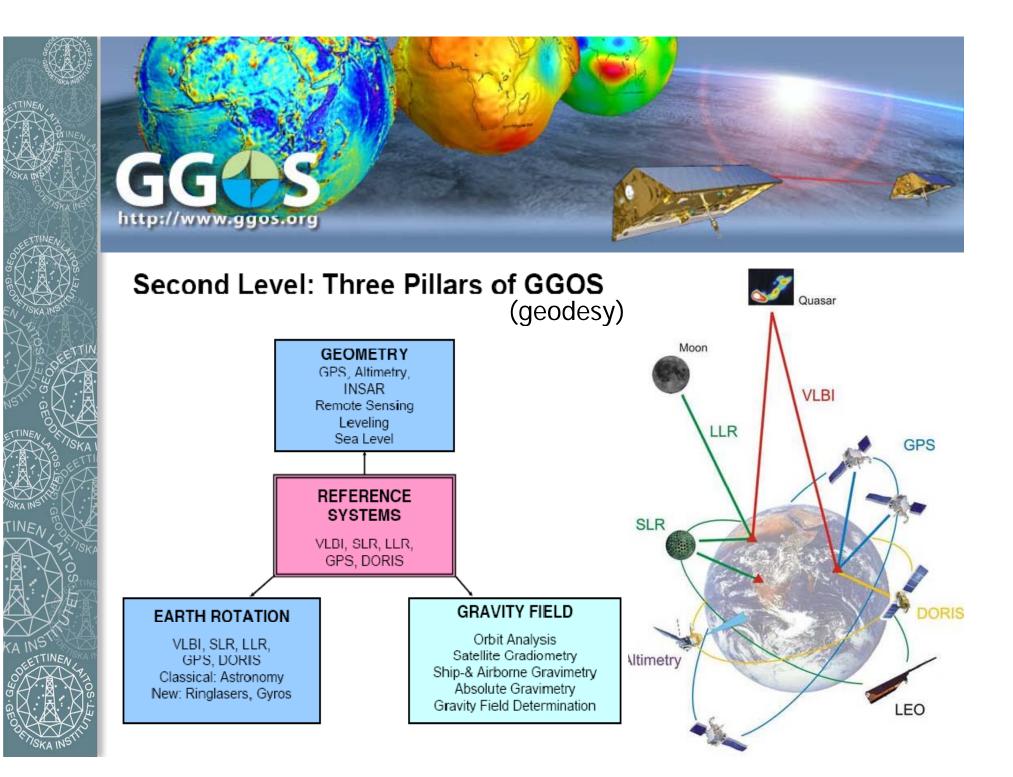
ECGN

A regional geodetic observing system?

