## ETRS89 in Fennoscandia - with special emphasis on Sweden

### EUREF2016 Tutorial on ETRS89, San Sebastian, Spain

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### Outline

The specific situation in Fennoscandia

Realizations of ETRS89 in Fennoscandia

Expectations from the user community

Common Nordic/Baltic efforts of models of crustal deformations

Transformation scheme from ITRFs to realization of ETRS89

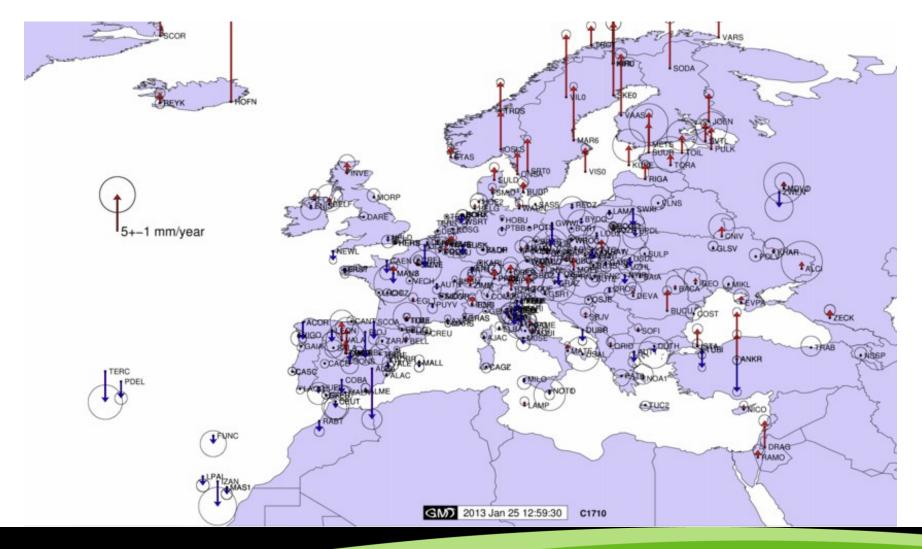
Example from Sweden:

- Implementation in post-processing service
- About the network RTK service

Discussion!

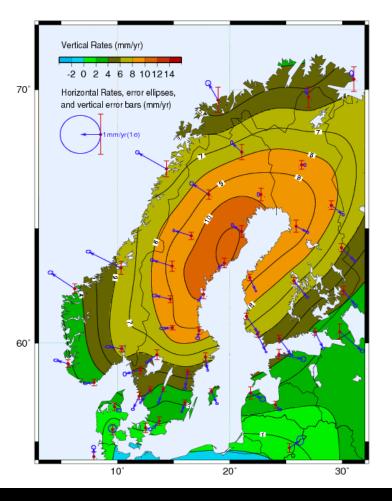


### **Vertical velocities in ETRS89**





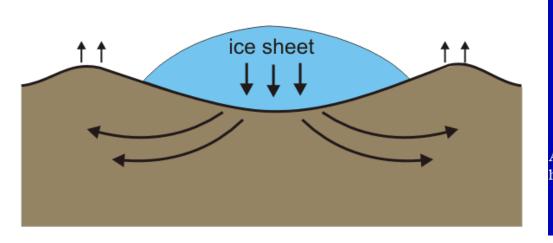
#### The Specific situation in Fennoscandia

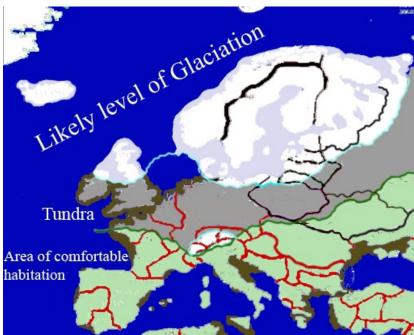






## The Glacial Isostatic Adjustment (GIA) phenomenon







#### To note:

In presence of crustal deformations, the epoch is crucial.

