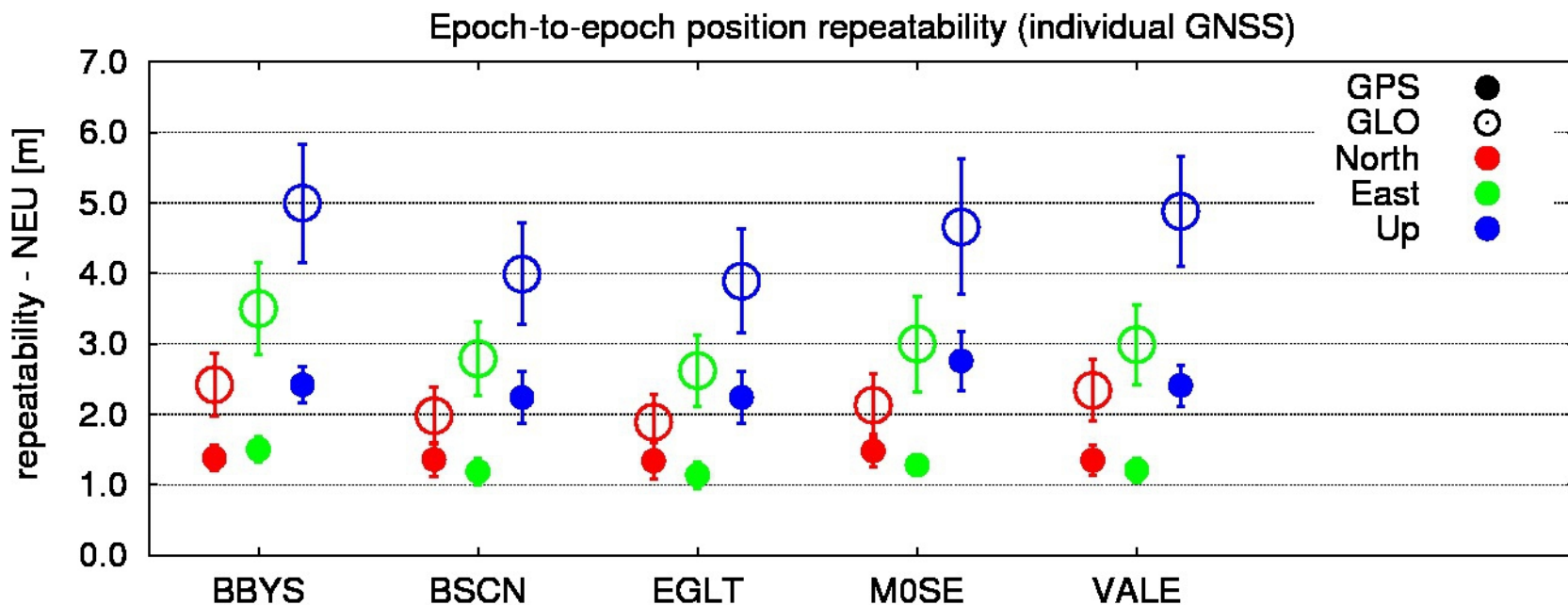
Day-to-day position repeatability

- Source: daily averages of individual GNSS solutions: **GPS, GLONASS**
- Repeatability of daily position averages during Jan-Dec 2013