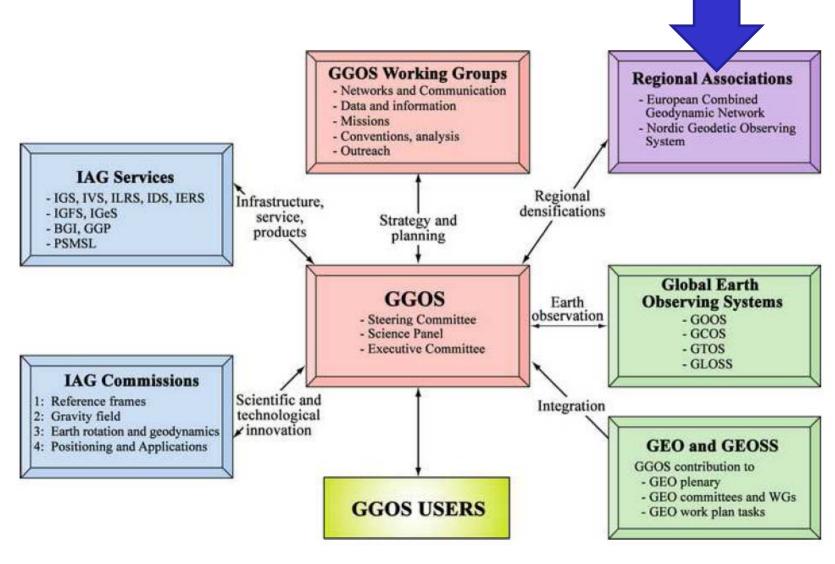
Johannes Ihde, Markku Poutanen

7.SKA





GGOS Structure

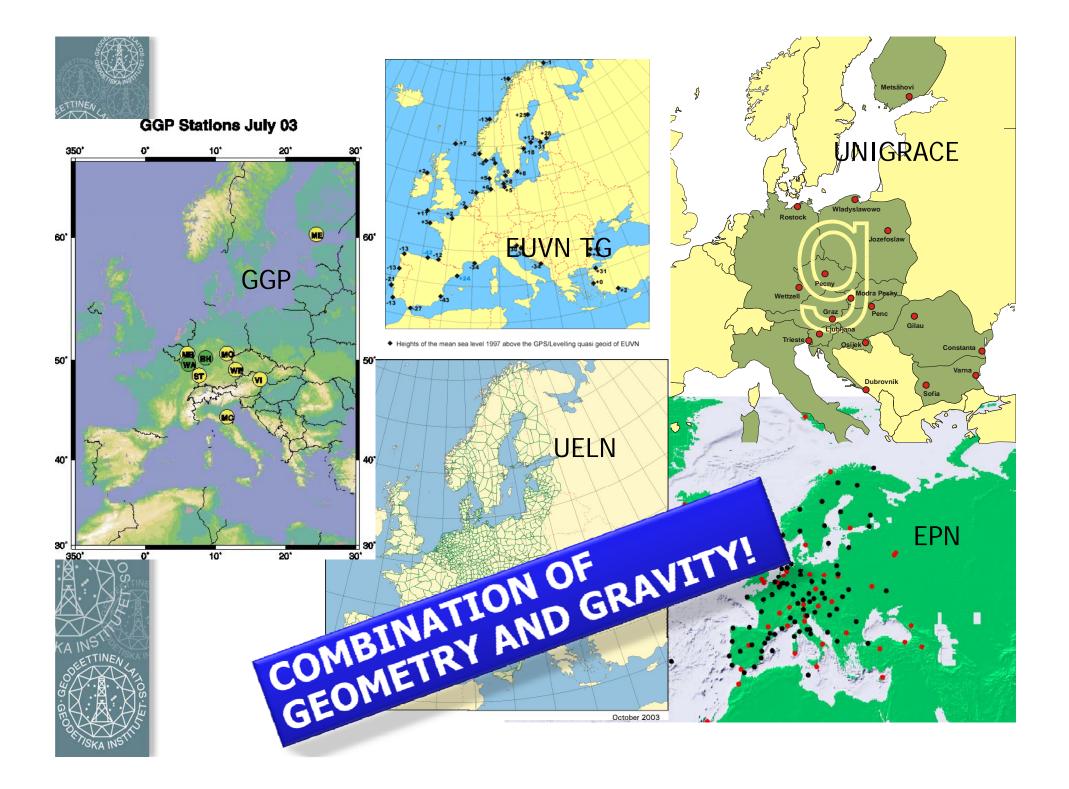


European Combined GeodeticNetworkECON

Objectives of the ECGN as an integrated European Reference System for Spatial Reference and Gravity are:

- Realization of a terrestrial reference system and maintenance of long time stability with an accuracy 10⁻⁹ for Europe especially in the <u>vertical component</u>
- In-situ <u>combination</u> of space geodesy (GPS) with Earth gravity parameters (gravity, heights)
- Modelling of influences of <u>time depended parameters</u> to TRF (of the solid Earth of the Earth gravity field, the atmosphere, the oceans, the hydrosphere)
- Modelling of terrestrial gravity field components to validate <u>satellite gravity missions</u>
- Geodetic platform in Europe for <u>geo-initiatives</u> (GMES, INSPIRE, GEOSS, GGOS)

The ECGN is considered as a European contribution to the IAG's Global Geodetic Observation System (GGOS). At the business meeting of the IGGC at the Gravity and Geoid 2002 Symposium in Thessaloniki the ECGN project as a cross-commission project was approved. The primary concern of the project consists in connecting the height component with the gravity determination while allowing for measuring data that are acquired in the European coastal regions and above adjacent seas.