Therefore:

## Time tag everything!

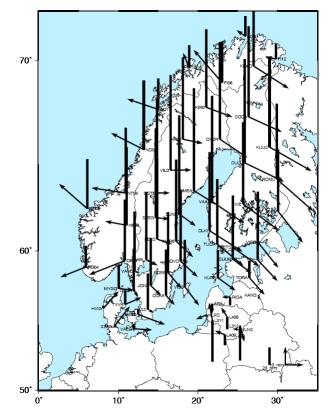


### **Realizations of ETRS89 in Fennoscandia** (the Nordic / Baltic countries)

Country	Country ID	Name of realization	Based on ITRFxx	Realization epoch
Denmark	DK	EUREF-DK94	ITRF92	1994.704
Estonia	EE	EUREF-EST97	ITRF96	1997.56
Faroe Islands	FO		ITRF2005 (ETRF2000)	2008.75
Finland	FI	EUREF-FIN	ITRF96	1997.0
Latvia	LV	LKS-92	ITRF89(?)	1992.75
Lithuania	LT	EUREF-NKG- 2003	ITRF2000	2003.75
Norway	NO	EUREF89	ITRF93	1995.0
Sweden	SE	SWEREF 99	ITRF97	1999.5



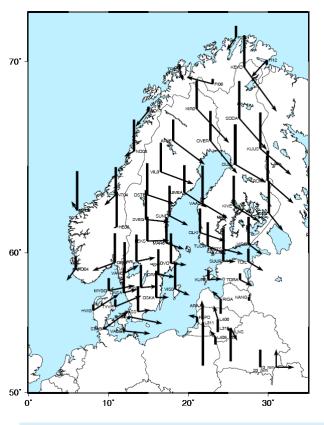
### **Comparing the national realizations of ETRS89 in Fennoscandia**



The NKG2008 campaign in ETRS2000 compared to national realizations.

Left, @ epoch 2008.75.

**Right**, @ epoch 2000.0, using a model for intraplate velocities (NKG\_RF03vel)



Statisti	cs:(n,	e,u) i	n mm
RMS	8	11	28
Mean	-3	7	19

Statistics:(n,e,u) in mm RMS 9 12 69 Mean -4 5 53

# Comparing the NKG2008, and the NKG2003 common campaigns. (in ETRF2000)

70' 60' 50 10 20. 30. Statistics:(n,e,u) in mm RMS 24 5 16 Mean -5 -4

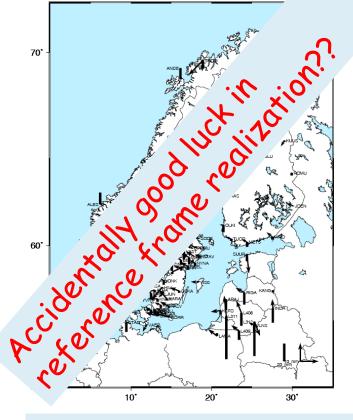
NKG2003 based on ITRF2000,

NKG2008 based on ITRF2005.

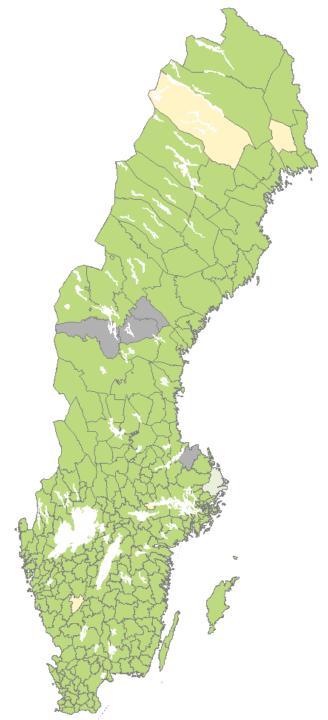
Left, NKG2008 @2008.75; NKG2003 @ 2003.75

