

ETRS89 Realizations

- What is the problem ?
- Proposal for Remedy
- Procedures
- Recommendations

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Problem

Coordinates jumps between successive ETRS89 realizations at epochs posterior to 1989.0, due to transformation parameter rates between successive ITRS realizations.

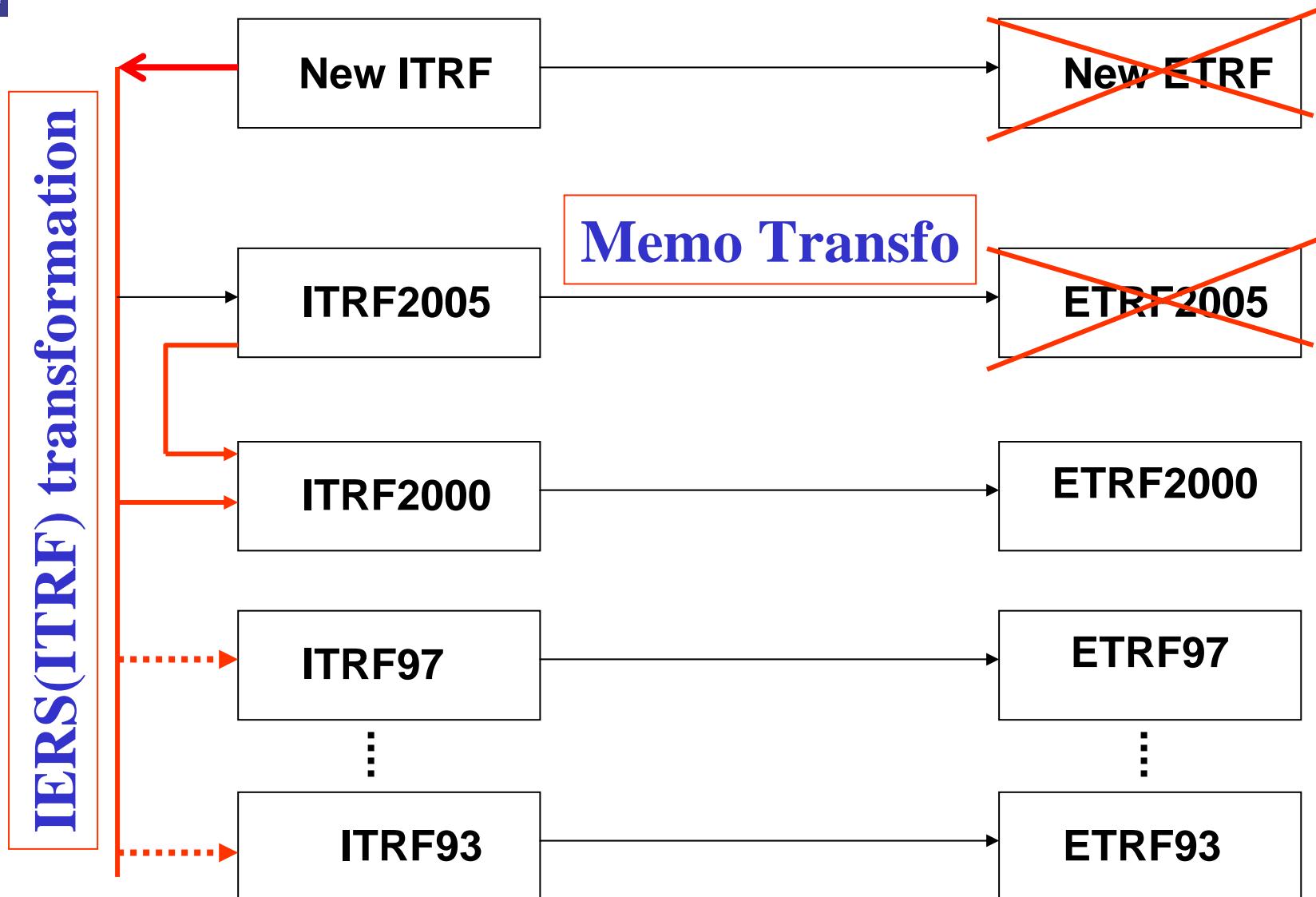
Proposal

- **Minimize the transformation between ETRF2000 and future ETRFyy solutions, starting with the ETRF2005.**
- **This means adopting ETRF2000 as a conventional frame of the ETRS89 system.**