Techniques

Technique	Objective	Accuracy	Component(s)
VLBI	Point positioning relative	0.001 ppb	Surface displacement; Earth rotation;
	to space	0.1 mas	Reference frame
SLR	Point positioning relative	< 1 cm (range)	Surface displacement; Earth rotation;
	to many satellites	1-2 cm	Reference frame
GNSS	Point positioning relative	E: $1-2 \text{ cm}^{*}$	Surface displacement;
	to a satellite system	C: 1-2 mm	Reference frame
DORIS	Point positioning relative	1-5 cm	Surface displacement;
	to satellites		Reference frame
Levelling	Height differences of	$< 1 \text{ mm/km}^{\frac{1}{2}}$	Surface displacement;
	points relative to the geoid		Reference frame
Tide gauges	Height of points relative to	E: 10 cm	Surface displacement;
	sea level	C: 1 cm	Reference frame
Absolute	Absolute gravimetric	2-3 µGal	Surface displacement; Earth rotation;
gravimeters	accelerations		Gravity; Reference frame
Superconducting	Relative gravimetric	0.1 µGal	Surface displacement; Earth rotation;
gravimeters	accelerations	(< 1 nGal periods)	Gravity; Reference frame
Spring	Relative gravimetric	2-3 µGal	Gravity;
gravimeters	accelerations		Reference frame

*) E means episodical and C continuous measurements



ECGN - Stations



Status and Techniques (Standard: GPS, absolute gravity, levelling)





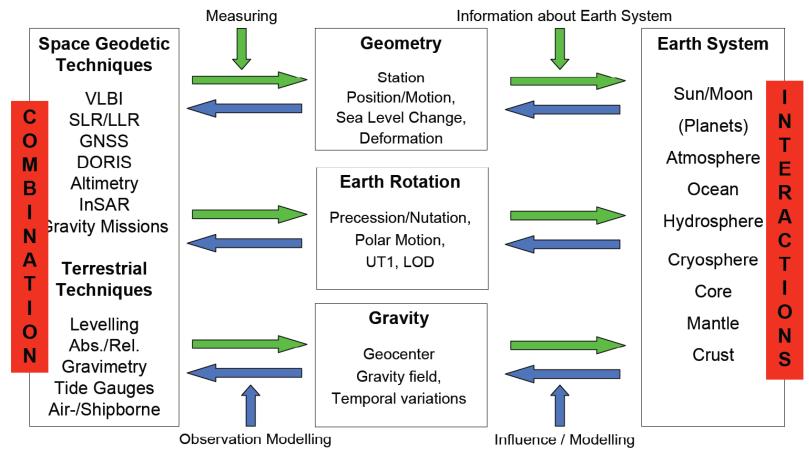
Why ECGN?

- Geodetic networks of different techniques separated (reference frames, levelling, gravity)
- Connection of observations of different techniques
- Availability of data, access of data
- Quality control of data
- Continuation and stability of the infrastructure
- Response to political and societal needs
- Delivery or products to the end users
- Unawareness of geodetic methods