**Right**, booth @ epoch 2003.75, using the model NKG\_RF03vel

(No fit – just coordinate



Statistics:(n,e,u) in mmRMS44Mean0-3-3



### Adoption of ETRS89 (SWEREF 99) in Sweden at the local authority level (2016-04-22)

In total 290 local authorities

Adopted (281)

Relation delivered (1)

Work in progress (4)

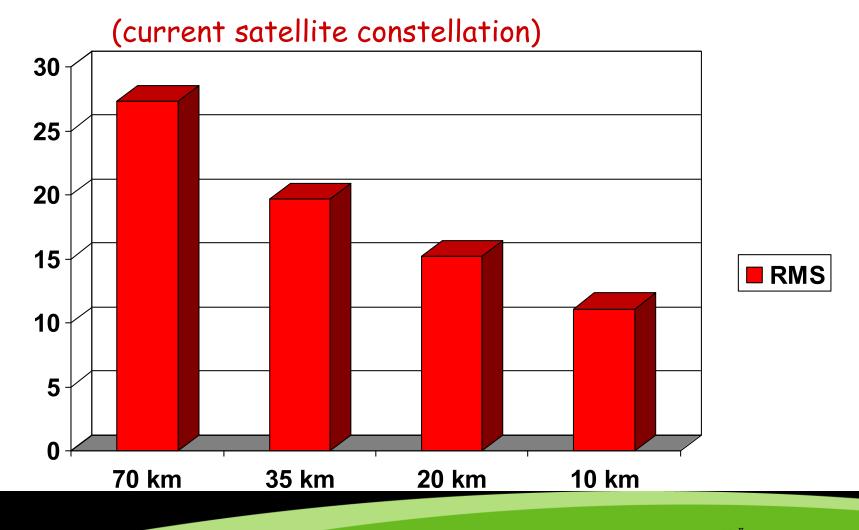
Progress unclear (4)

## Expectations from users – users asking for improved performance, and "stable" coordinates in time.



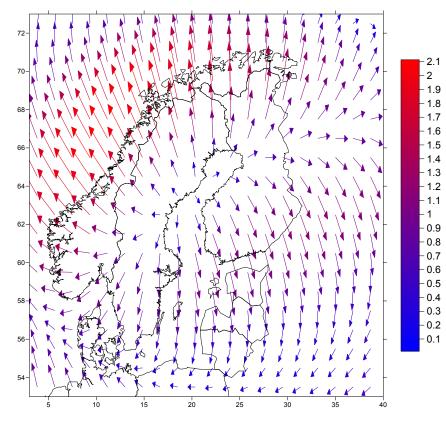


#### **Realistic expectations? Vertical performance from Network-RTK.** (The CLOSE-RTK study. The EUREF meeting in Florence)



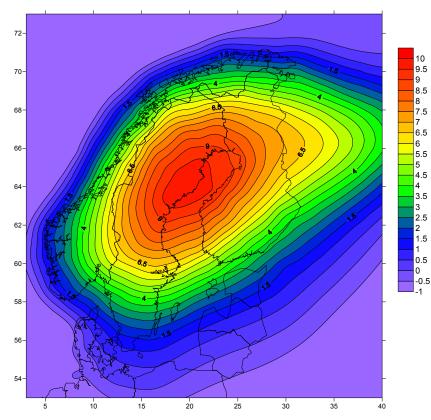
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## The NKG\_RF2003\_vel velocity model



Horizontal (0 to 2 mm/yr): The GIA model in Milne 2001 transformed to the GPSvelocities (in Lidberg 2007). Vertical (-1 to 10 mm/yr): The NKG2005LU(ABS) model Based on: TG, repeated levelling, and GPS. (Ågren & Svensson 2006)

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## Some formulas for the use of the model of crustal (intraplate) deformation