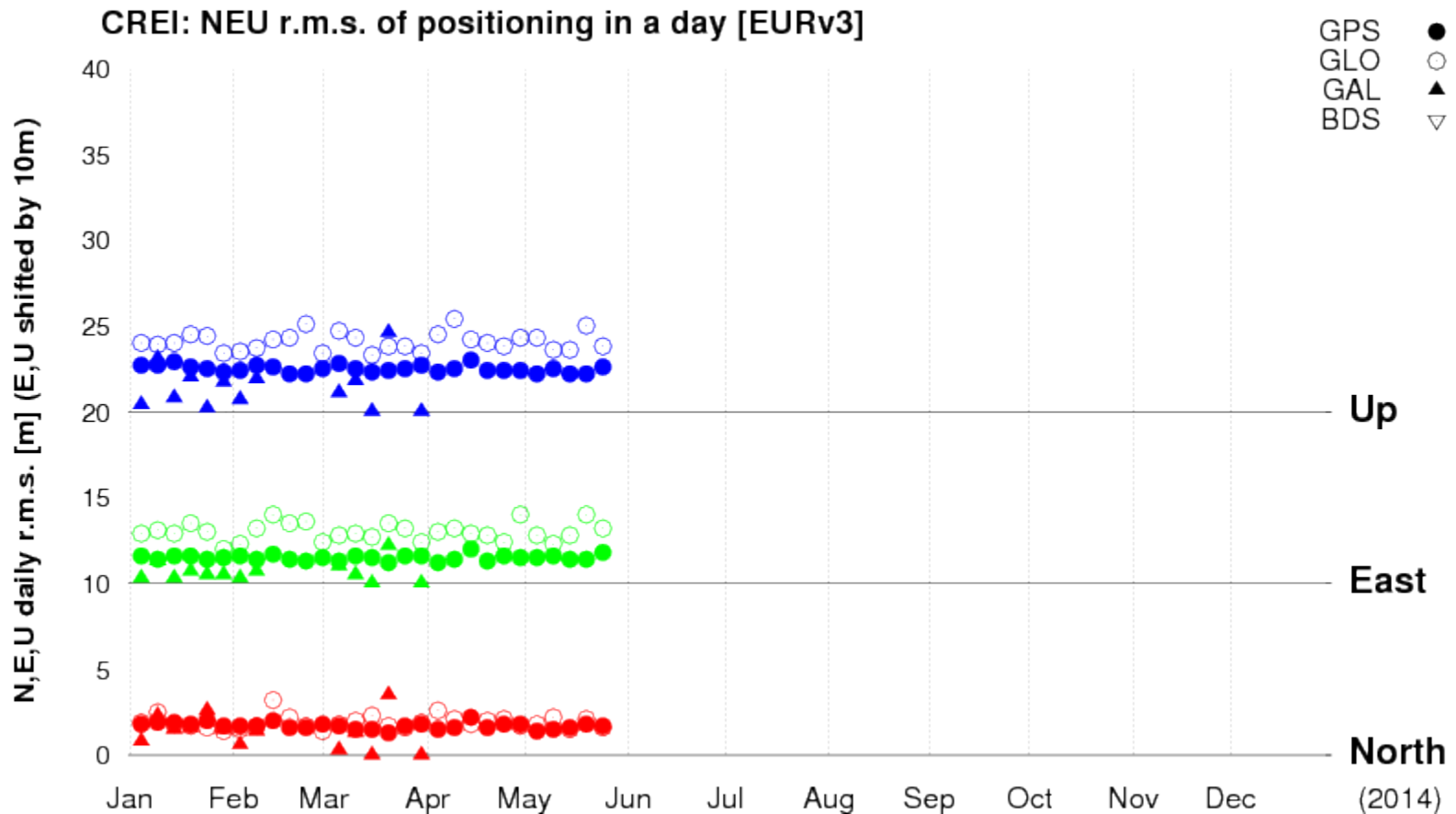
Epoch-to-epoch repeatability (NEU)

- Source: epoch-wise (15min) individual GNSS solutions: **GPS, GLONASS**
- Mean epoch-to-epoch position repeatability for each day of Jan-Dec, 2013
- RMS of mean epoch-to-epoch position repeatability (Jan-Dec, 2013)