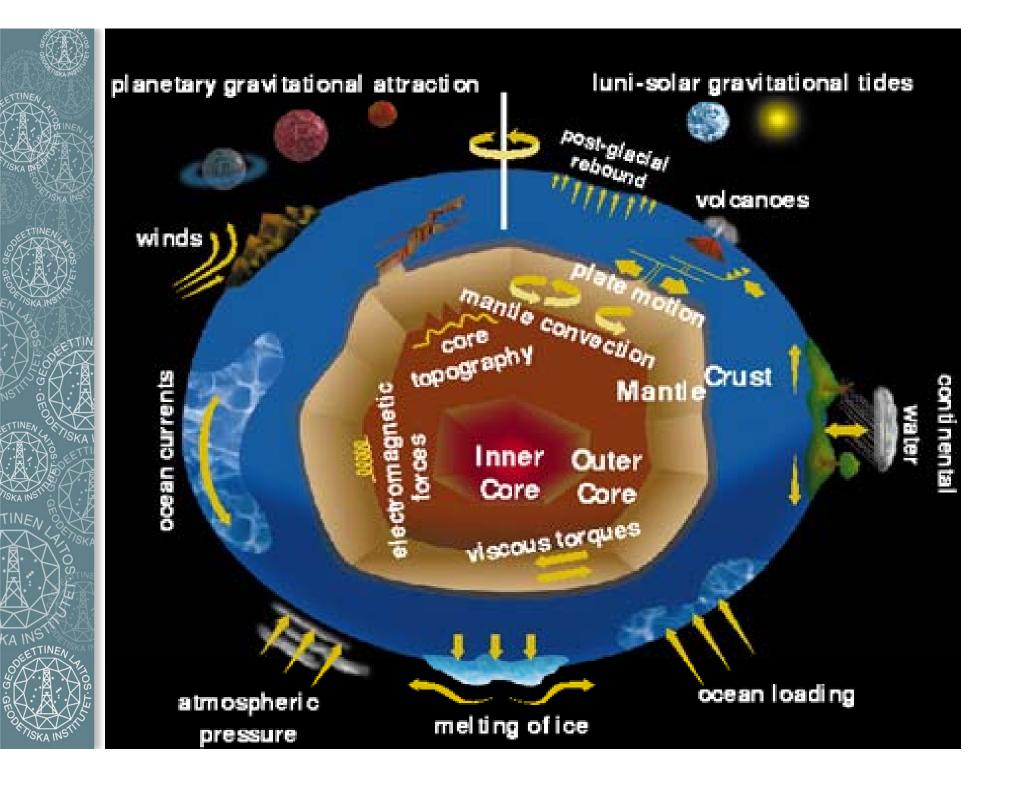


How?

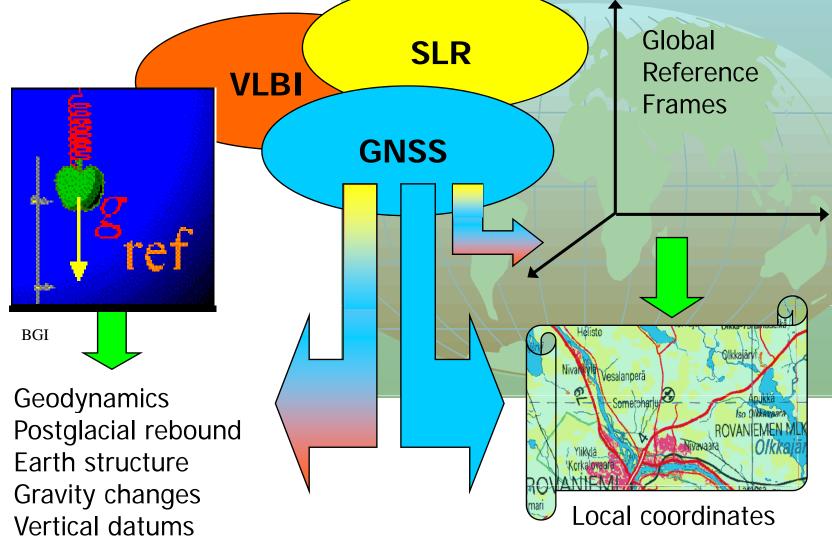
Measuring and Modeling the Earth's System



M. Rothacher



Motivation for multitechnique sites





Future?

Challenge for geodesy

- Ignorance and unawareness of geodetic networks and importance of stable and well defined reference frames is common. Every civilized country needs up-to-date, easily accessible reference frames for its societal tasks, and such frames do not exist without continuous maintenance.
 - Research of global change is an example of the need of geodesy: stable reference frames and precise geodetic observations



To do...

- Convince dear colleagues about the need of geodetic observing system(s)
- "Re-establishment" of the ECGN WG
- Create connections to other groups, organizations (GGOS, ...)
- 2-way benefit of GGOS: use GGOS results locally and contribute to GGOS
- Geodesy, geophysics, ... (multi-disciplinary project)

...but we're not going to re-invent a wheel