Procedures

- There are two proposed procedures
- Approach A:
 - Transform from ITRF2005(8, 10) to ITRF2000 (97, ...,93)
 - Use the ITRS-to-ETRS89 Transformation Formulae
- Approach B: Use 14 Transformation Parameters between ITRF2005(8, 10,..) and ETRF2000 :
 - B-1 Computed Parameters
 - or
 - B-2 Estimated Parameters

Approach A



Approach A: Advantages

- Straightforward and clear approach
- Minimum update of the Memo
- Valid for the past and the future
- Satisfies all users
- Already used by a certain number of NMAs
- Guarantees zero jumps

B-1 Computed Parameters

Summation of the transformation

- ITRF2005-To-ITRF2000 (IERS)
and
- ITRF2000-To-ETRF2000 (EUREF Memo)

	T1 mm	T2 mm	T3 mm	D 10-9	R1 mas	R2 mas	R3 mas	Epoch y
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	54.1	50.2	-53.8	0.40	0.891	5.390	-8.712	00:001
Rates	-0.2	0.1	-1.8	0.08	0.081	0.490	-0.792	

B-2 Estimated Parameters

Using ITRF2005 & ETRF2000 published solutions: 35 stations

(1)

	T1 mm	T2 mm	T3 mm	D 10-9	R1 mas	R2 mas	R3 mas	Epoch y
<hr/>								
	49.3	54.0	-49.1	0.58	0.983	5.616	-8.838	00:001
+/-	1.9	3.0	1.6	0.23	0.089	0.065	0.063	
Rates	-1.6	3.4	-0.6	-0.14	0.161	0.553	-0.848	
+/-	1.9	3.0	1.6	0.23	0.089	0.065	0.063	

(2) Using EPN-ITRF2005 Dens-solution & ETRF2000: 48 stations

(2)

	T1 mm	T2 mm	T3 mm	D 10-9	R1 mas	R2 mas	R3 mas	Epoch y
<hr/>								
	57.1	40.3	-56.1	0.86	0.710	5.293	-8.468	00:001
+/-	1.8	3.4	1.8	0.27	0.100	0.062	0.077	
Rates	-0.3	0.4	-1.8	-0.09	0.064	0.491	-0.808	
+/-	1.8	3.4	1.8	0.27	0.100	0.062	0.077	

Correlation between parameters and their rates

	Tx	Ty	Tz	D	Rx	Ry	Rz
Tx						-0.88	
Ty					0.94		-0.79
Tz				-0.72		0.65	
D							
Rx							
Ry							
Rz							