Preliminary Galileo positioning

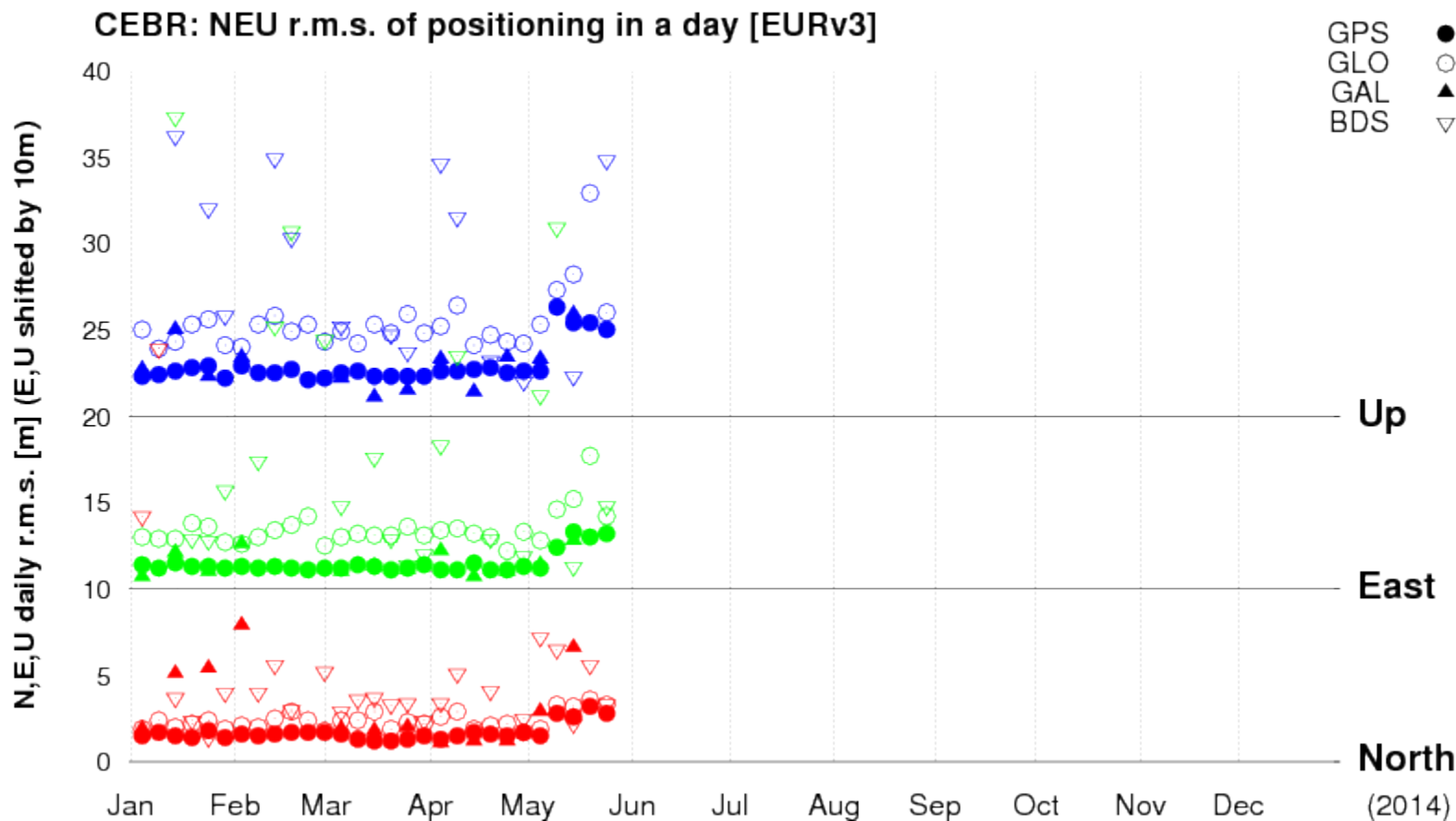
Galileo: a few satellites only --> a few epochs in a day
... starting from 2014