From velocities to coordinate differences

$$\begin{pmatrix} dX \\ dY \\ dZ \end{pmatrix} = \left( t_{t \operatorname{arg}et\_epoch} - t_{observation\_epoch} \right) \begin{pmatrix} V_{X_{\operatorname{int}ra}} \\ V_{Y_{\operatorname{int}ra}} \\ V_{Z_{\operatorname{int}ra}} \end{pmatrix}_{NKG\_RF03vel}$$

From velocities in (n,e,u) to (X,Y,Z) frame

$$\begin{cases} \dot{X} = \frac{-Z}{R} \frac{X}{P} \dot{n} + \frac{-Y}{P} \dot{e} + \frac{X}{R} \dot{u} \\ \dot{Y} = \frac{-Z}{R} \frac{Y}{P} \dot{n} + \frac{X}{P} \dot{e} + \frac{Y}{R} \dot{u} \\ \dot{Z} = \frac{P}{P} \dot{n} + \frac{Z}{P} \dot{u} \end{cases}$$

Where:  $R = \sqrt{X^2 + Y^2 + Z^2}$ And:  $P = \sqrt{X^2 + Y^2}$ (assuming a spherical earth)



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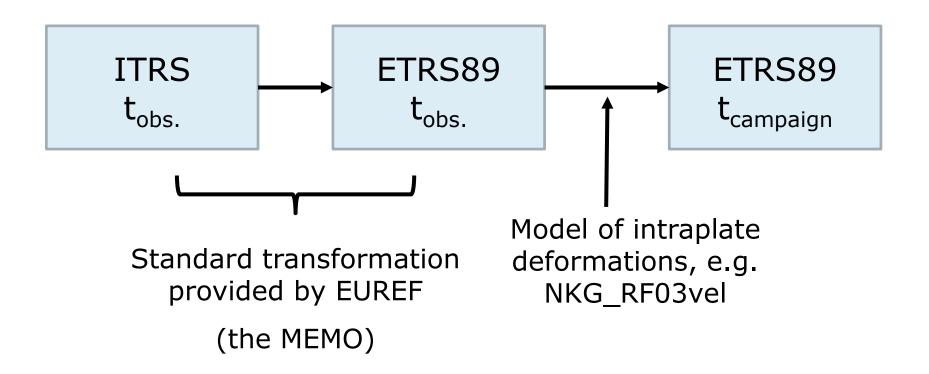
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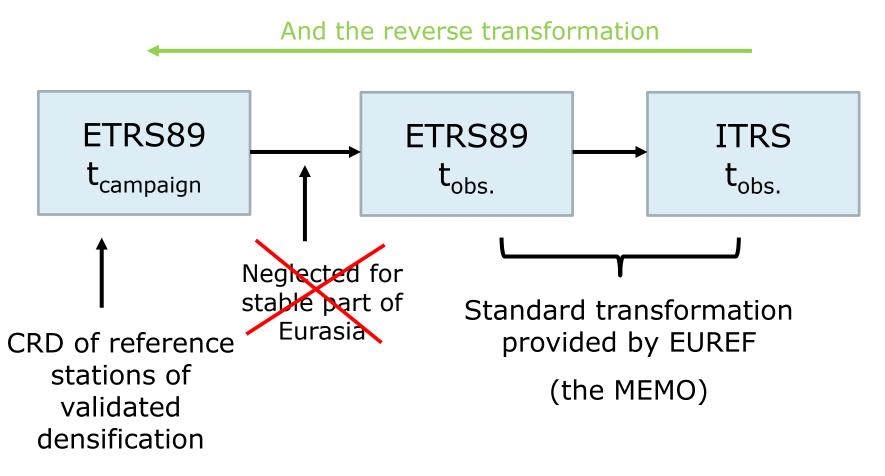