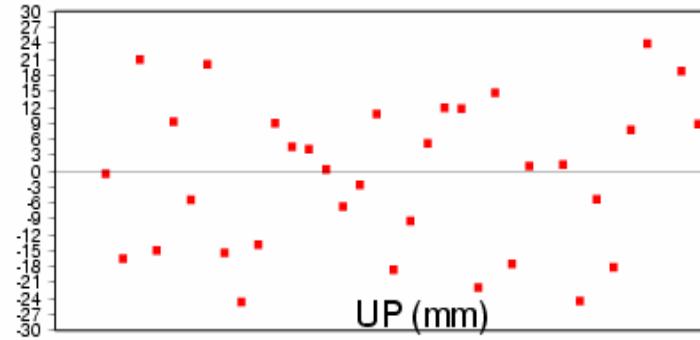
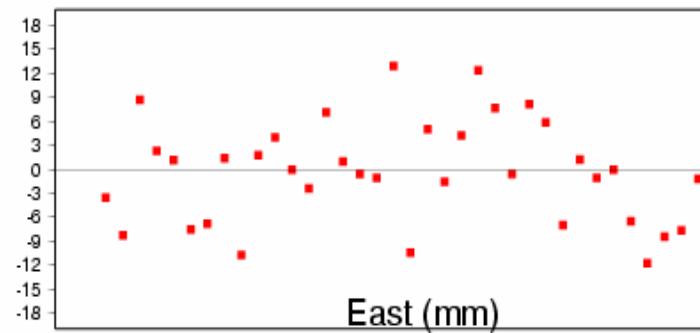
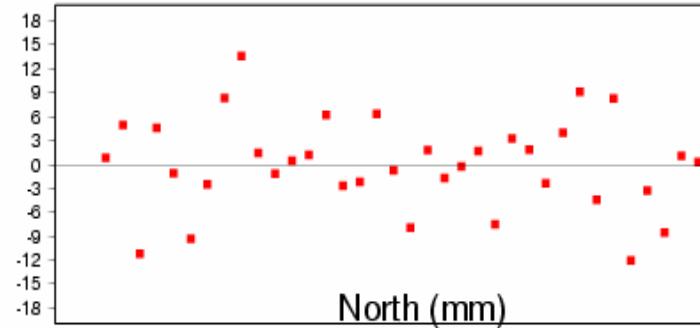
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	33.6	87.9	-55.1	-0.81	2.595	11.141	-17.314	10:001
+/-	7.1	11.2	5.9	0.86	0.338	0.247	0.239	
Rates	-1.6	3.4	-0.6	-0.14	0.161	0.553	-0.848	
+/-	1.9	3.0	1.6	0.23	0.089	0.065	0.063	

	N	WRMS-Pos.			Epoch	WRMS-Vel.			
		E	N	U		E	N	U	
		mm	mm	y		mm/y	mm/y	y	
<hr/>									
	35	2.1	1.8	3.1	00:	1	0.5	0.5	1.4
	35	6.2	5.6	14.5	10:	1	0.5	0.5	1.4

Residuals at 2010



Conclusions

- Approach A is the most straightforward
- A & B are equivalent only if the computed parameters are adopted
- The estimated 14 parameters are subject to imprecision and introduce more jumps at current epochs.

Recommendations

- Adopte Approach A: the simpliste for the users
- Explain all possible approaches to EUREF community: advantages and disadvantages
- Leave the freedom to users to adopt their preferred Frame and their preferred procedure, do we have any choice to influence NMAs ?
- Possibly think about modifying the ETRS89 definition



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ETRS89: Basic Principles

- **Avoid complication to the users**
- **The ETRS89 as a system should remain unchanged**
- **Keep the existing geodetic/mathematical transformation formulae between ITRS and ETRS89. An essential link between the two systems**
- **Admit/accept the existence of different realizations of both systems**
- **Keep one way to realize the ETRS89, using the pre-existing transformation formulae**
- **Different users adopted different frames (ETRFyy)**

Users of ETRS89 Realizations

- **Type_1 : all national datum users:**
 - Different ETRFyy frames were already adopted by different countries, with legal status!
- **Type_2: EPN users: weekly time solutions**
 - (1): users who wants to have access ETRS89 via the whole EPN network
 - (2): users of country-EPN stations, but need weekly solutions expressed in their national ETRFyy

Concluding Remarks

- Different users with different frames (ETRFyy)
- Impossible to eliminate now shifts between already existing and USED frames
- Shifts/changes are not limited to ETRF2000 and ETRF2005, but concern almost all ETRFyy
- Impossible to impose/recommend the usage of one frame (not a system) for the entire Europe
- We have to leave the freedom to users to select their « preferred » frame

Recommendations

- Transformation formulae should remain flexible (not to be changed)
- Recommendation: (Approach A)
 - Use the most recent ITRF (IGS) frame for GPS data reduction
 - Transform to ITRFyy corresponding to the user ETRFyy
 - Do the transformation ITRF-to-ETRF
- Advantages:
 - No extra formula is added to the « famous » memo
 - Satisfy « all » type of users