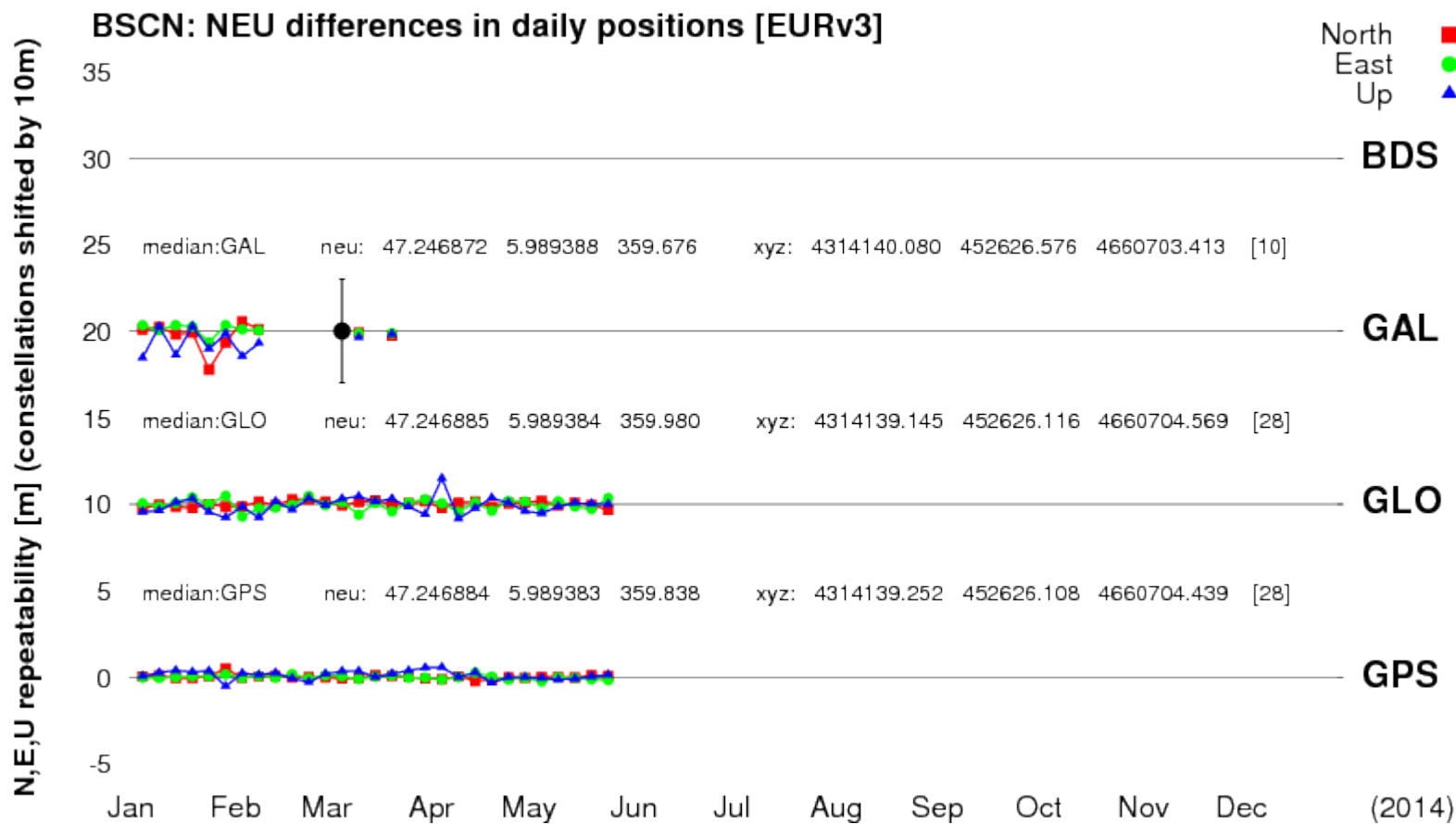
Preliminary Galileo & BeiDou positioning