# Principle transformation scheme from ITRFs to national realization of ETRS89

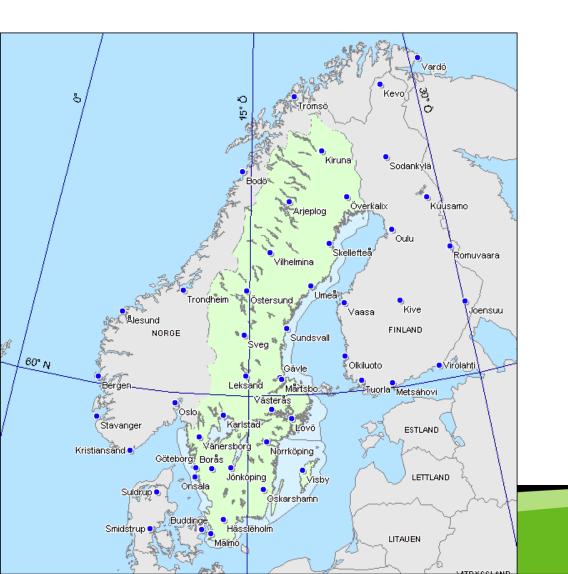




# Example of a Network-RTK service (VRS software)



### **Example from Sweden**

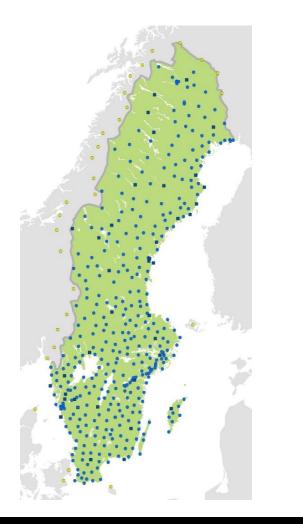


SWEREF 99 Epoch 1999.5 Class B densification of ETRS89 validated by EUREF TWG

Used as the national geodetic reference frame in Sweden.

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#### SWEPOS Network-RTK SWEPOS Post Processing Service



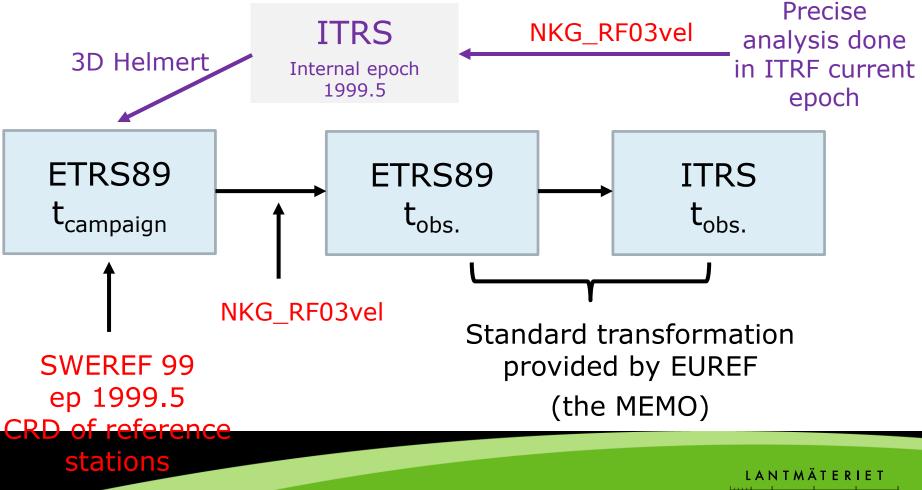


Also used for management of the geodetic infrastructure and the geodetic reference frame