BeiDou: a few satellites --> two stations in Europe only

.. starting from 2014

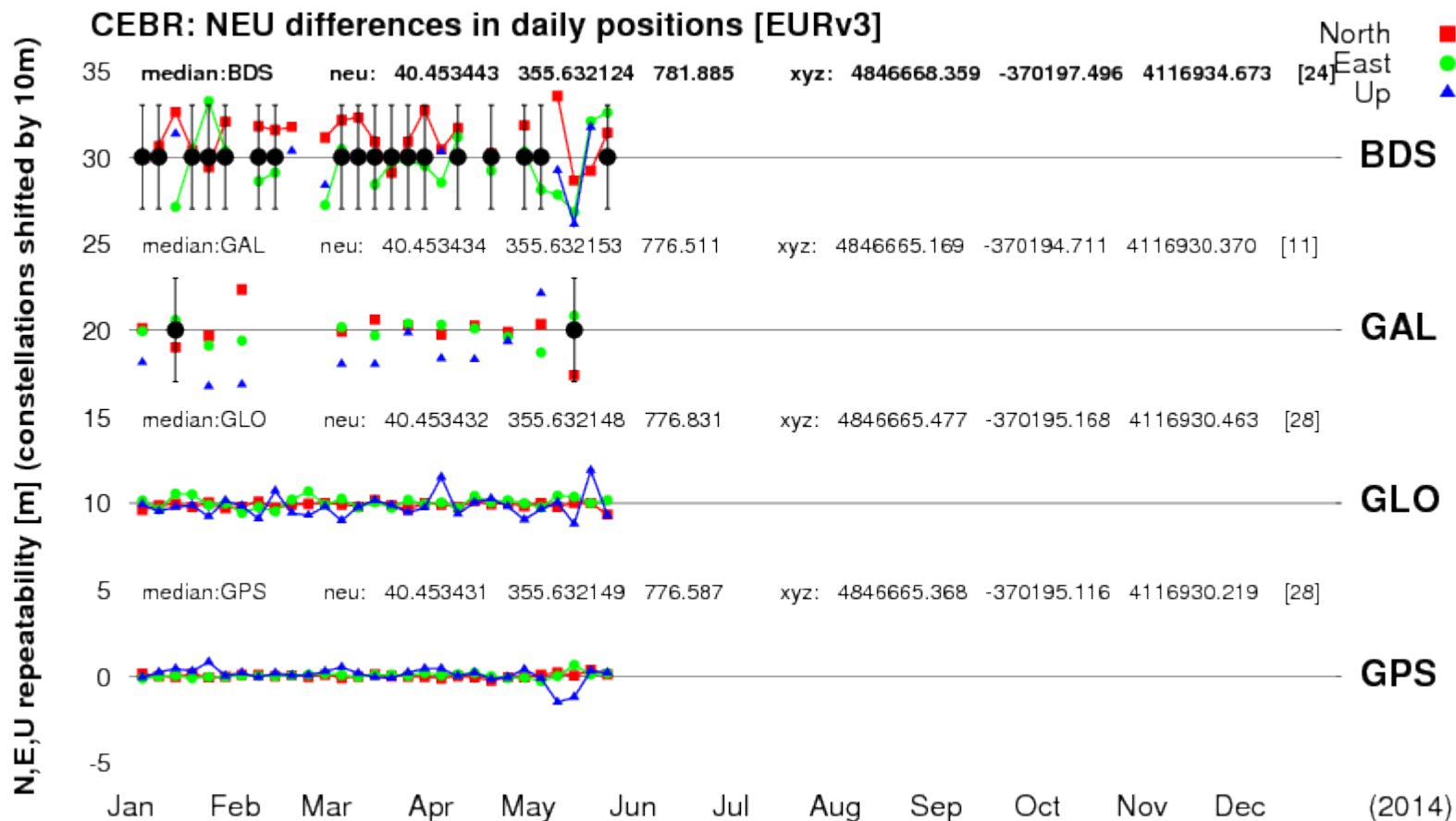


Preliminary Galileo position time-series



(c) GOP/RIGTC, 2014-06-03

Preliminary Galileo & BeiDou positioning



(c) GOP/RIGTC, 2014-06-03

Summary

- **G-Nut/Anubis V1.1:** only GPS+GLO with Bancroft solution
- **G-Nut/Anubis V1.2 :** all GNSS supported with SPP solution
 - V1.2 will be released in summer 2014

Source: <http://www.pecny.cz/Joomla25/index.php/gnss/sw/anubis>

Pending question: What is a 'standard' methodology for the assessment

- epoch-to-epoch solution
- day-to-day solution
- which solution (SPP), which models to use
- navigation messages – which to use, QC, ...
- how to optimally generate statistics

Output: Numerical values will be provided when the above is agreed