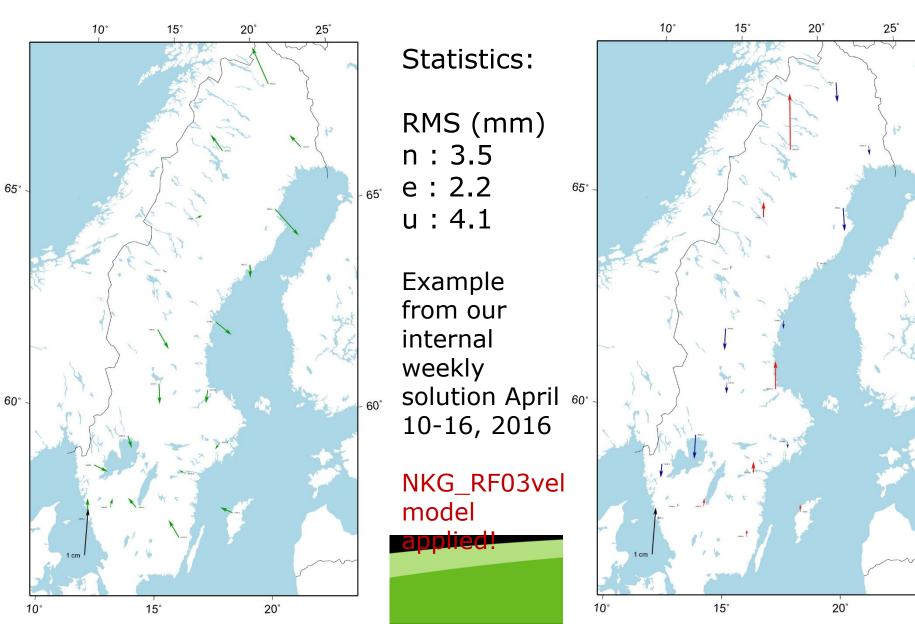
Most (all?) precise applications in SWEREF 99 is done relative to the permanent GNSS stations!



### Practical transformation scheme while connecting to known permanent GNSS stations – example SWEPOS



## Agreement between a modern analysis using data from 2016, and SWEREF 99



65°

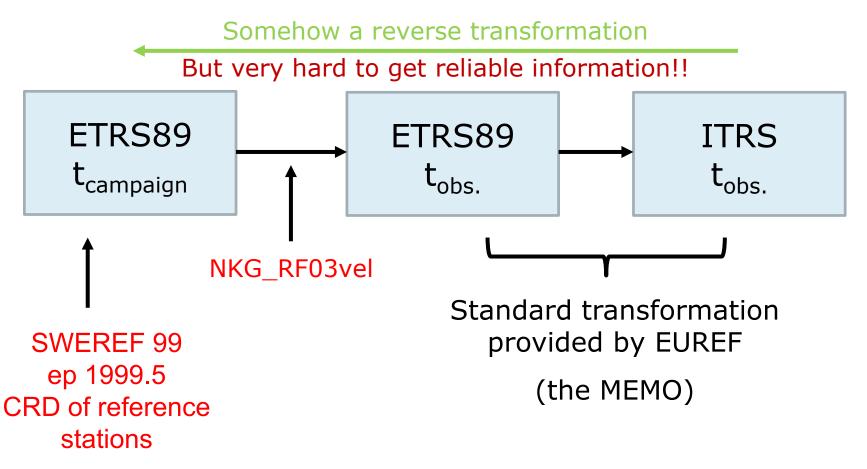
60°

### The SWEPOS RTK service: - Setup in TPP (Trimble Pivot Platform)

- Position References				
Reference frame		ETRS89		
Default tectonic plate		Eurasia		
Reference time [System startup]		Year [01.01.yy 00:00:00]		
Agency Observer	Trimble Navigation Limited  Station Information		ited	
	Station ID Station name Station code		381	
			0ABI	
			0ABI	
	Last modif	ication time [GPS Time]	2014-03-04 19:48:39	
	□ Position   Tectonic plate   X   Y			
			Eurasia	
			2233558.0134	
			761080.1007	
	Z		5906185.7509	
	Velocity × [m/year]		0.000580	
	Velocity Y	/ [m/year]	-0.000590	
	Velocity Z [m/year]		0.005600	
	Reference	e time	1999-07-01 00:00	



# Example of a Network-RTK service (VRS software)





## **Thanks for your attention!**

## **Discussions?**

Presentation by Pasi Häkli tomorrow Wednesday at 11:45

